

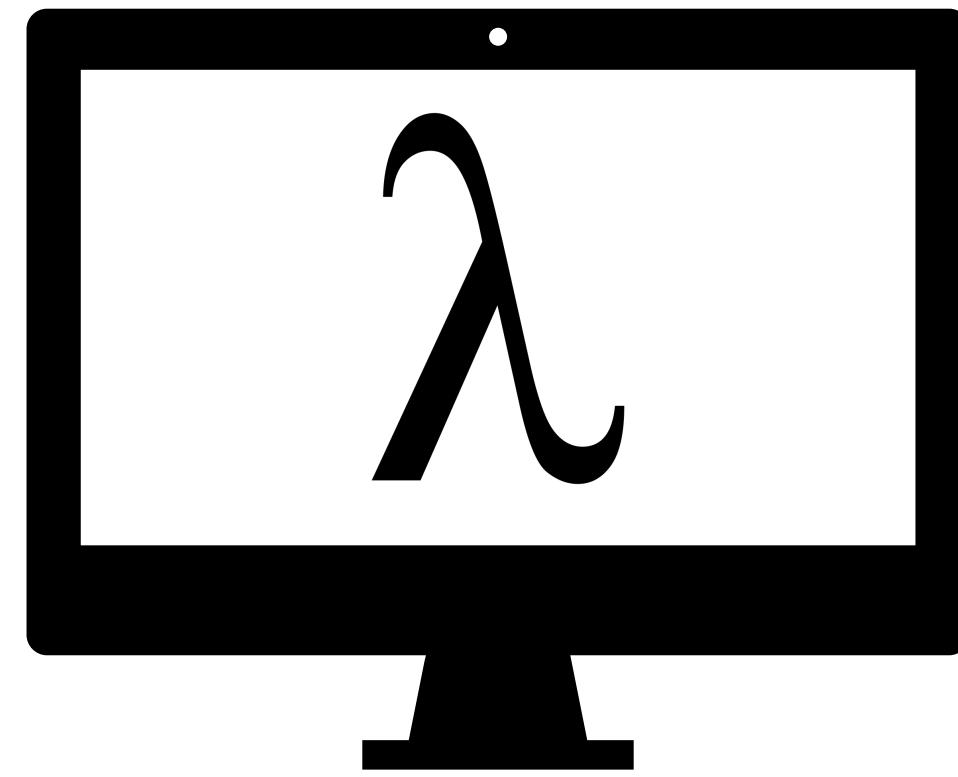
프로그래밍 언어와 기계 학습의 만남

허기홍

전산학부 / 프로그래밍 시스템 연구실

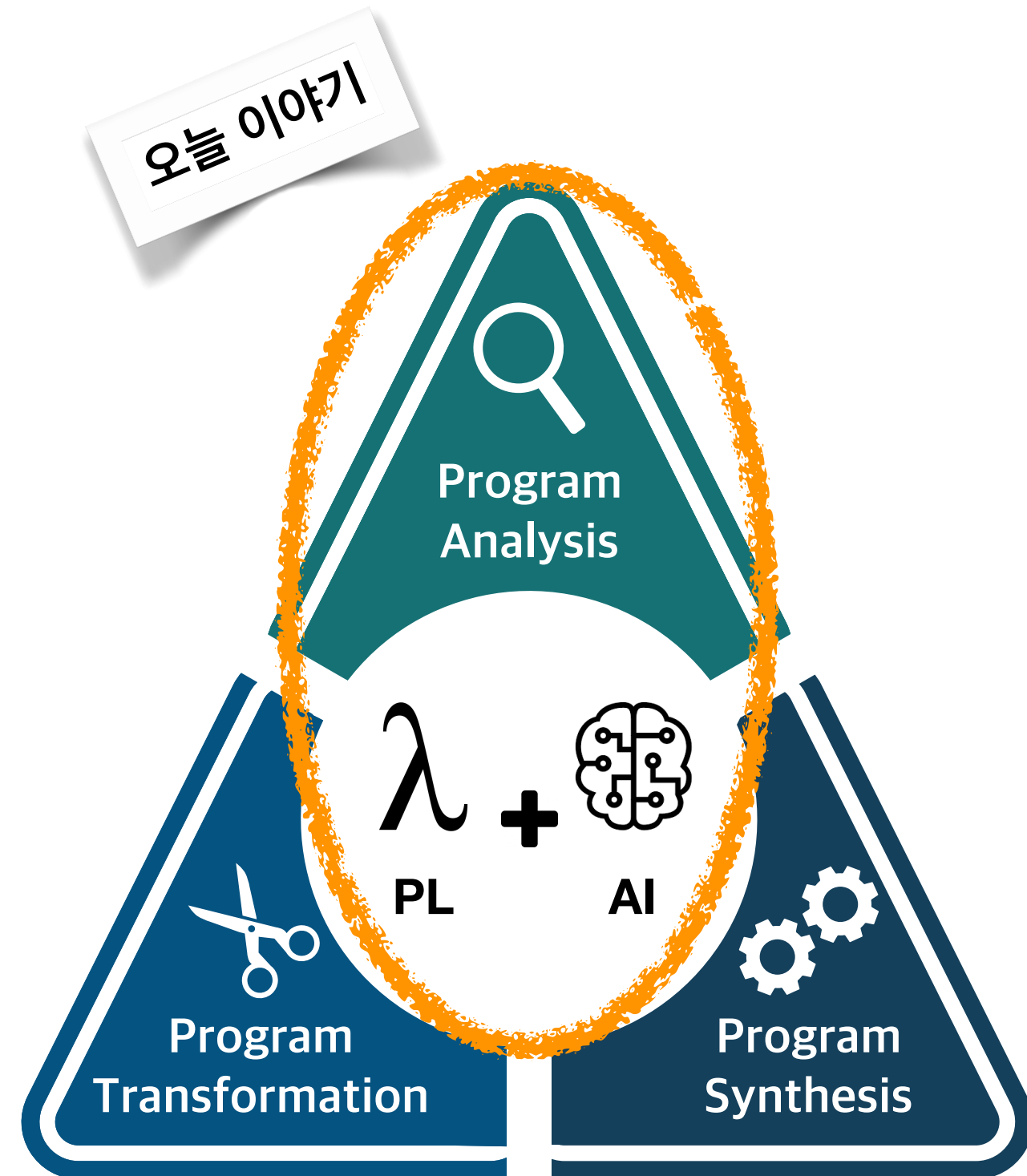
제 2회 KAIST PL 워크샵




목표

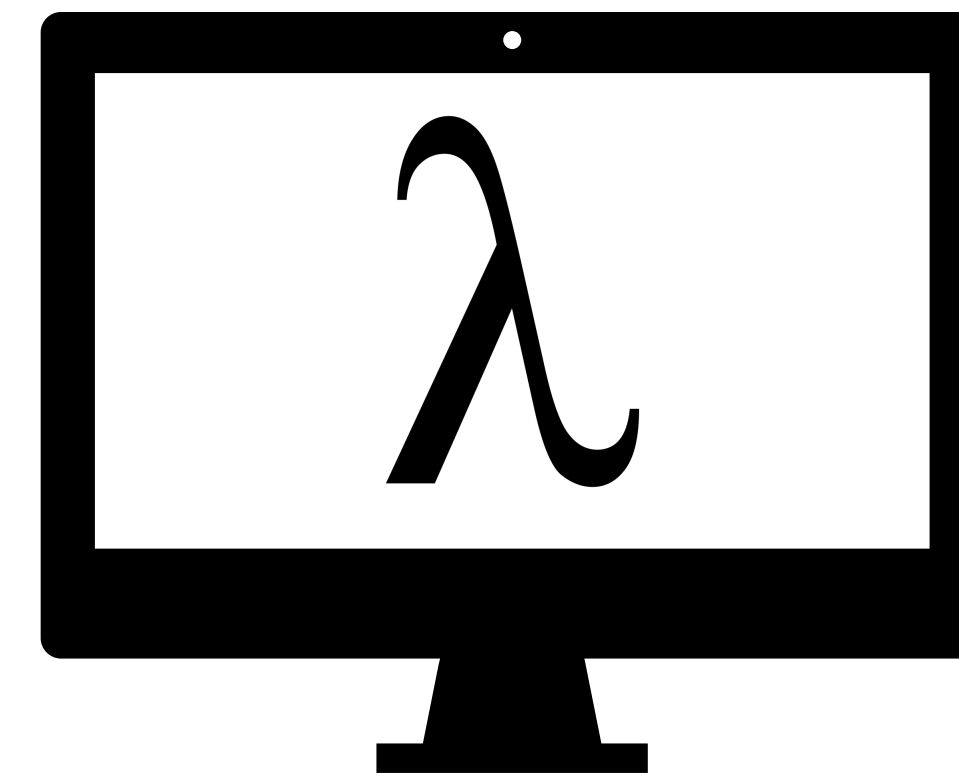


**Next-generation
Programming Systems**

목표

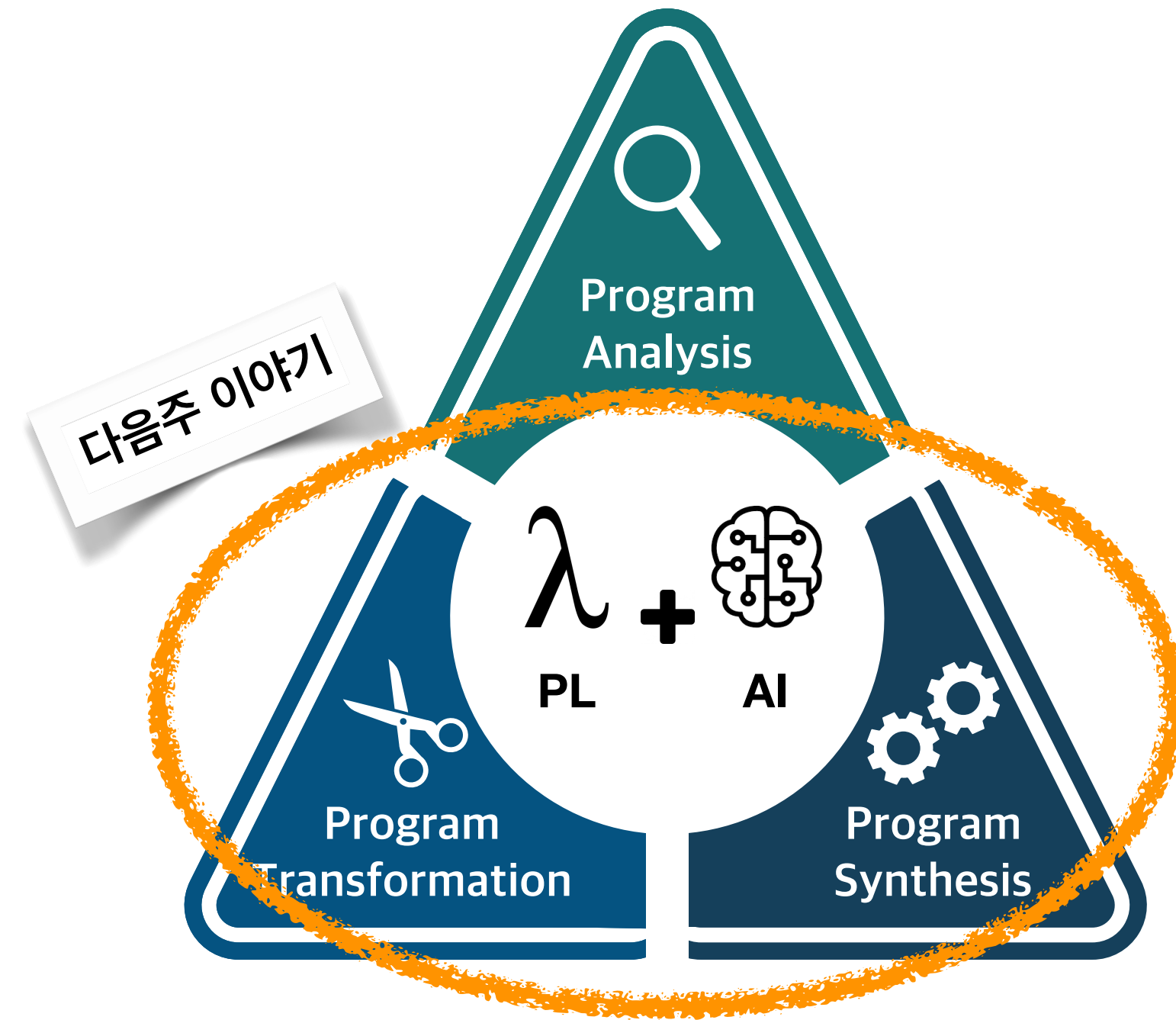





- {
-  Safe
 -  Simple
 -  Smart

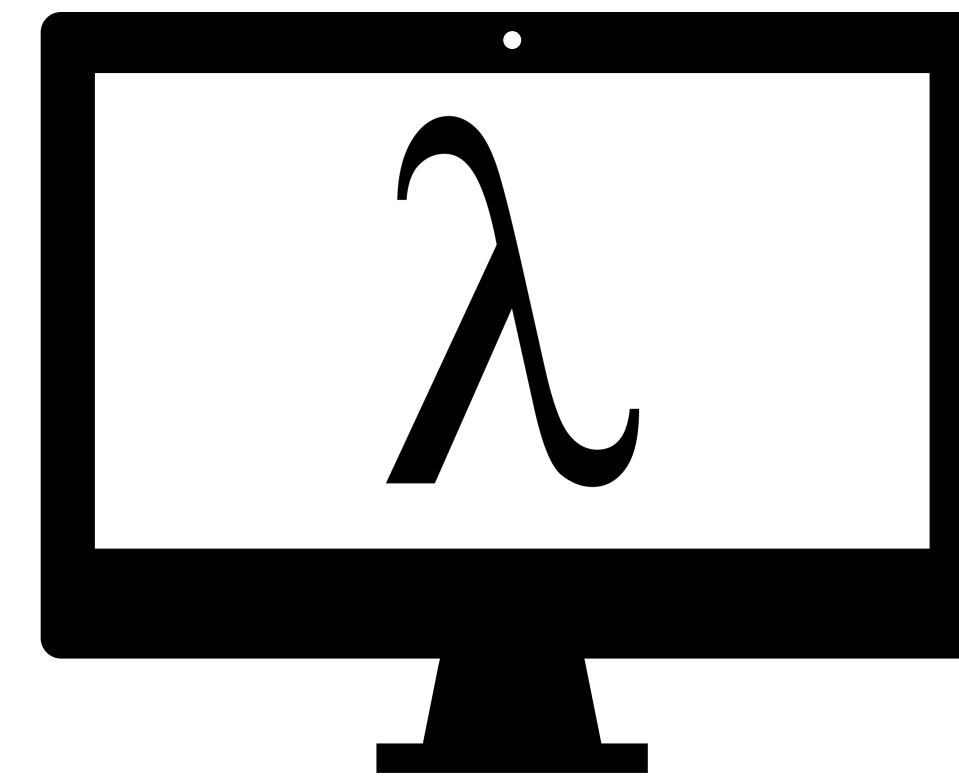


**Next-generation
Programming Systems**

목표

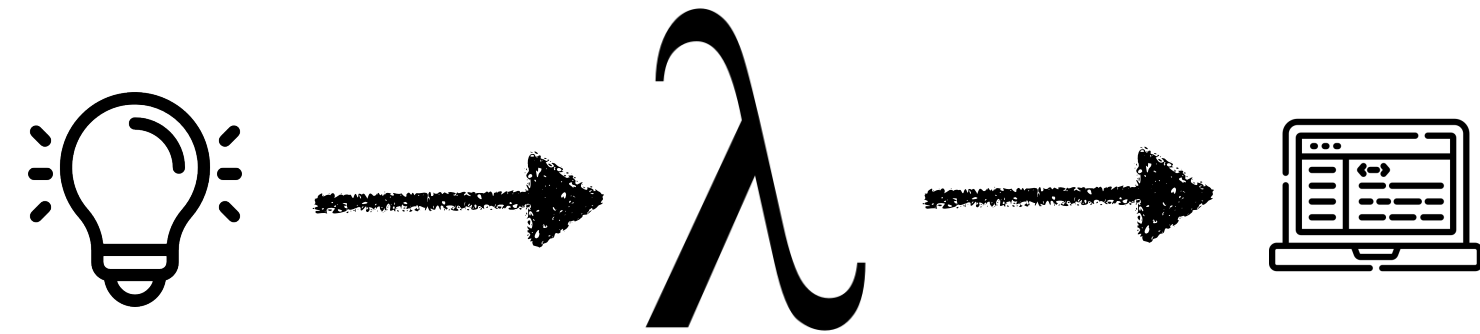


-  Safe
-  Simple
-  Smart

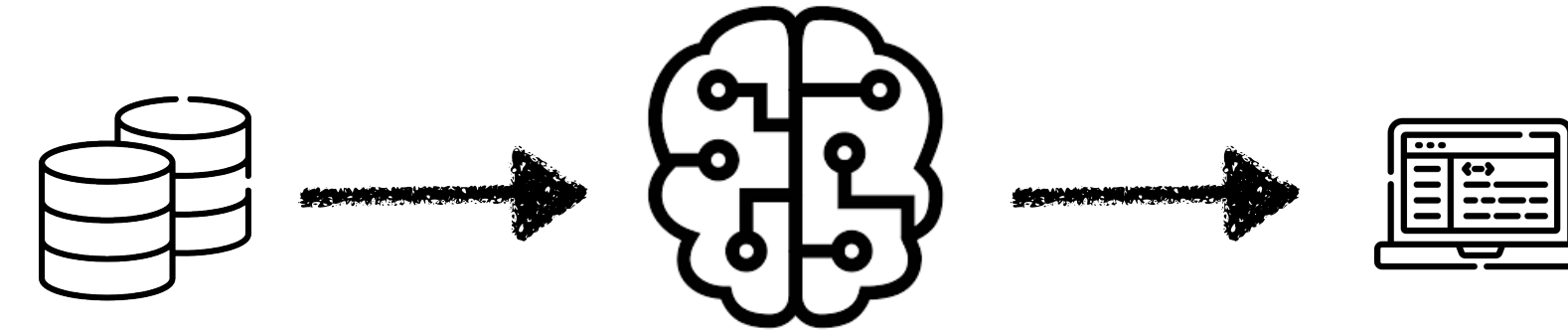


Next-generation
Programming Systems

PL vs ML

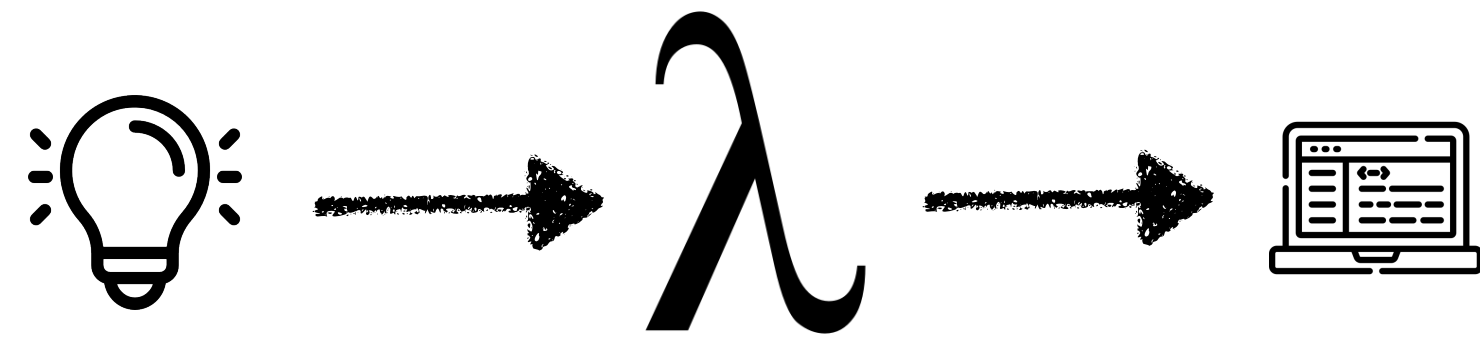


- 논리 기반
- 엄밀함 (문법, 실행 의미, 타입 등)
- 증명 가능, 해석 가능
- 올바른 답을 내지만 오래 걸릴 수도
- 못 푸는 문제도 있다 (예: 결정불가능)
- 사칙 연산, 논리 증명 등 잘함 (직렬순차)

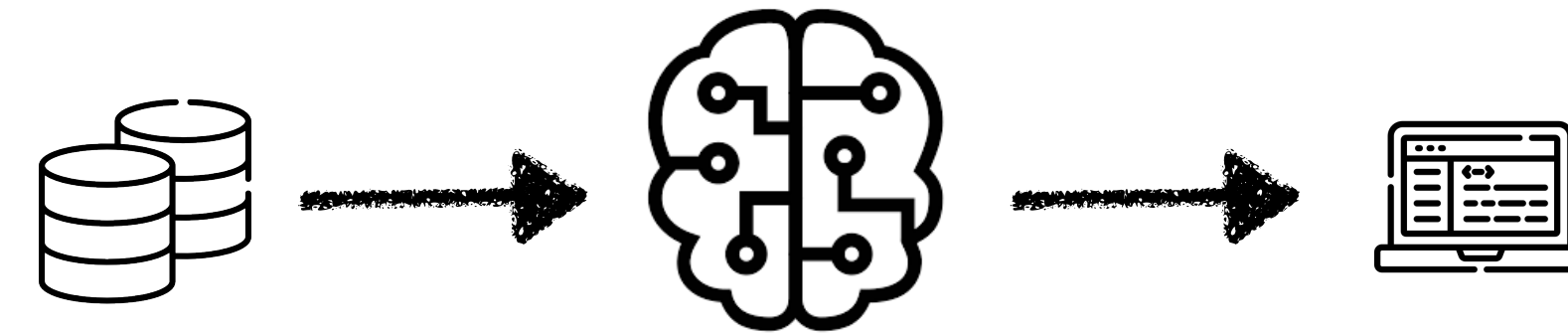


- 확률 기반
- 유연함 (모든 것이 숫자, 벡터)
- 증명과 해석이 어려움
- 그럴듯한 답을 빨리 내지만 틀릴 수도
- 못 푸는 문제는 없다 (정확도가 낮을 뿐)
- 그림 맞추기, 번역하기 등 잘함 (병렬동시)

PL + ML?



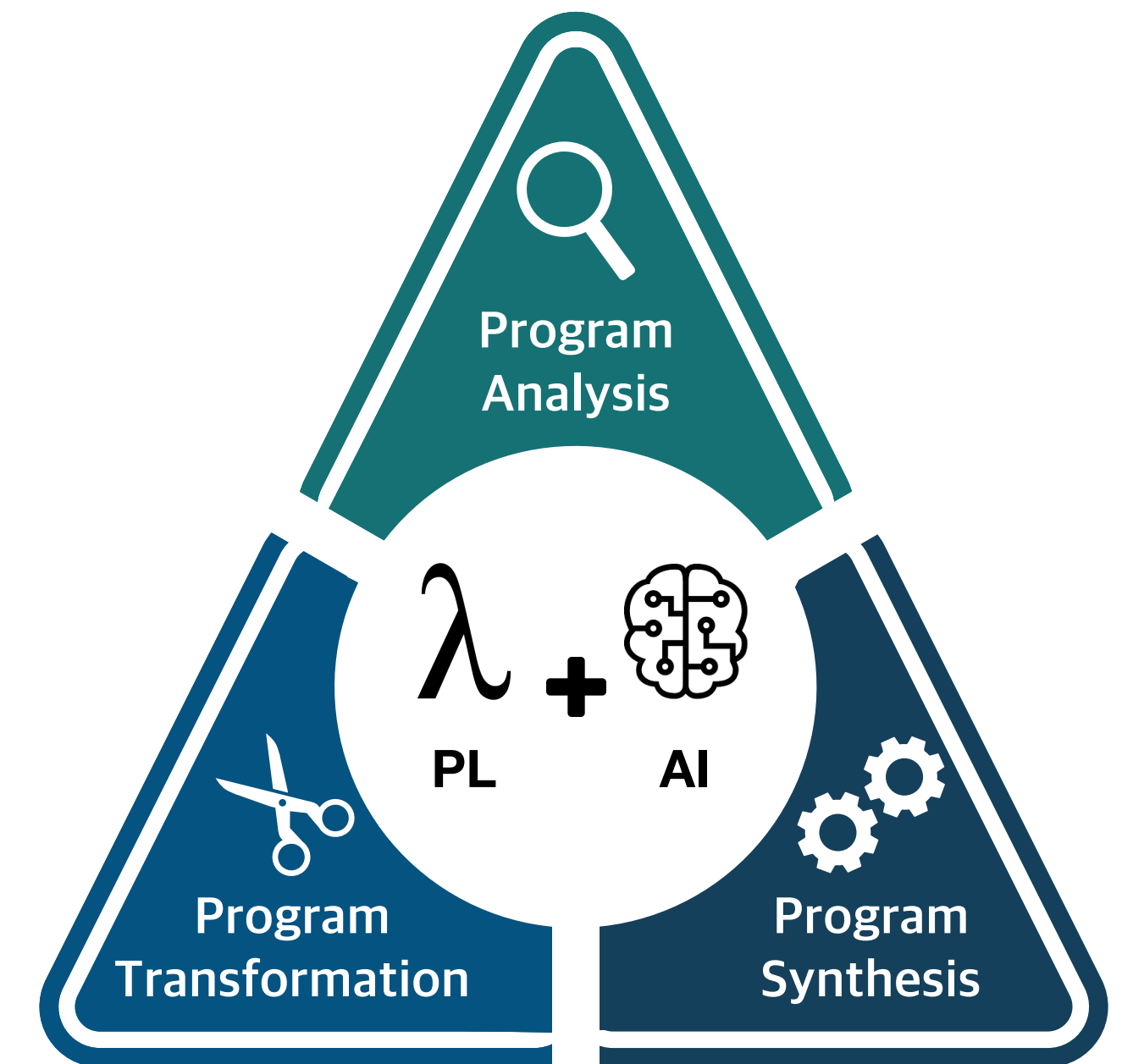
- 논리 기반
- 엄밀함 (문법, 실행 의미, 타입 등)
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- 확률 기반
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몇 가지 경험과 사례

- 프로그램 분석
 - 유연한 프로그램 분석을 위한 지도 학습, 강화 학습
 - 편리한 프로그램 분석을 위한 베이지안 추론
- 프로그램 변환과 합성
 - 빠른 합성을 위한 언어 모델
 - 빠른 변환을 위한 강화 학습



프로그램 정적 분석

- SW 의 동작을 자동으로 예측하는 일반적이고 체계적인 방법
 - 예측: 실행하기 전에 미리 (정적)
 - 자동: 소프트웨어를 분석하는 소프트웨어 (“분석기”)
 - 일반적: 언어와 성질에 국한되지 않음
 - 체계적 : 요약 해석 (abstract interpretation) 이라는 이론에 기반
- 응용: 오류 검출, 검증, 보안, 코드 유지보수, 코드 최적화 등

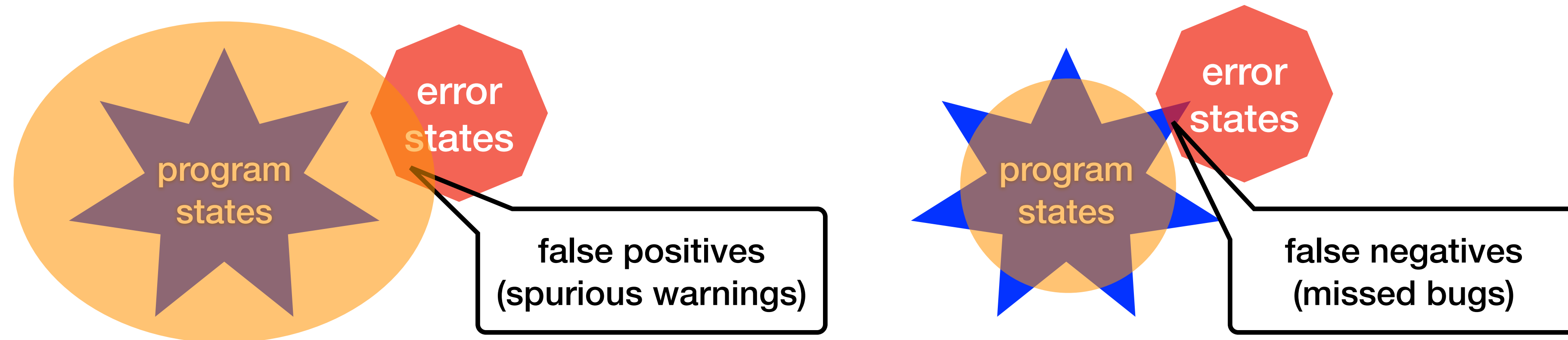


“SW MRI”

예제

```
1: static char *curfinal = "HDACB FE"; // curfinal: buffer of size 10
2:
3: keysym = read_from_input(); // keysym : any integer
4:
5: if ((KeySym)(keysym) >= 0xFF9987)
6: {
7:     unparseputc((char)(keysym - 0xFF91 + 'P'), pty);
8:     key = 1;
9: }
10: else if (keysym >= 0)
11: {
12:     if (keysym < 16) // keysym: [0, 15]
13:     {
14:         if (read_from_input())
15:         {
16:             if (keysym >= 10) return; // keysym: [0, 9]
17:             curfinal[keysym] = 1; // SAFE
18:         }
19:         else
20:         {
21:             curfinal[keysym] = 2; // Buffer-overflow, size of curfinal: [10, 10], keysym: [0, 15]
22:         }
23:     }
24:     if (keysym < 10) // keysym: [0, 9]
25:         unparseputc(curfinal[keysym], pty);
26: }
```

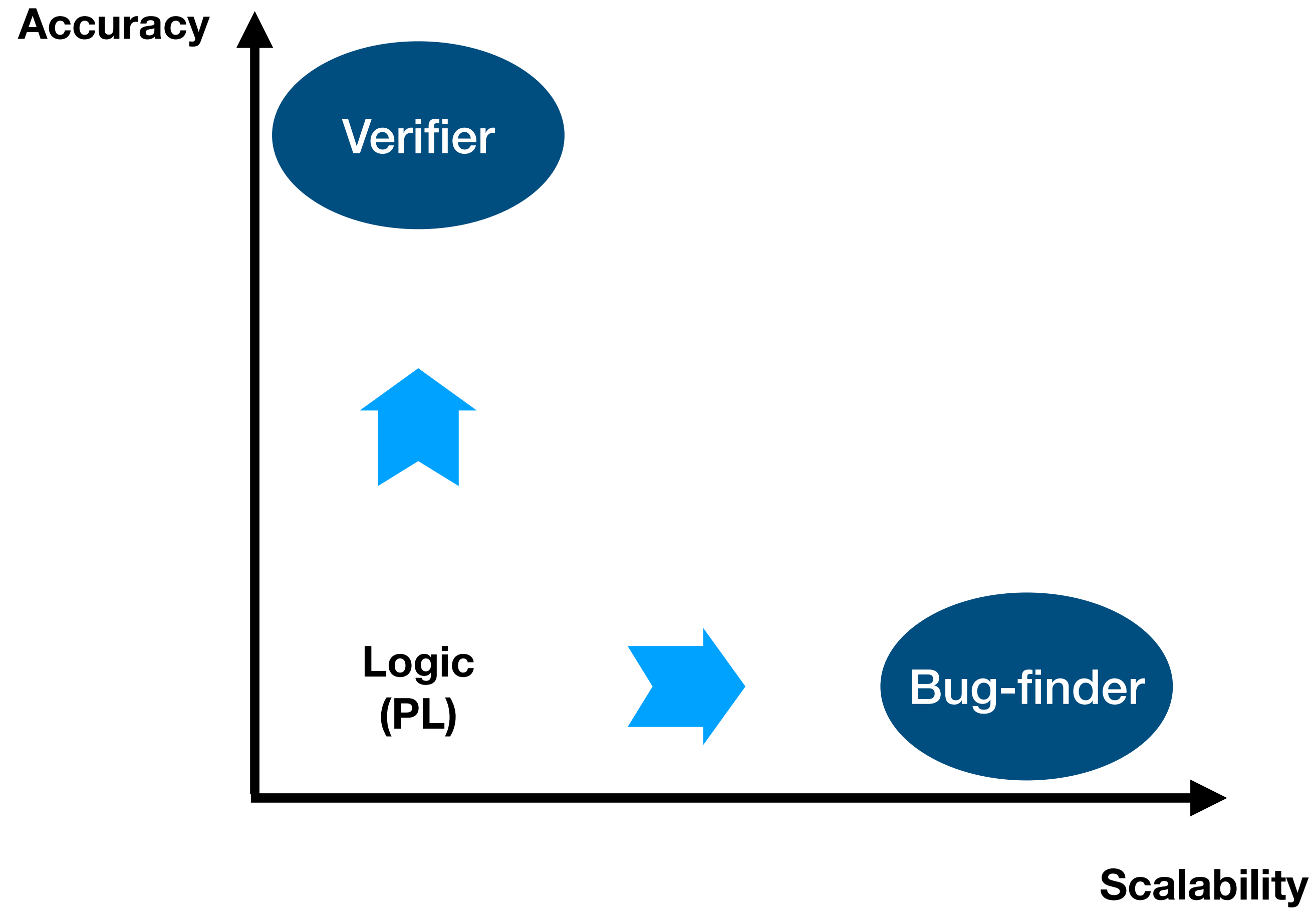
프로그램 분석의 고질적 문제



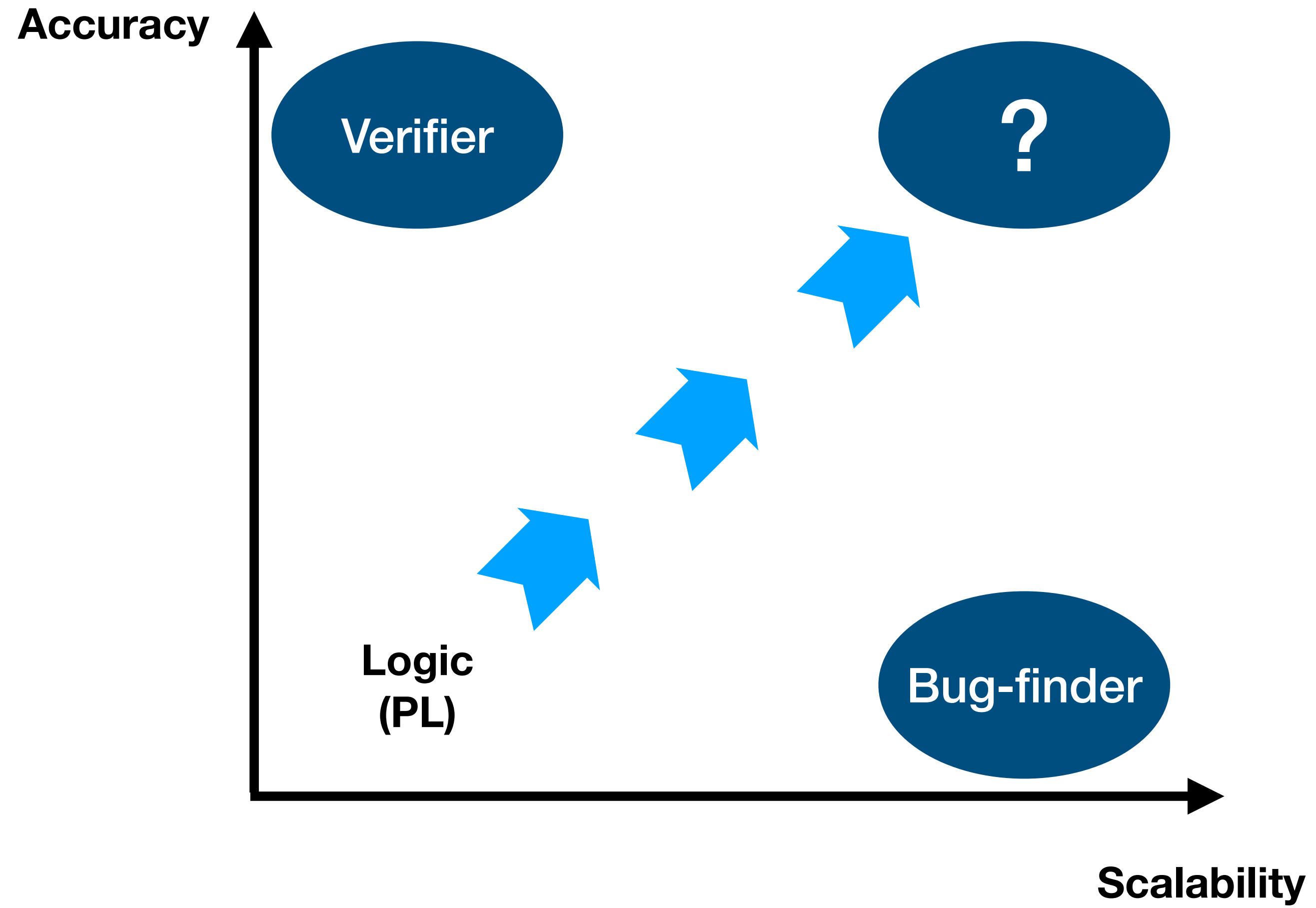
“... can be difficult to do without introducing large numbers of **false positives**, or scaling **performance** exponentially poorly. In this case, **balancing** these ... caused us to **miss the defect**.”

– *On Detecting Heartbleed with Static Analysis, (Coverity, 2014)*

전통적인 프로그램 분석



우리의 목표



전통적인 프로그램 분석의 문제점

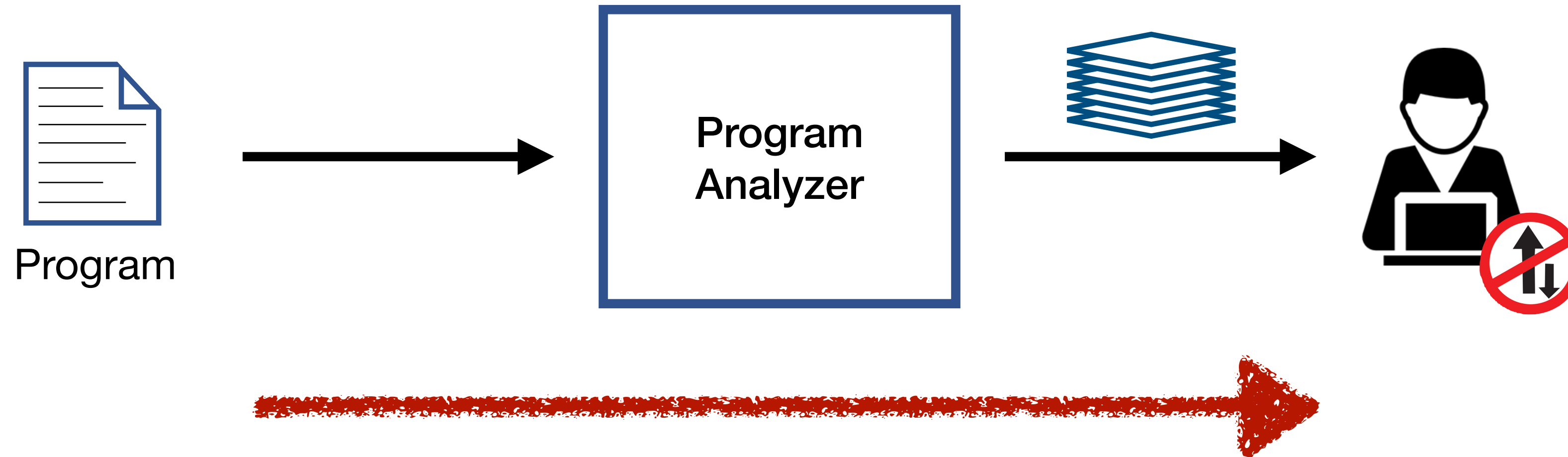


전통적인 프로그램 분석의 문제점



1. Inflexible

전통적인 프로그램 분석의 문제점



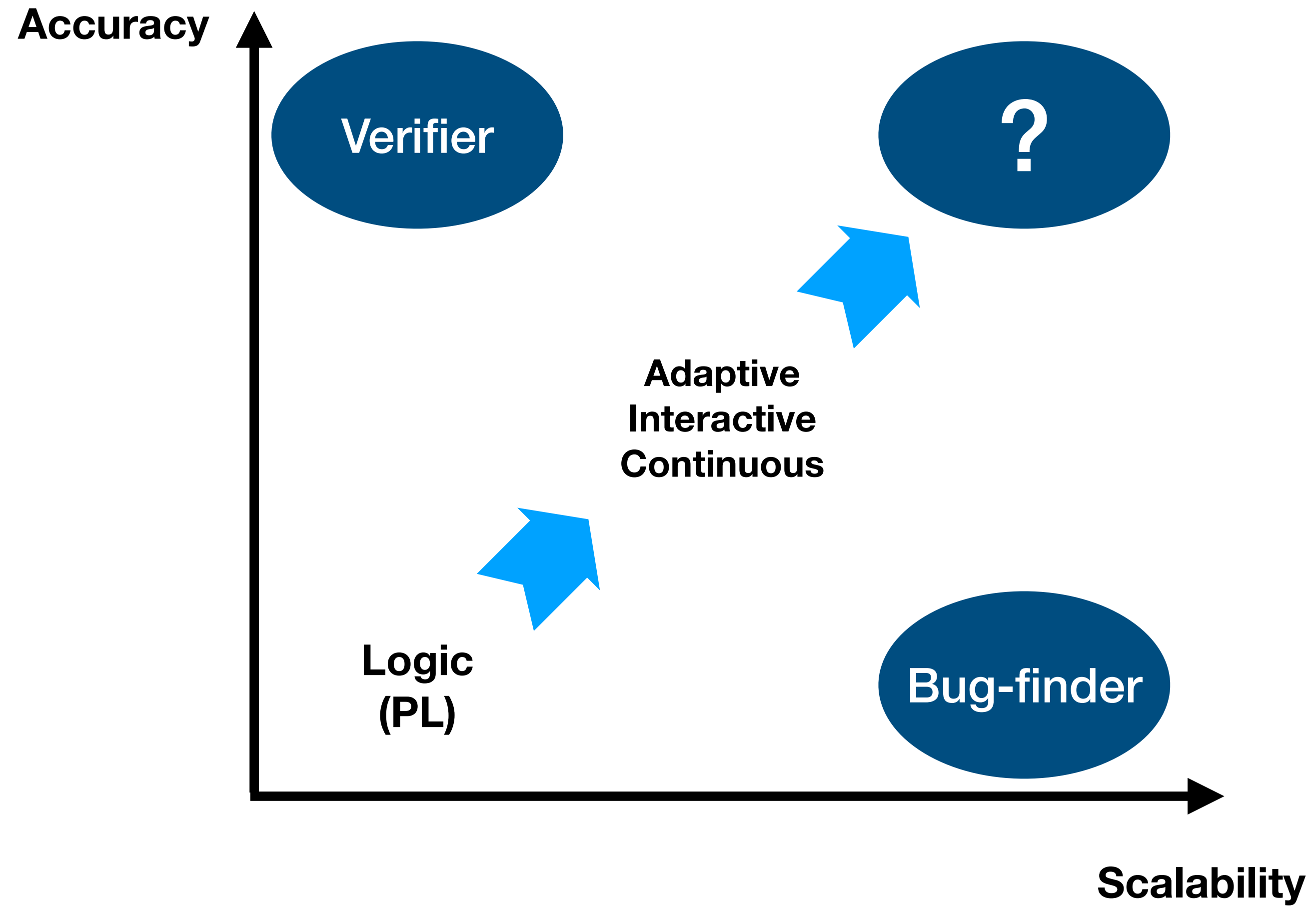
2. Unidirectional

전통적인 프로그램 분석의 문제점

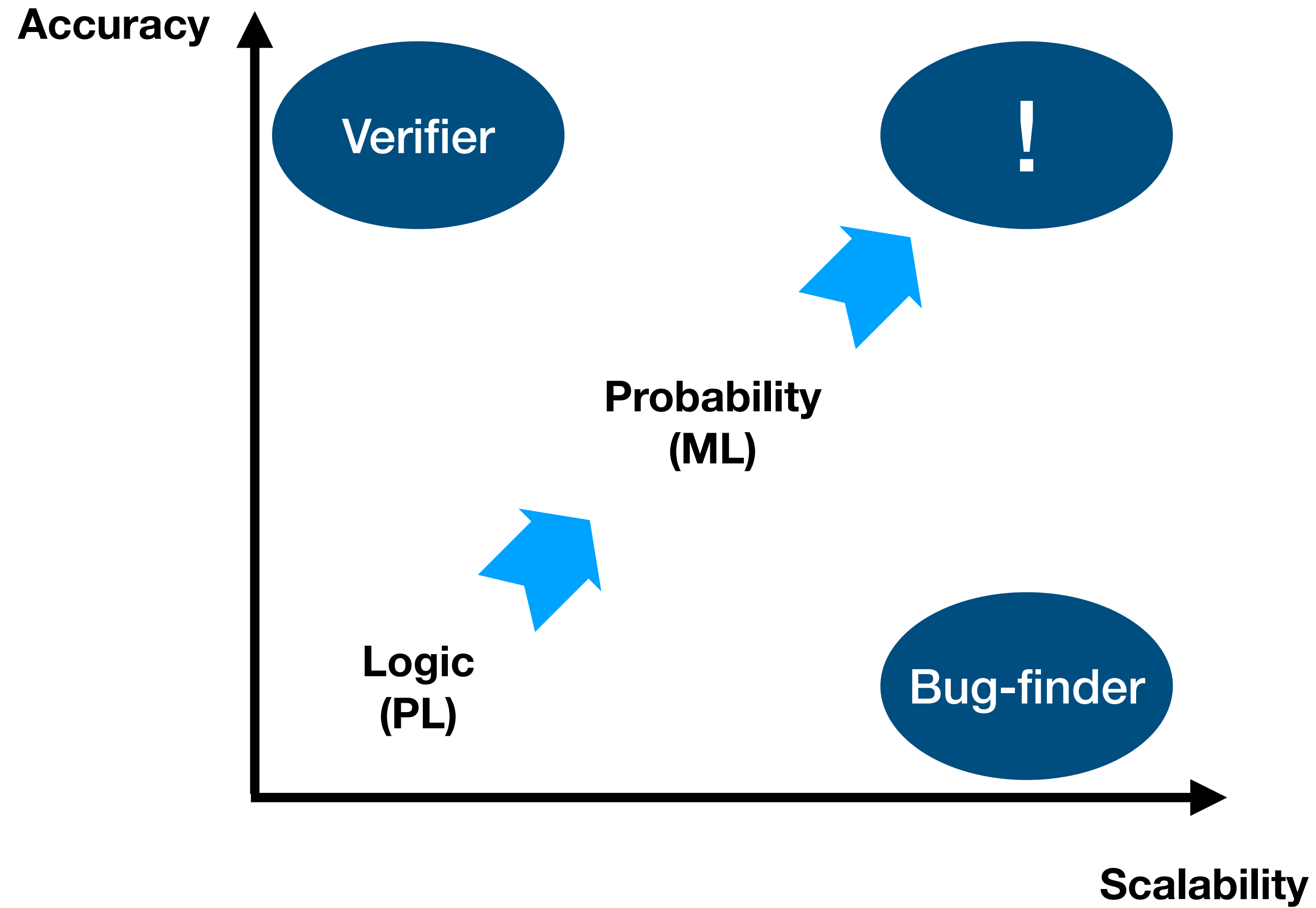


3. Narrow-sighted

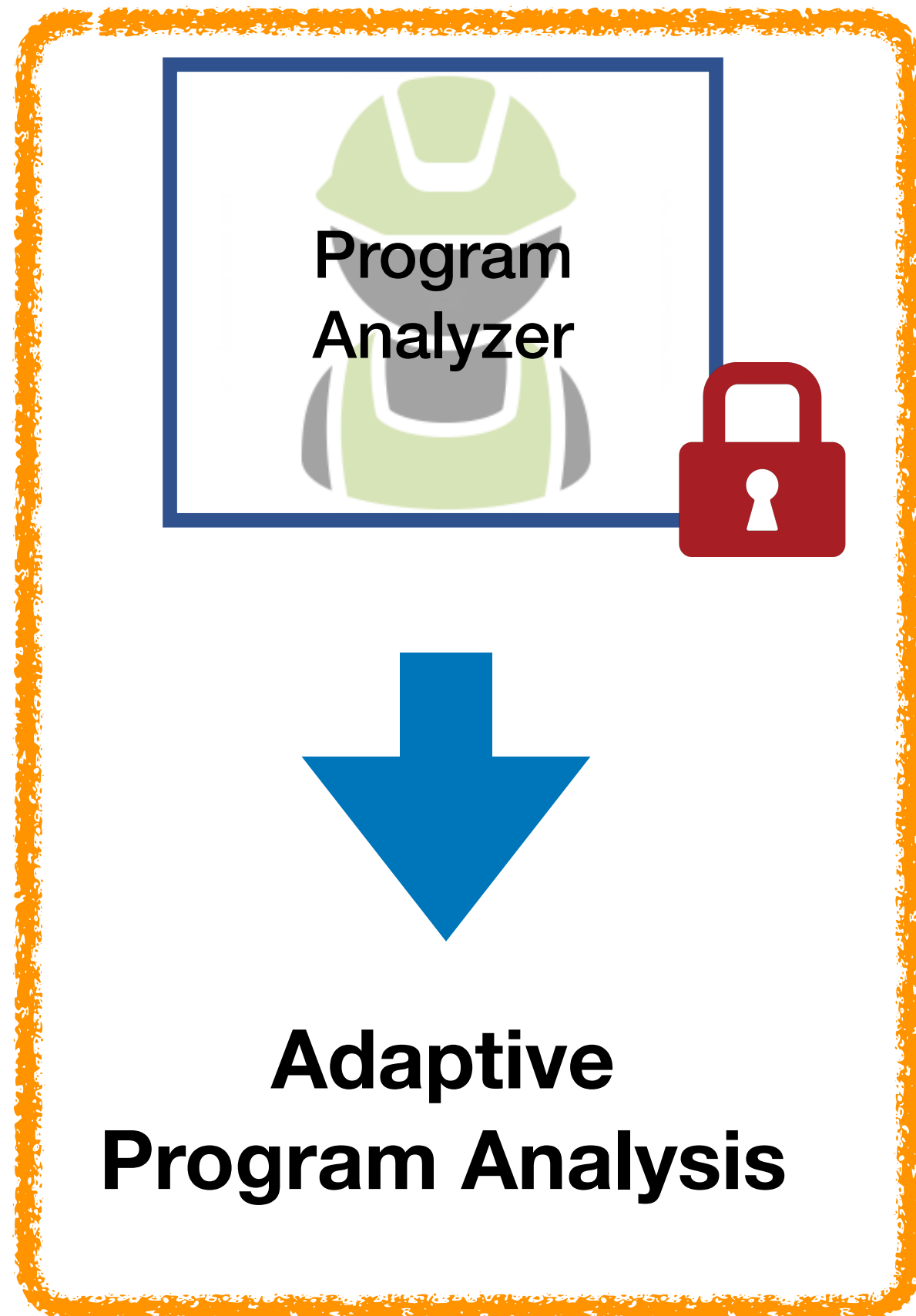
우리의 목표



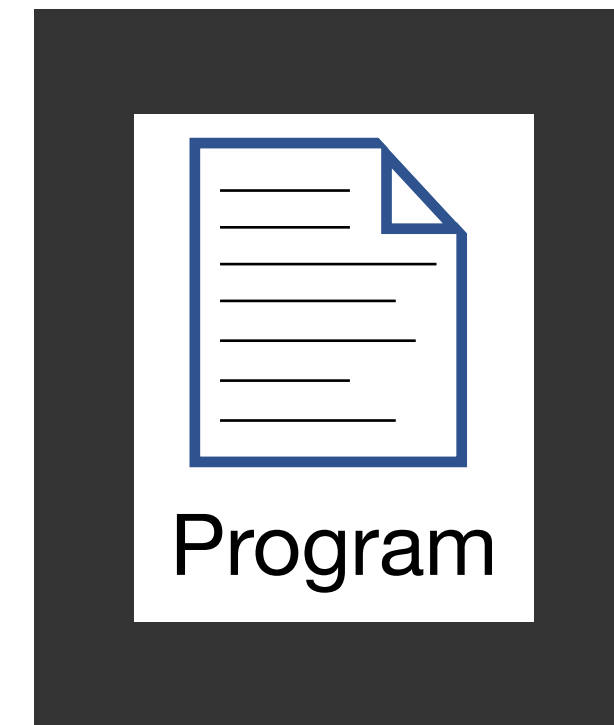
ML 을 이용한 정적 분석



세 가지 소원



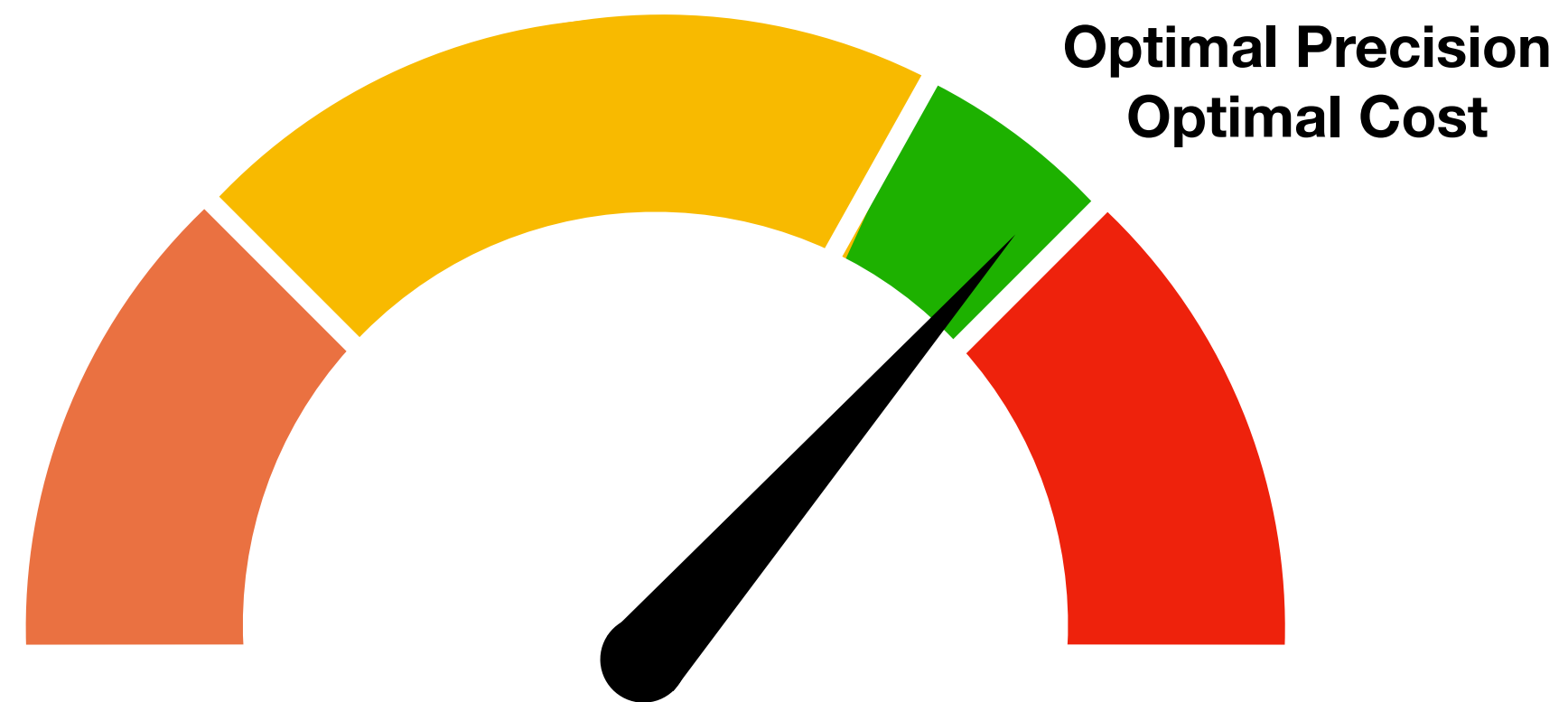
Interactive Program Analysis



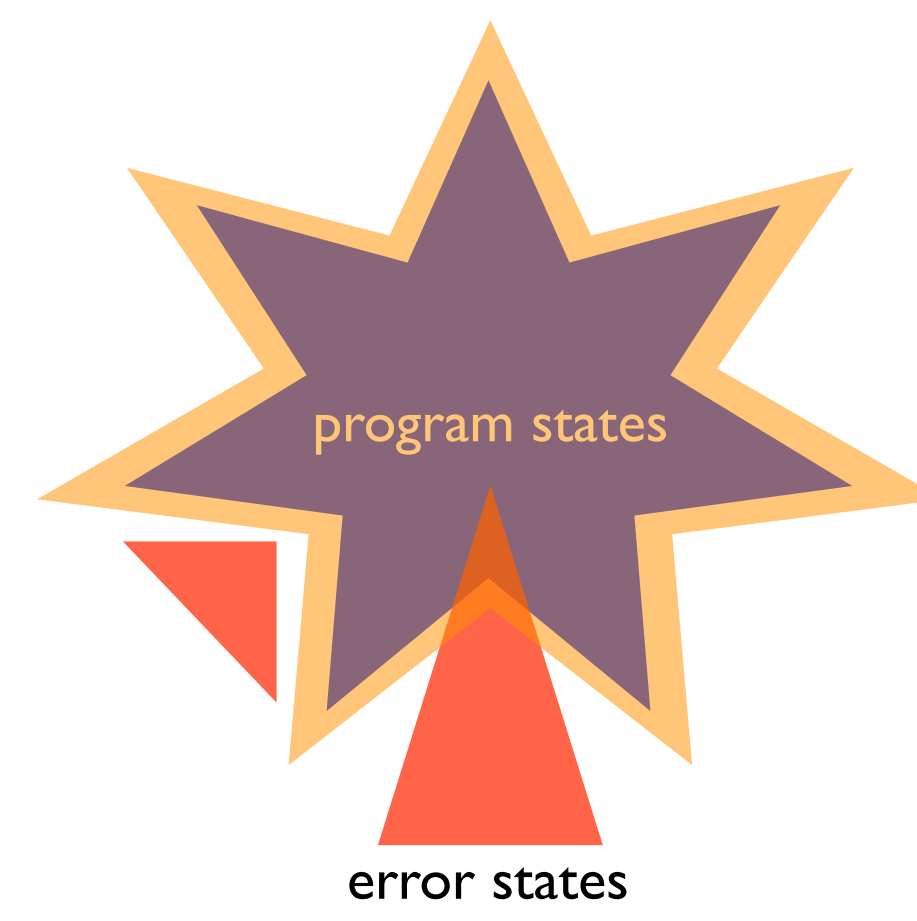
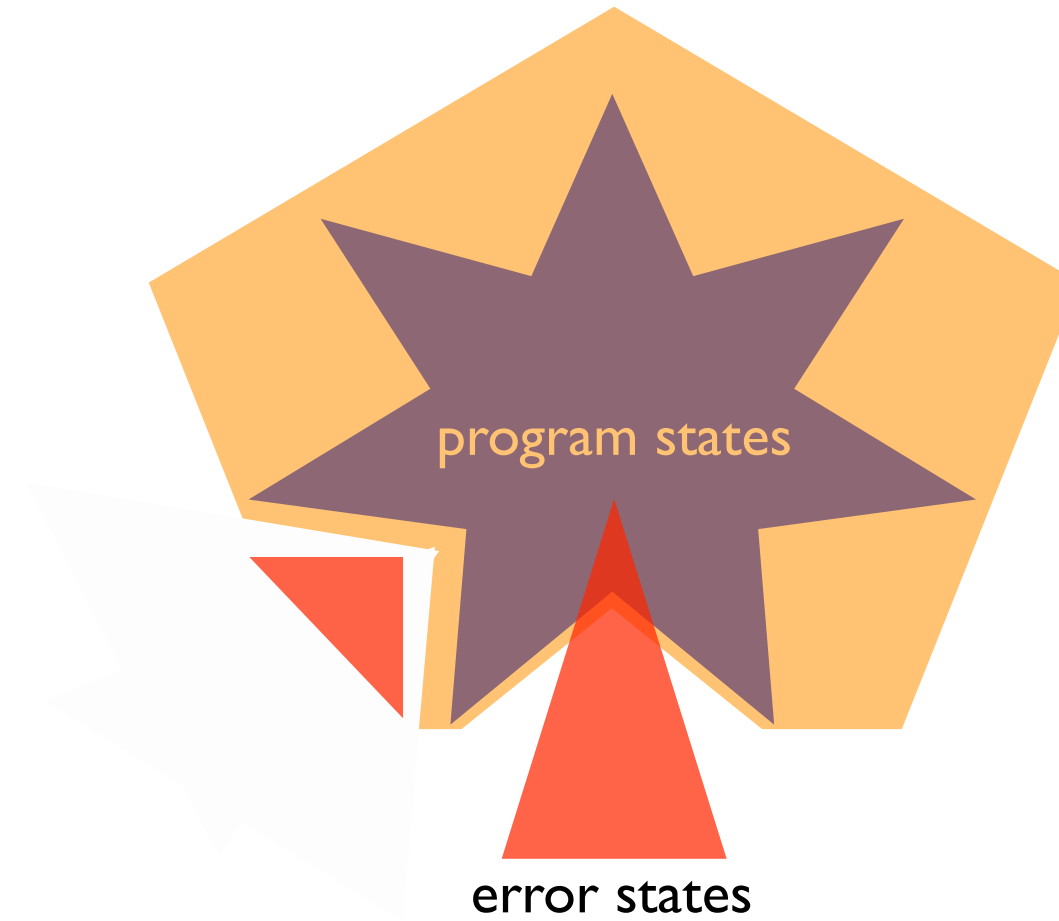
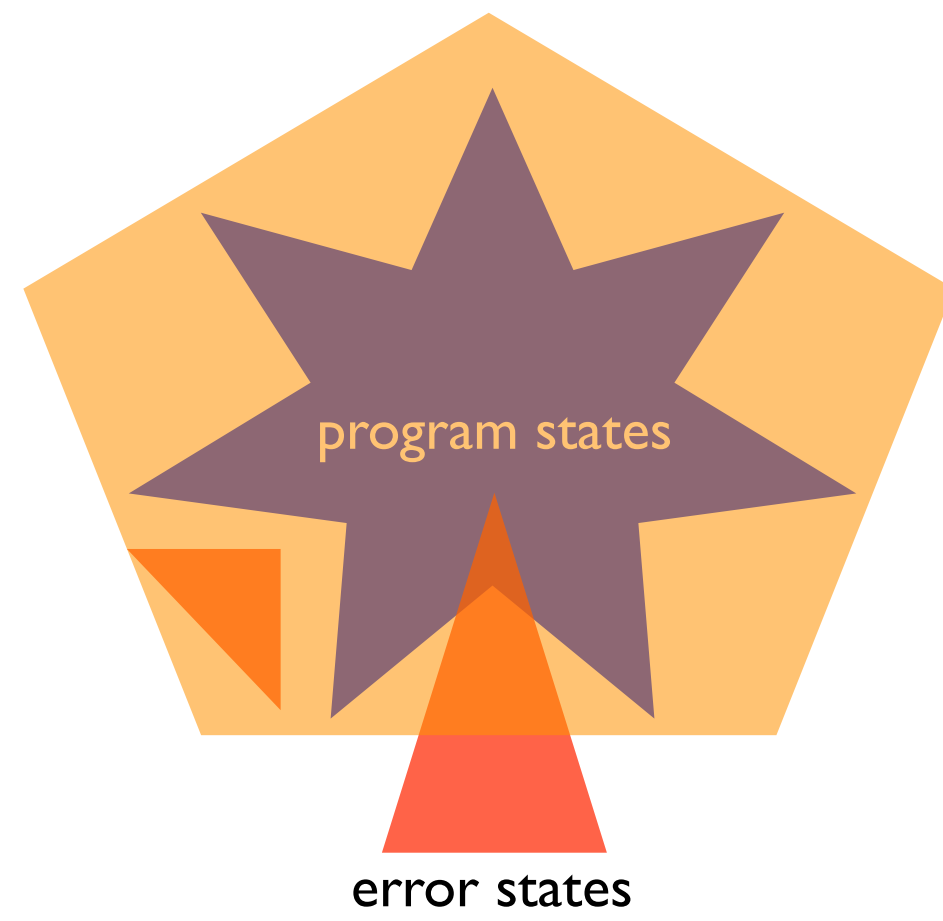
Continuous Program Analysis

Adaptive Program Analysis

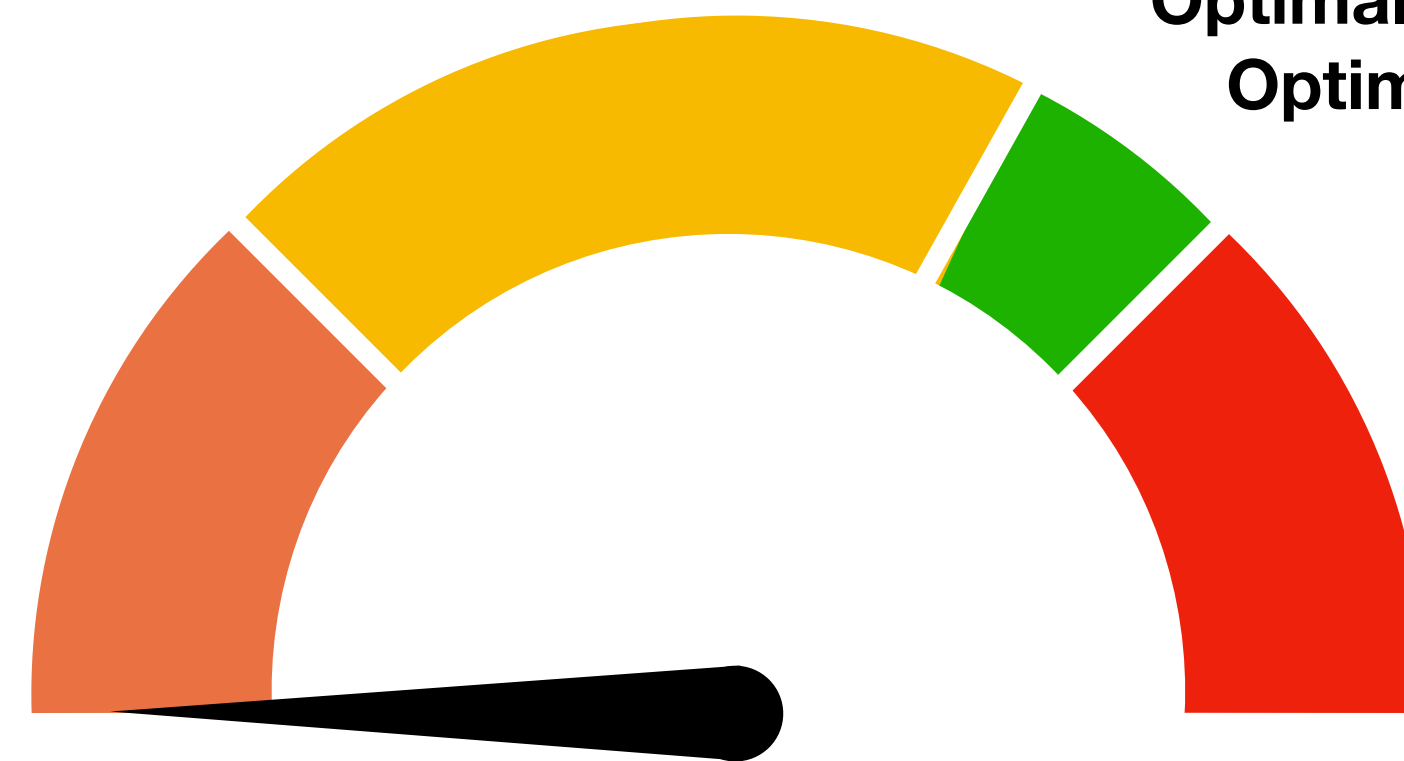
[SAS'16, OOPSLA'17, ICSE'17, ICSE'19]



유연한 정적 분석



Low Precision
Low Cost



High Precision
High Cost

Sensitivity (knob)

정적 분석기 길들이기

```
kihong@elvis01 ~$ clang -cc1 -analyzer-config-help | grep "default"
add-pop-up-notes (bool) Whether pop-up notes should be added to the final output. (default: true)
aggressive-binary-operation-simplification (bool) Whether SValBuilder should rearrange comparisons and additive operations of symbolic expressions to the maximum value of that type. A + n <OP> B + m becomes A - B <OP> m - n, where A and B symbolic, n and m are integers. <OP> is any of '=', '<!--
avoid-suppressing-null-argument-paths (bool) Whether a bug report should not be suppressed if its path includes a call with a null argument, even if the argument is a constant. (default: true)
c++-allocator-inlining (bool) Whether or not allocator call may be considered for inlining. (default: true)
c++-container-inlining (bool) Whether or not methods of C++ container objects may be considered for inlining. (default: false)
c++-inlining (string) Controls which C++ member functions will be considered for inlining. Value: "constructors", "destructors"
c++-shared_ptr-inlining (bool) Whether or not the destructor of C++ 'shared_ptr' may be considered for inlining. This covers std::shared_ptr
c++-stdlib-inlining (bool) Whether or not C++ standard library functions may be considered for inlining. (default: true)
c++-temp-dtor-inlining (bool) Whether C++ temporary destructors should be inlined during analysis. If temporary destructors are disabled, this option has no effect. (default: true)
c++-template-inlining (bool) Whether or not templated functions may be considered for inlining. (default: true)
cfg-conditional-static-initializers (bool) Whether 'static' initializers should be in conditional logic in the CFG. (default: true)
cfg-implicit-dtors (bool) Whether or not implicit destructors for C++ objects should be included in the CFG. (default: true)
cfg-lifetime (bool) Whether or not end-of-lifetime information should be included in the CFG. (default: false)
cfg-loopexit (bool) Whether or not the end of the loop information should be included in the CFG. (default: false)
cfg-rich-constructors
cfg-scopes
cfg-temporary-dtors
crosscheck-with-z3
ctu-dir
ctu-import-threshold
ctu-index-name
display-ctu-progress
eagerly-assume
downside is that it eagerly
elide-constructors
expand-macros
experimental-enable-naive
exploration_strategy
faux-bodies
graph-trim-interval
inline-lambdas
ipa
ipa-always-inline-size
max-inlinable-size
max-nodes
max-symbol-complexity
max-times-inline-large
min-cfg-size-treat-function
mode
model-path
notes-as-events
objc-inlining
prune-paths
region-store-small-struct
report-in-main-source-file
serialize-stats
stable-report-filename
suppress-c++-stdlib
suppress-inlined-defensive
suppress-null-return-path
track-conditions
track-conditions-debug
unroll-loops
widen-loops
```

[cfe-dev] Handling of loops in the Clang Static Analyzer

Sean Eveson via cfe-dev [cfe-dev at lists.lvm.org](mailto:cfe-dev@lists.lvm.org)
Mon Feb 27 03:18:36 PST 2017

- Previous message: [\[cfe-dev\] Handling of loops in the Clang Static Analyzer](#)
- Next message: [\[cfe-dev\] Handling of loops in the Clang Static Analyzer](#)
- Messages sorted by: [\[date\]](#) | [\[thread\]](#) | [\[subject\]](#) | [\[author\]](#)

Hi Venugopal,

> Sean Eveson (cc'd) did some initial work on loop widening to mitigate this problem.

I started to work on this, but have unfortunately not had time to take the next steps. There is a mode which does 'loop widening' which is off by

FAQ and How to Deal with Common False Positives

1. [How do I tell the analyzer that I do not want the bug being reported here since my custom error handler will safely end the execution before the bug is reached?](#)
2. [The analyzer reports a null dereference, but I know that the pointer is never null. How can I tell the analyzer that a pointer can never be null?](#)
3. [How do I tell the static analyzer that I don't care about a specific dead store?](#)
4. [How do I tell the static analyzer that I don't care about a specific unused instance variable in Objective C?](#)
5. [How do I tell the static analyzer that I don't care about a specific unlocalized string?](#)
6. [How do I tell the analyzer that my instance variable does not need to be released in -dealloc under Manual Retain/Release?](#)
7. [How do I decide whether a method's return type should be _Nullable or _Nonnull?](#)
8. [How do I tell the analyzer that I am intentionally violating nullability?](#)
9. [The analyzer assumes that a loop body is never entered. How can I tell it that the loop body will be entered at least once?](#)
10. [How can I suppress a specific analyzer warning?](#)
11. [How can I selectively exclude code the analyzer examines?](#)

세상에 나쁜 정적 분석은 없다

정적 분석 훈련사

의뢰인 개발자



공간탐색

AlphaGo



Lee Sedol



ALPHAGO
01:59:50

LEE SEDOL
01:59:44



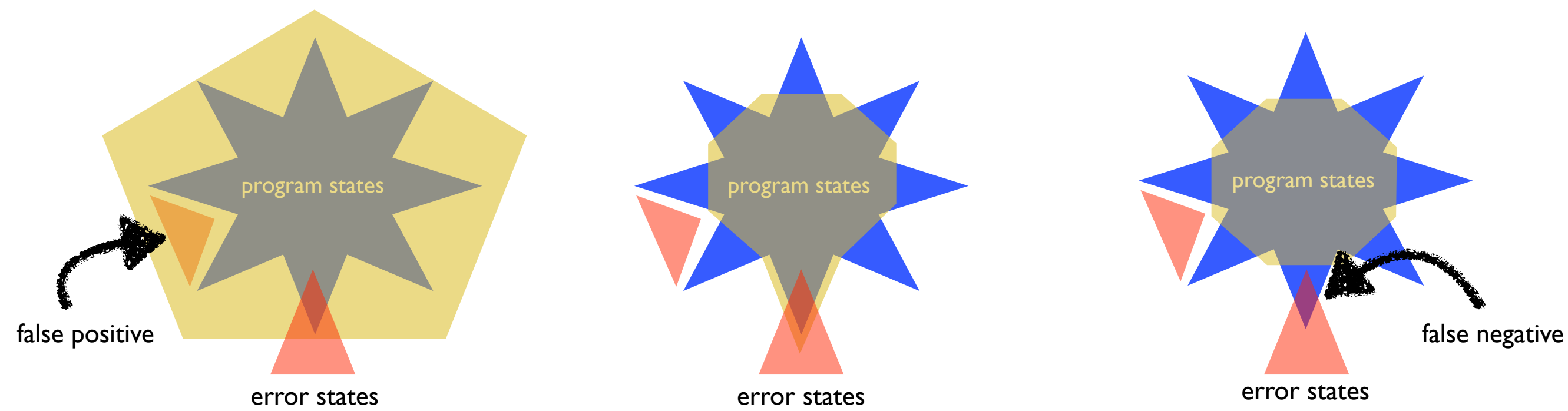
여러 사례

Abstraction (Knob)	Cost	Online/Offline	Method	Result
Variable Relationship	Running Time	Offline	Supervised Learning	[SAS'16]
Statement Order Variable Relationship	Running Time	Offline	Supervised Learning	[OOPSLA'17]
Loop Unrolling Library Call Handling	Missed Bugs	Offline	Supervised Learning	[ICSE'17]
Statement Order	Memory Consumption	Online	Reinforcement Learning	[ICSE'19]

선별적으로 안전한 분석

- 정확도를 높이기 위해 안전성 (soundness) 을 포기하는 여러 전략
 - 예: 유한번 순환문 풀기, 복잡한 라이브러리 함수 무시

`while(e){ C }` ▶ `if(e){ C }` `A;lib();B;` ▶ `A;B;`






Uniformly Sound

Selectively Unsound

Uniformly Unsound

예제

- 인터벌 도메인을 이용한 버퍼 오버런 분석기: 모든 순환문을 **안전하게** 분석

```
str = "hello world";  
for (i = 0; str[i]; i++) // buffer access 1   
    skip;  
  
size = positive_input();  
for (i = 0; i < size; i++)  
    skip;  
  
str[i] = ... // buffer access 2  
```

str.size: [12, 12]




i: [0, +∞]

size: [0, +∞]

i: [0, +∞]

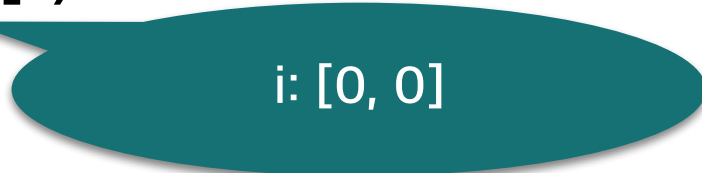


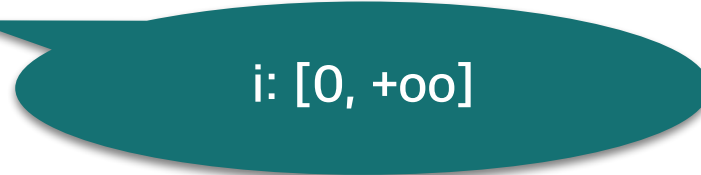
예제

- 인터벌 도메인을 이용한 버퍼 오버런 분석기: 모든 순환문을 **안전하지 않게** 분석

```
str = "hello world";  
i = 0;  
if (str[i]) // buffer access 1  
    skip;   
  
size = positive_input();  
i = 0;  
if (i < size)  
    skip;  
  
str[i] = ... // buffer access 2  
```

예제

- 인터벌 도메인을 이용한 버퍼 오버런 분석기: **필요할 때 적절히** 안전성을 포기하는 분석

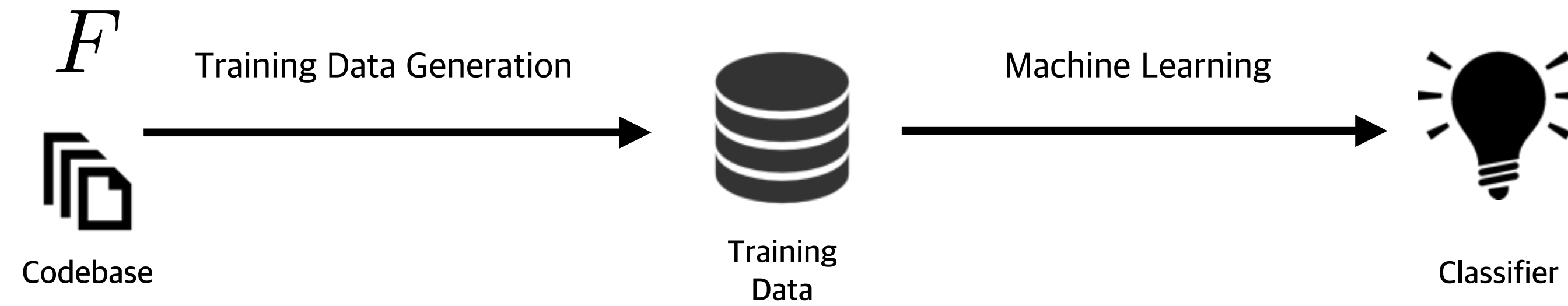
```
str = "hello world";  
i = 0;  
if (str[i]) // buffer access 1  
    skip;  i: [0, 0]  
  
size = positive_input();  
for (i = 0; i < size; i++)  
    skip;  
  
str[i] = ... // buffer access 2    
 i: [0, +oo]
```

문제 정의

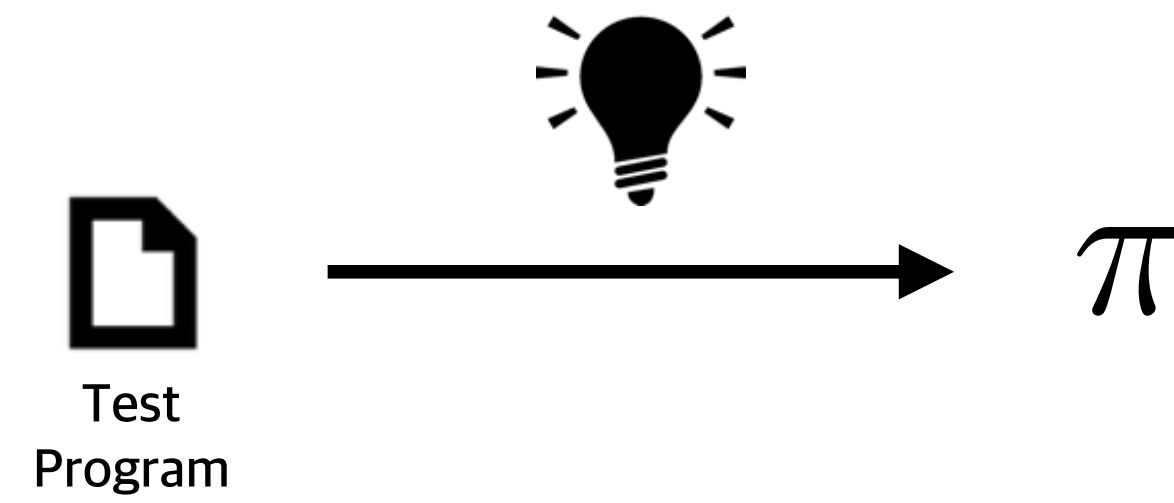
$$F \in Pgm \times \Pi \rightarrow \mathcal{A}$$

- 목표: 안전성 포기 대상의 집합 $\pi \in \Pi$ 찾기
 - 최대한 많은 오류를 찾아내면서, 거짓 경보는 최소화
 - 예: 순환문 ($\Pi = 2^{Loop}$), 라이브러리 호출 ($\Pi = 2^{Lib}$)
- 분석: 해당 집합의 원소들에 안전성 포기 전략을 적용

조감도



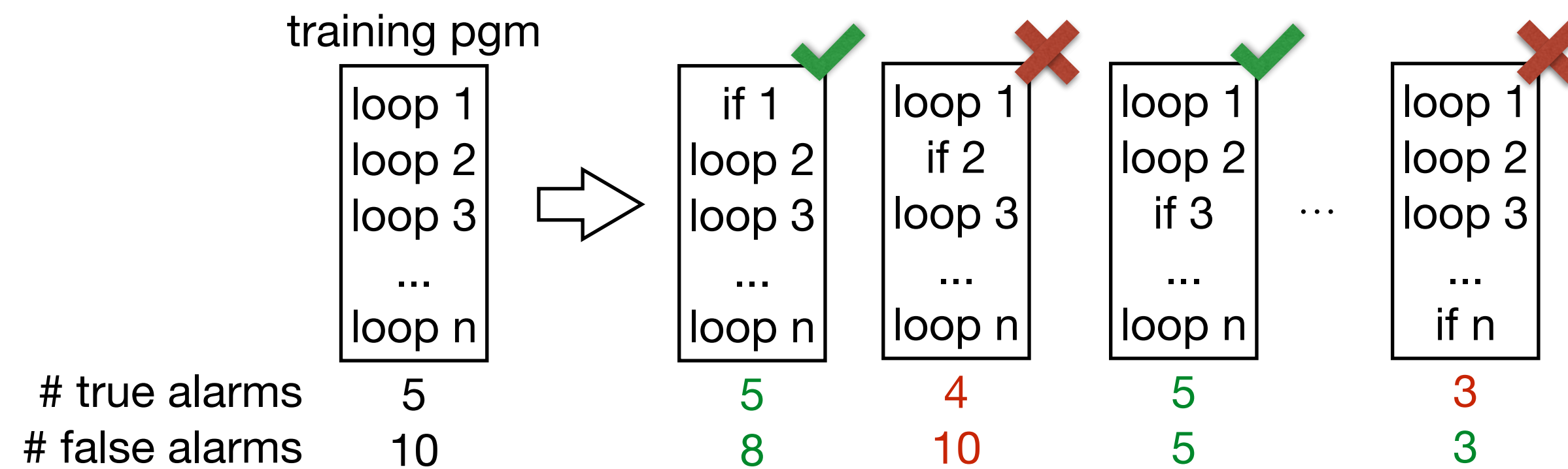
Training Harmless Unsoundness



Inferring Harmless Unsoundness

학습 데이터 수집

- 오류 지점이 알려져 있는 프로그램 집합 + 안전성을 조절할 수 있는 분석기
- 안전성 포기 전략이 적용되었을 때 1) 거짓 경보는 줄어들고, 2) 오류는 하나도 놓치지 않는 대상



특징 벡터와 학습

- 각 데이터를 특징 벡터 (feature vector) 로 표현

$$f(x) = \langle f_1(x), f_2(x), \dots, f_n(x) \rangle$$

$$f(\text{loop}_1) = \langle 1, 0, \dots, 1 \rangle$$

$$f(\text{loop}_2) = \langle 0, 1, \dots, 1 \rangle$$

$$f(\text{lib}_1) = \langle 0, 1, \dots, 0 \rangle$$

$$f(\text{lib}_2) = \langle 1, 1, \dots, 1 \rangle$$

- 데이터를 토대로 분류기 (classifier) 를 학습
 - 널리 알려진 학습 알고리즘 이용 (예: SVM)

순환문의 특징 벡터

- 22 가지 구문적, 의미적 특징

Feature	Property	Type	Description
Null	Syntactic	Binary	Whether the loop condition contains nulls or not
Const	Syntactic	Binary	Whether the loop condition contains constants or not
Array	Syntactic	Binary	Whether the loop condition contains array accesses or not
Conjunction	Syntactic	Binary	Whether the loop condition contains && or not
IdxSingle	Syntactic	Binary	Whether the loop condition contains an index for a single array in the loop
IdxMulti	Syntactic	Binary	Whether the loop condition contains an index for multiple arrays in the loop
IdxOutside	Syntactic	Binary	Whether the loop condition contains an index for an array outside of the loop
InitIdx	Syntactic	Binary	Whether an index is initialized before the loop
Exit	Syntactic	Numeric	The (normalized) number of exits in the loop
Size	Syntactic	Numeric	The (normalized) size of the loop
ArrayAccess	Syntactic	Numeric	The (normalized) number of array accesses in the loop
ArithInc	Syntactic	Numeric	The (normalized) number of arithmetic increments in the loop
PointerInc	Syntactic	Numeric	The (normalized) number of pointer increments in the loop
Prune	Semantic	Binary	Whether the loop condition prunes the abstract state or not
Input	Semantic	Binary	Whether the loop condition is determined by external inputs
GVar	Semantic	Binary	Whether global variables are accessed in the loop condition
FinInterval	Semantic	Binary	Whether a variable has a finite interval value in the loop condition
FinArray	Semantic	Binary	Whether a variable has a finite size of array in the loop condition
FinString	Semantic	Binary	Whether a variable has a finite string in the loop condition
LCSize	Semantic	Binary	Whether a variable has an array of which the size is a left-closed interval
LCOffset	Semantic	Binary	Whether a variable has an array of which the offset is a left-closed interval
#AbsLoc	Semantic	Numeric	The (normalized) number of abstract locations accessed in the loop

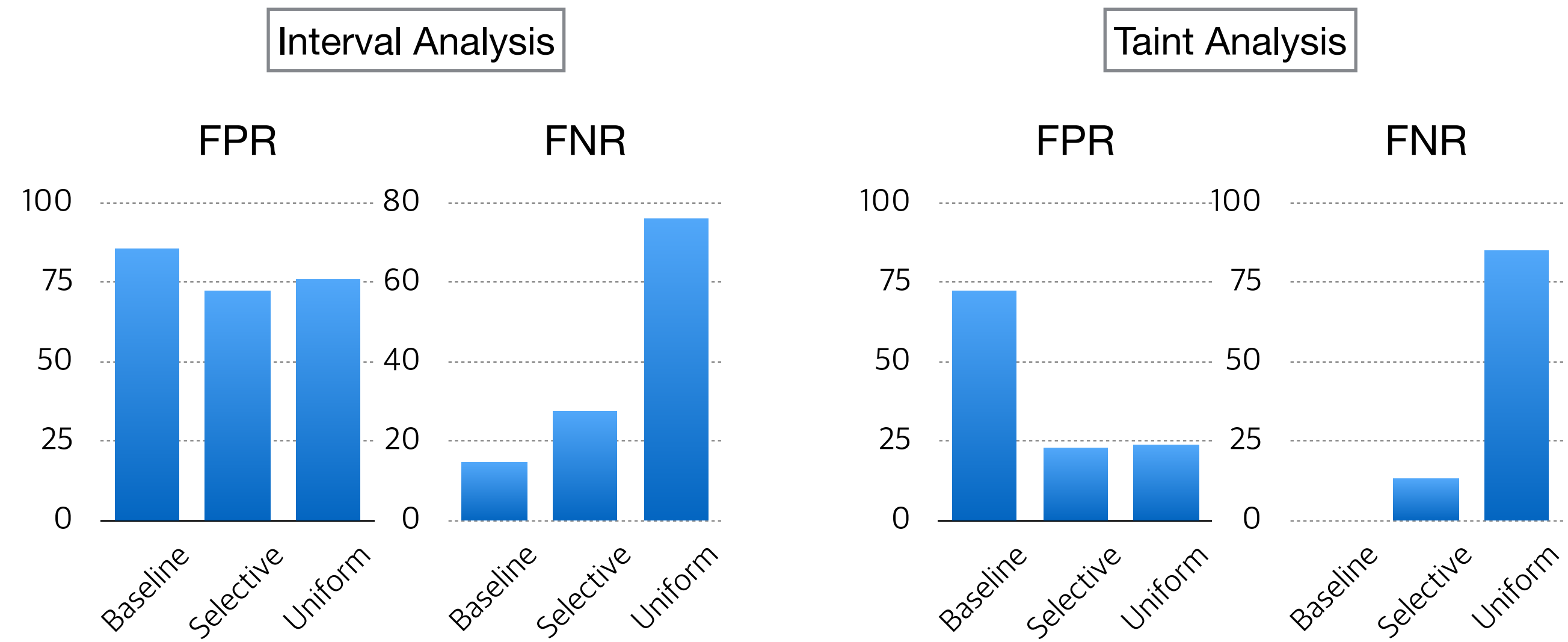
라이브러리 호출의 특징 벡터

- 15 가지 구문적, 의미적 특징

Feature	Property	Type	Description
Const	Syntactic	Binary	Whether the parameters contain constants or not
Void	Syntactic	Binary	Whether the return type is void or not
Int	Syntactic	Binary	Whether the return type is int or not
CString	Syntactic	Binary	Whether the function is declared in <code>string.h</code> or not
InsideLoop	Syntactic	Binary	Whether the function is called in a loop or not
#Args	Syntactic	Numeric	The (normalized) number of arguments
DefParam	Semantic	Binary	Whether a parameter are defined in a loop or not
UseRet	Semantic	Binary	Whether the return value is used in a loop or not
UptParam	Semantic	Binary	Whether a parameter is update via the library call
Escape	Semantic	Binary	Whether the return value escapes the caller
GVar	Semantic	Binary	Whether a parameters points to a global variable
Input	Semantic	Binary	Whether a parameters are determined by external inputs
FinInterval	Semantic	Binary	Whether a parameter have a finite interval value
#AbsLoc	Semantic	Numeric	The (normalized) number of abstract locations accessed in the arguments
#ArgString	Semantic	Numeric	The (normalized) number of string arguments

성능

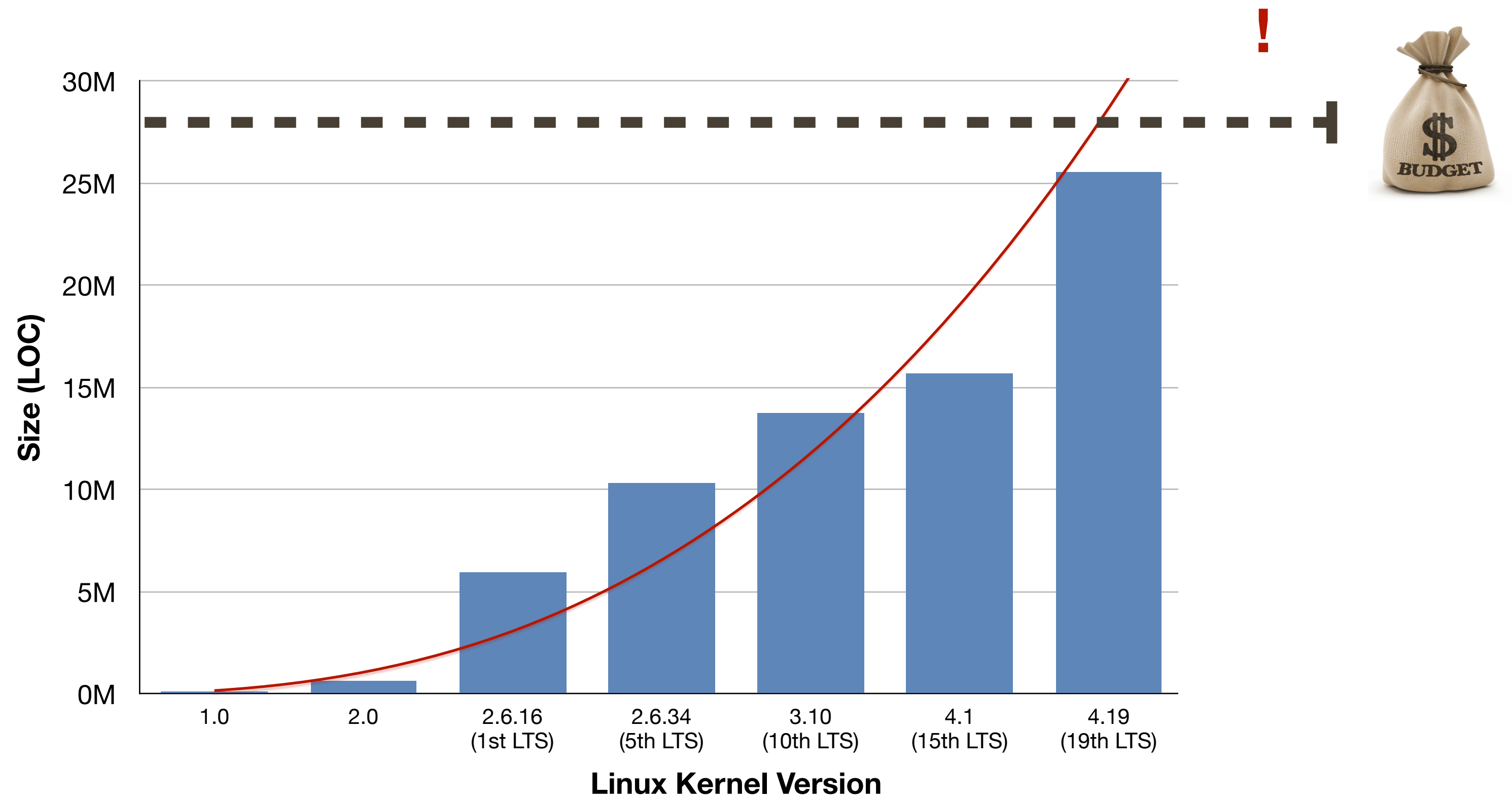
- 두 가지 분석
 - 정수 구간 (interval) 분석: 138 버퍼 오버런 오류 / 23 프로그램
 - 오염 (taint) 분석: 106 포맷 스트링 오류 / 13 프로그램



여러 사례

Abstraction (Knob)	Cost	Online/Offline	Method	Result
Variable Relationship	Running Time	Offline	Supervised Learning	[SAS'16]
Statement Order Variable Relationship	Running Time	Offline	Supervised Learning	[OOPSLA'17]
Loop Unrolling Library Call Handling	Missed Bugs	Offline	Supervised Learning	[ICSE'17]
Statement Order	Memory Consumption	Online	Reinforcement Learning	[ICSE'19]

어제, 오늘 그리고



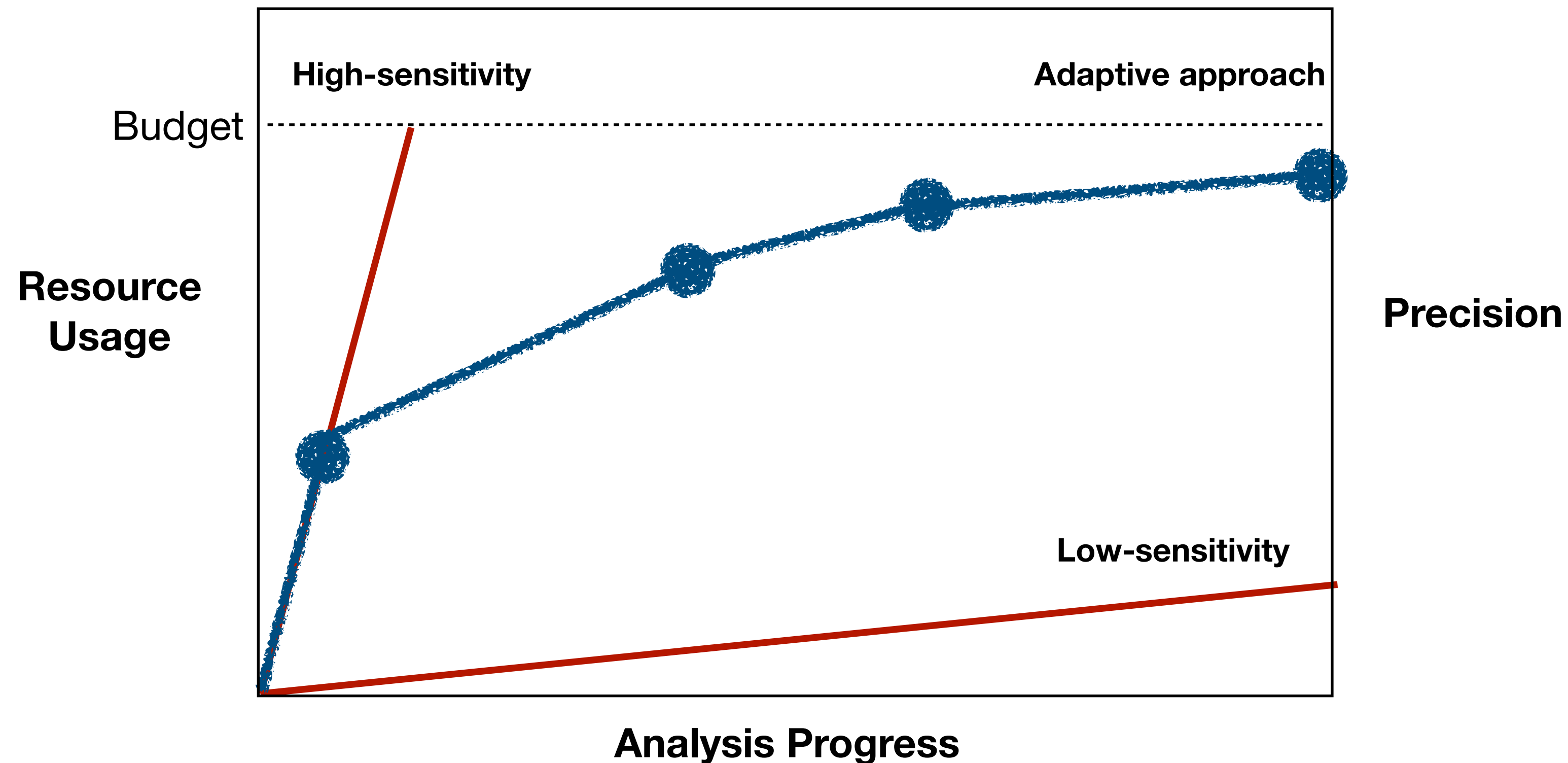
분석기 사용자의 어려움

- 분석기 동작을 예측하기가 상당히 어려움
 - 단순한 구문적 특징 (예: 소스 코드 크기) 으로는 예측하기 어려움
 - 복잡한 의미 구조가 결정하므로 분석 전문가가 아니면 이해하기 어려움

Sensitivity: 0% vim60 (227KLOC)	<	Sensitivity: 0% emacs-26.0.91 (503KLOC)	<	Sensitivity: 5% emacs-26.0.91 (503KLOC)
Memory: 51GB	>	Memory: 18GB	<<	Memory: > 128GB

자원 소모량을 스스로 고려하는 정적 분석

- 주어진 **자원 한도** 내에서 가능한 **최대 정확도**를 **자동**으로 달성하는 기술
 - 예: 128GB 메모리



요약 정도 조절 장치

- Flow-sensitivity: 구문의 순서를 요약하는 정도

Flow-sensitive

```
1: x = 0;
2: y = 1;
3: x = 1;
4: y = 0;
```

Line	State
1	{x = [0,0]}
2	{x = [0,0], y = [1,1]}
3	{x = [1,1], y = [1,1]}
4	{x = [1,1], y = [0,0]}

Partially Flow-sensitive

```
1: x = 0;
3: x = 1;
2: y = 1;
4: y = 0;
```

Line	FS	FI
1	{x = [0,0]}	
2	{x = [0,0]}	{y = [0, 1]}
3	{x = [1,1]}	
4	{x = [1,1]}	

Flow-insensitive

```
1: x = 0;
3: x = 1;
2: y = 1;
4: y = 0;
```

Line	State
*	{x = [0, 1], y = [0, 1]}

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Line	Flow-Sensitive Abstract State
1	{x = [0,0], y = [0,0], z = [1,1], v = \top , w = \top }

3 Intervals

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Line	Flow-Sensitive Abstract State
1	{x = [0,0], y = [0,0], z = [1,1], v = \top , w = \top }
2	{x = [1,1], y = [0,0], z = [1,1], v = \top , w = \top }

6 Intervals

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Line	Flow-Sensitive Abstract State
1	{x = [0,0], y = [0,0], z = [1,1], v = \top , w = \top }
2	{x = [1,1], y = [0,0], z = [1,1], v = \top , w = \top }
3	{x = [1,1], y = [0,0], z = [2,2], v = \top , w = \top }
4	{ x = [1,1], y = [1,1], z = [2,2] , v = \top , w = \top }

12 Intervals

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

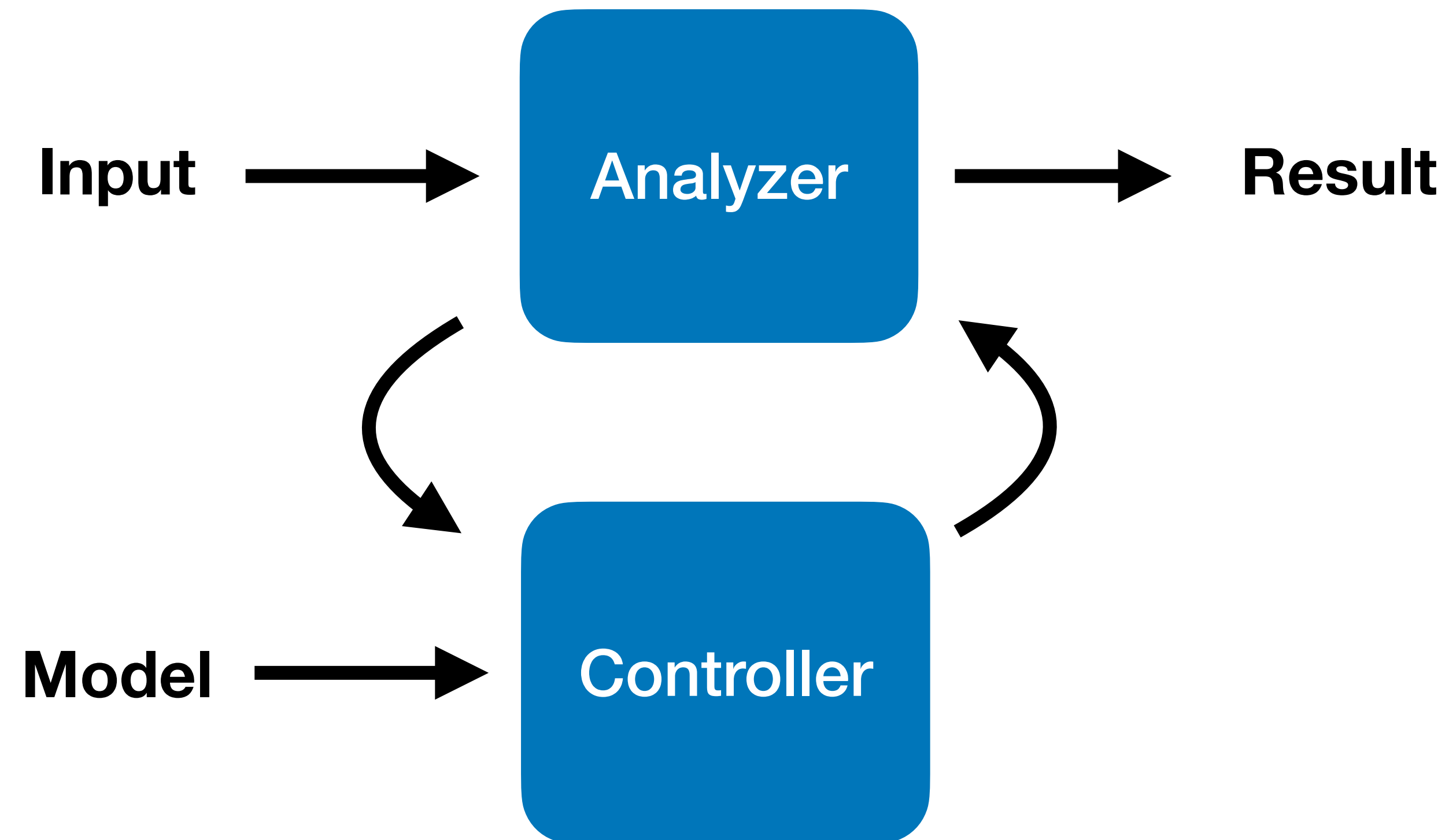
```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Line	Flow-Insensitive Abstract State
*	{ x = [0,+∞] , y = [0,+∞] , z = [1,+∞] , v = T, w = T}

3 Intervals

유연한 정적 분석

- 분석 도중에 요약 정도를 스스로 조절
 - 여러 분석 데이터를 기반으로 확률 모델과 조절 장치를 스스로 학습



변수에 관한 확률 모델

- Model $M : \text{Variable} \rightarrow [0, 1]$
- Importance of each variable in terms of flow-sensitivity
- Learned using Bayesian Optimization
 - represent variables as feature vectors and learn weights of features

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

$$M(x) > M(y) > M(z) > M(v) > M(w)$$

요약 조절 장치

- 조절 함수 $\pi : \mathbf{F} \rightarrow \text{Pr}(A)$ 이고 $A = \{0, \dots, 100\}$
- 입력: 현재 상태를 나타내는 특징 벡터
 - 예: 메모리 사용량, 분석 진행도
- 출력: 지금부터 몇 % 변수를 순서 무관하게 분석할지에 관한 확률 분포
- 강화 학습 방법을 이용하여 학습

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Model: $M(x) > M(y) > M(z) > M(v) > M(w)$

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Model: $M(x) > M(y) > M(z) > M(v) > M(w)$

Line	Flow-Sensitive Abstract State
1	{x = [0,0], y = [0,0], z = [1,1], v = T, w = T}
2	{x = [1,1], y = [0,0], z = [1,1], v = T, w = T}

6 Intervals

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Model: $M(x) > M(y) > M(z) > M(v) > \cancel{M(w)}$

Line	Flow-Sensitive	Flow-Insensitive
1	{x = [0,0], y = [0,0], z = [1,1], v = \top }	{w = \top }
2	{x = [1,1], y = [0,0], z = [1,1], v = \top }	

6 Intervals

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Model: $M(x) > M(y) > M(z) > M(v) > \cancel{M(w)}$

Line	Flow-Sensitive	Flow-Insensitive
1	{x = [0,0], y = [0,0], z = [1,1], v = \top }	
2	{x = [1,1], y = [0,0], z = [1,1], v = \top }	{w = \top }
3	{x = [1,1], y = [0,0], z = [2,2], v = \top }	

9 Intervals

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Model: $M(x) > M(y) > \cancel{M(z)} > \cancel{M(v)} > \cancel{M(w)}$

Line	Flow-Sensitive	Flow-Insensitive
1	{x = [0,0], y = [0,0]}	
2	{x = [1,+∞], y = [0,0]}	{z = [1,+∞], v = ⊤, w = ⊤}
3	{x = [1,+∞], y = [0,0]}	

6 Intervals

예제

- Partially flow-sensitive interval analysis (budget: 10 intervals)

```
1: x = 0; y = 0; z = 1; v = input(); w = input();
2: x = z;
3: z = z + 1;
4: y = x;
5: assert(y > 0); // Query 1 (hold)
6: assert(z > 0); // Query 2 (hold)
7: assert(v == w); // Query 3 (may fail)
```

Model: $M(x) > M(y) > \cancel{M(z)} > \cancel{M(v)} > \cancel{M(w)}$

Line	Flow-Sensitive	Flow-Insensitive
1	{x = [0,0], y = [0,0]}	
2	{x = [1,+∞], y = [0,0]}	{z = [1,+∞], v = T, w = T}
3	{x = [1,+∞], y = [0,0]}	
4	{x = [1,+∞], y = [1,+∞]}	

8 Intervals

요약 조절 장치 학습

- 조절 함수 $\pi : \mathbf{F} \rightarrow \text{Pr}(\mathbf{A})$ 이고 $\mathbf{A} = \{0, \dots, 100\}$
- 입력: 현재 상태를 나타내는 특징 벡터
 - 예: 메모리 사용량, 분석 진행도
- 출력: 지금부터 몇 % 변수를 순서 무관하게 분석할지에 관한 확률 분포
- Value function $Q : \mathbf{F} \times \mathbf{A} \rightarrow [0, 1]$: 각 특징 벡터와 행동에 관한 점수
- $\pi_Q(\mathbf{f})(\mathbf{a}) = \frac{Q(\mathbf{f}, \mathbf{a})}{\sum_{\mathbf{a}' \in \mathbf{A}} Q(\mathbf{f}, \mathbf{a}')}$

Value Function

$$Q : \mathbf{F} \times \mathbf{A} \rightarrow [0, 1]$$

- 특징 요약 함수 $\alpha : \text{State} \rightarrow \mathbf{F}$ 이고 $\mathbf{F} = [0, 1]^4$
 1. The inverse of memory budget
 2. Current memory consumption divided by the total budget
 3. Current lattice position divided by the lattice height
 4. Current workset size divided by the total workset size
- 보상 함수: FI 와 FS 사이에서 표준화한 상대적 알람 개수
 - 0 if #alarms = #flow-insensitive alarms
 - 1 if #alarms = #flow-sensitive alarms

학습 알고리즘

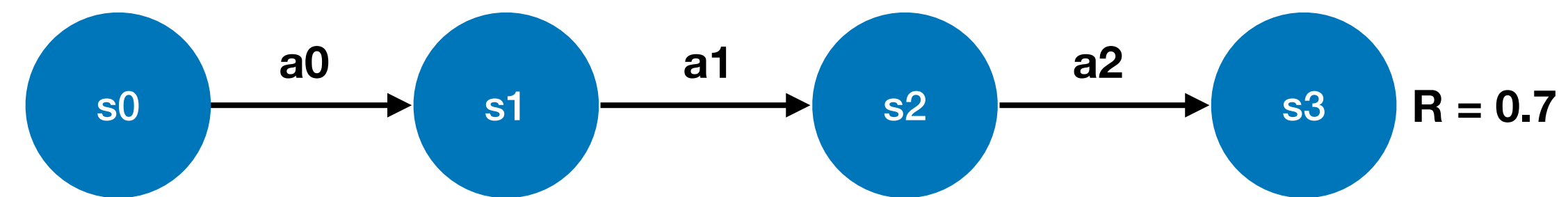
- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

1. Initialize π with a random policy

학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

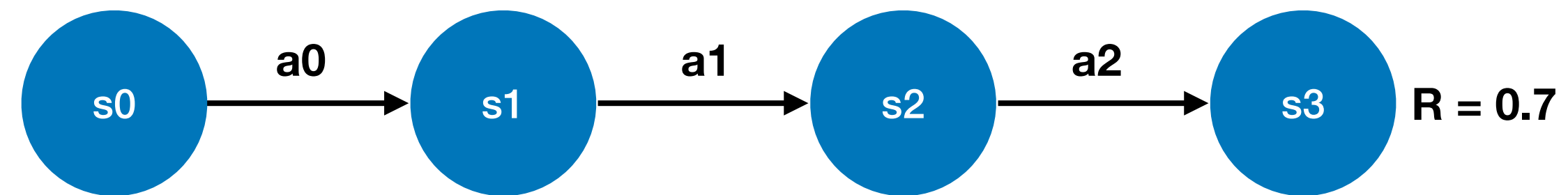
2. Run the analysis with π



학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

3. Collect all state-action pairs and the reward

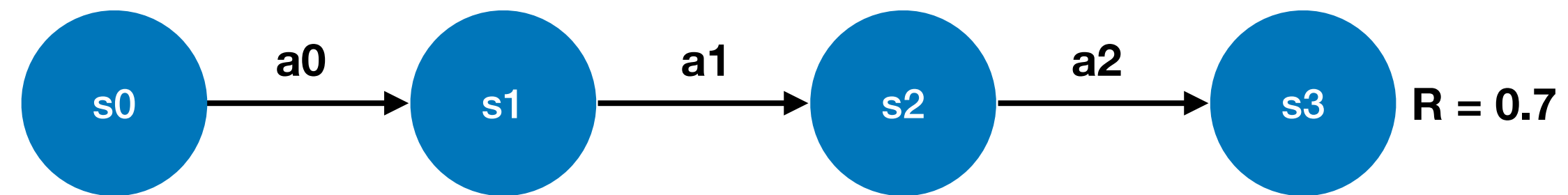


$$D_1 = \{(\langle \alpha(s_0), a_0 \rangle, 0.7), (\langle \alpha(s_1), a_1 \rangle, 0.7), (\langle \alpha(s_2), a_2 \rangle, 0.7)\}$$

학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

4. Learn Q using D_1 with a supervised learning algorithm

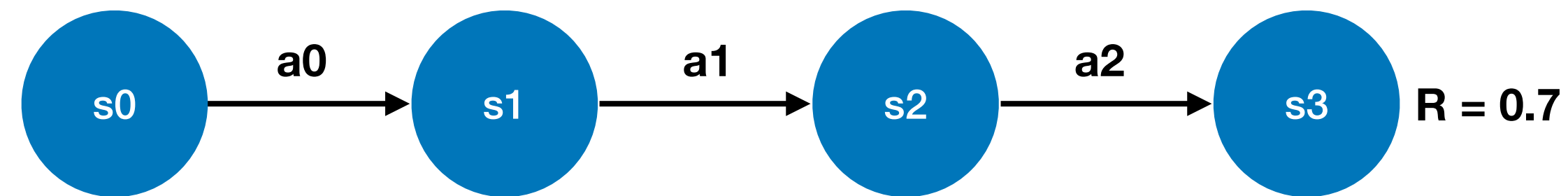


$Q = \text{SupervisedLearning}(D_1)$

학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

5. Refine π using Q

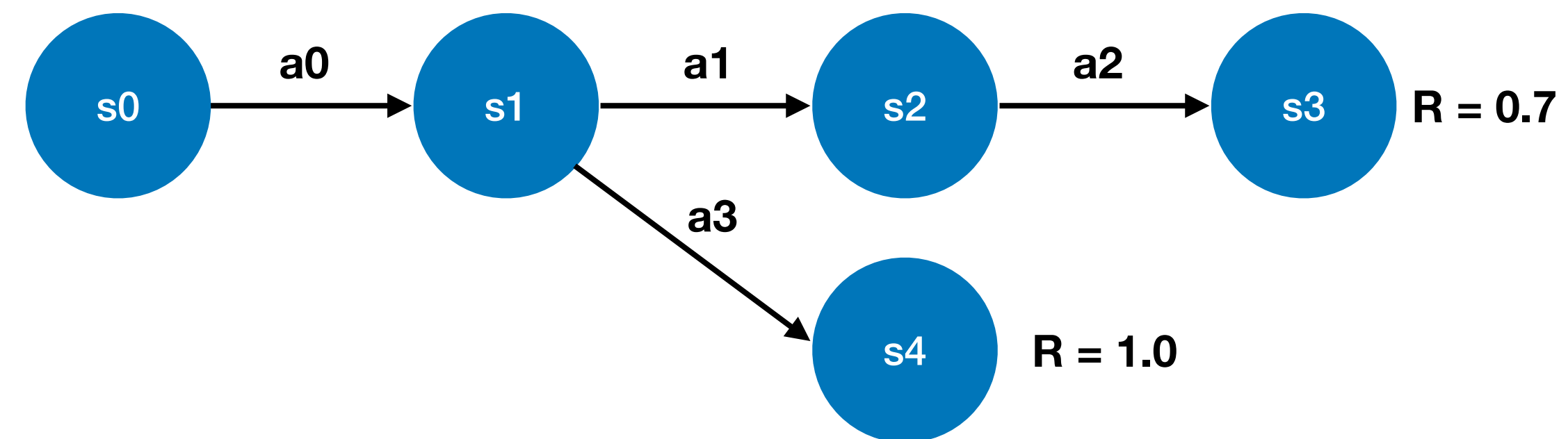


$$\pi_{Q(f)}(a) = \frac{Q(f, a)}{\sum_{a' \in A} Q(f, a')}$$

학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

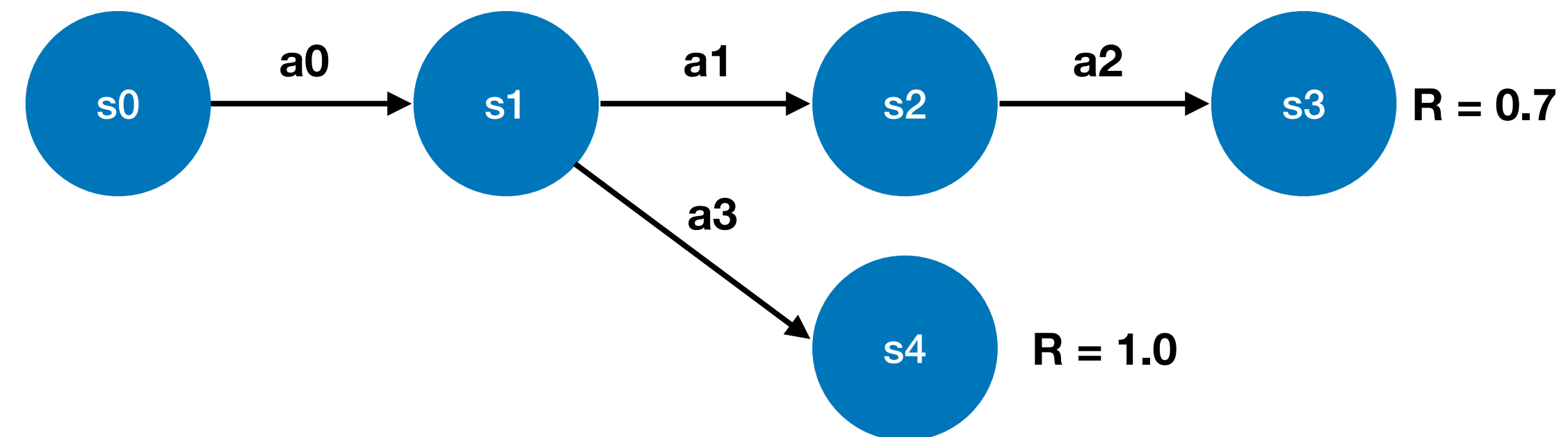
6. Run the analysis with refined π



학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

7. Accumulate data

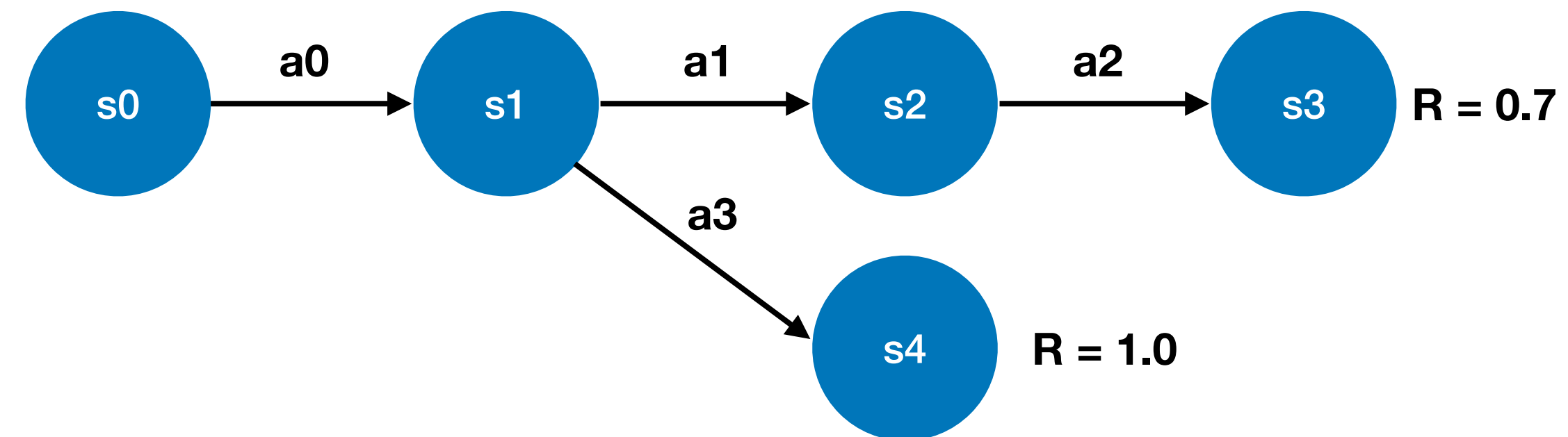


$$D_2 = D_1 \cup \{(\langle \alpha(s_0), a_0 \rangle, 1.0), (\langle \alpha(s_4), a_4 \rangle, 1.0)\}$$

학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

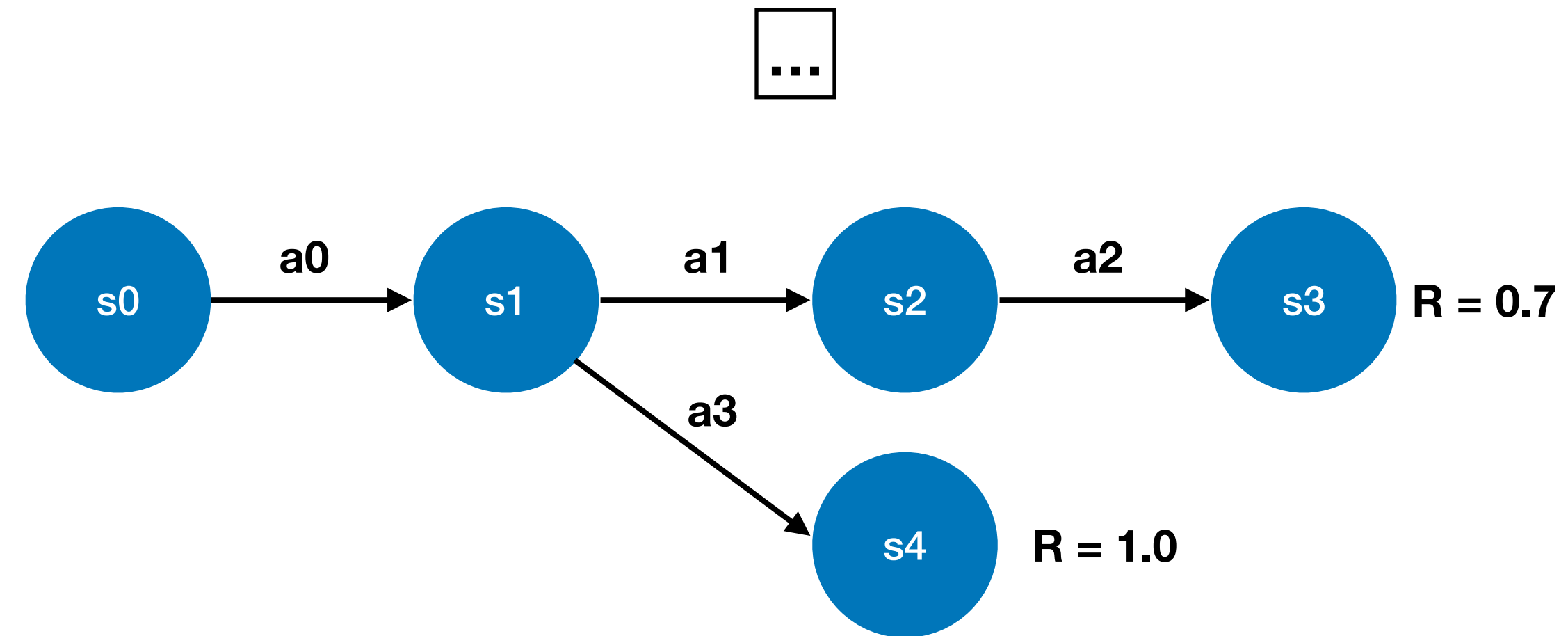
8. Refine Q using D_2 with a supervised learning algorithm



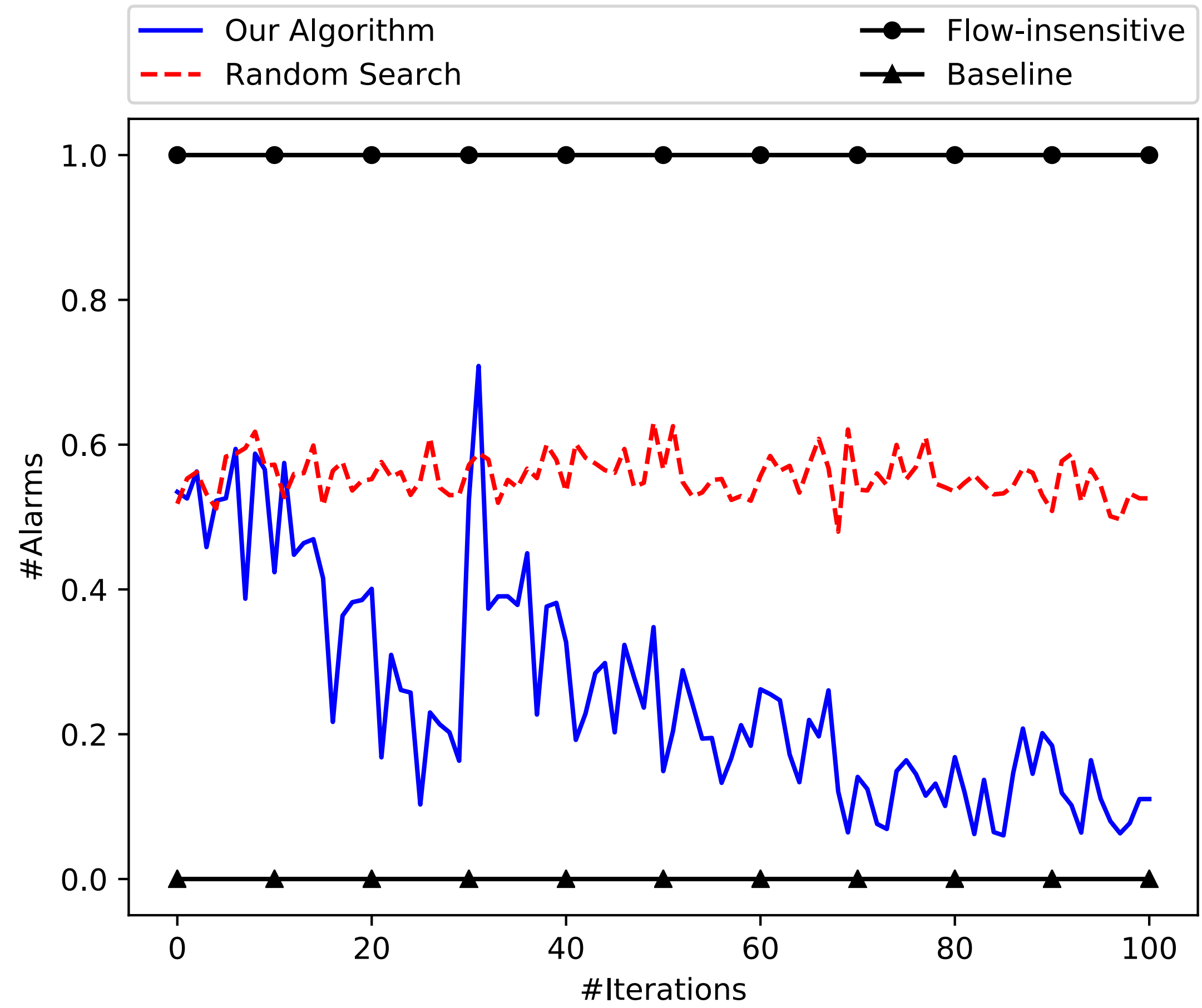
$Q = \text{SupervisedLearning}(D_2)$

학습 알고리즘

- 미리 제공된 학습 데이터와 강화 학습 알고리즘 이용

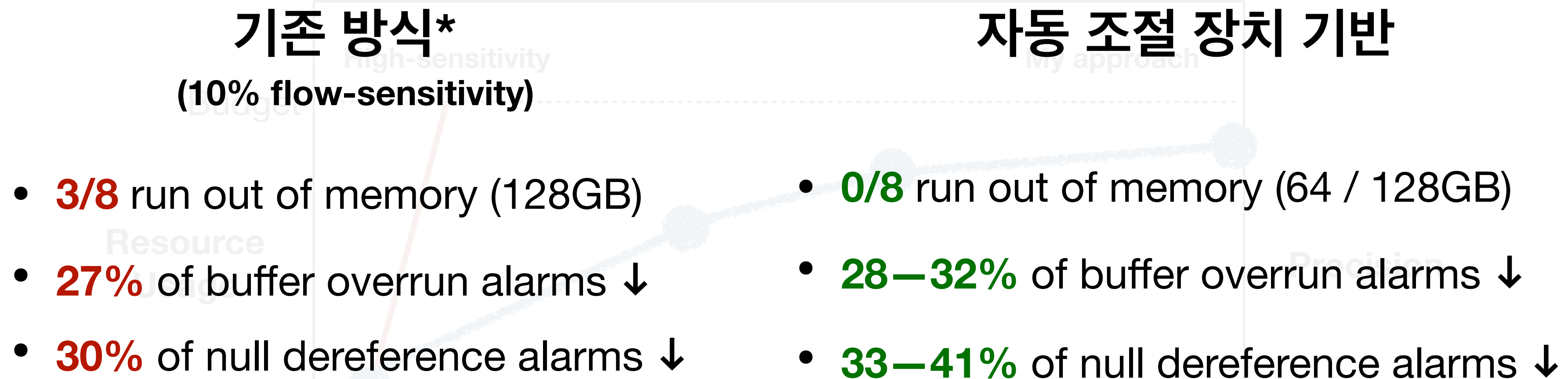


학습 진행



효과

- Achieving **maximum precision** within a given **resource budget**
 - e.g., within 128GB of memory



*Kihong Heo, Hakjoo Oh, Hongseok Yang, Kwangkeun Yi. Adapting Static Analysis via Learning with Bayesian Optimization. ACM TOPLAS, 2018

한계점

- 각 대상의 특징 (feature) 을 수동으로 정의해야 함

Target	Feature	Property	Type	Description
Loop	Null	Syntactic	Binary	Whether the loop condition contains nulls or not
	Const	Syntactic	Binary	Whether the loop condition contains constants or not
	Array	Syntactic	Binary	Whether the loop condition contains array accesses or not
	Conjunction	Syntactic	Binary	Whether the loop condition contains && or not
	IdxSingle	Syntactic	Binary	Whether the loop condition contains an index for a single array
	IdxMulti	Syntactic	Binary	Whether the loop condition contains an index for multiple arrays
	IdxOutside	Syntactic	Binary	Whether the loop condition contains an index for an array outside the loop
	InitIdx	Syntactic	Binary	Whether an index is initialized before the loop
	Exit	Syntactic	Numeric	The (normalized) number of exits in the loop
	Size	Syntactic	Numeric	The (normalized) size of the loop
	ArrayAccess	Syntactic	Numeric	The (normalized) number of array accesses in the loop
	ArithInc	Syntactic	Numeric	The (normalized) number of arithmetic increments in the loop
	PointerInc	Syntactic	Numeric	The (normalized) number of pointer increments in the loop
	Prune	Semantic	Binary	Whether the loop condition prunes the abstract state or not
	Input	Semantic	Binary	Whether the loop condition is determined by external inputs
	GVar	Semantic	Binary	Whether global variables are accessed in the loop condition
	FinInterval	Semantic	Binary	Whether a variable has a finite interval value in the loop condition
	FinArray	Semantic	Binary	Whether a variable has a finite size of array in the loop condition
	FinString	Semantic	Binary	Whether a variable has a finite string in the loop condition
	LCSize	Semantic	Binary	Whether a variable has an array of which the size is a local constant
LCOffset	Semantic	Binary	Whether a variable has an array of which the offset is a local constant	
#AbsLoc	Semantic	Numeric	The (normalized) number of abstract locations accessed	
Library	Const	Syntactic	Binary	Whether the parameters contain constants or not
	Void	Syntactic	Binary	Whether the return type is void or not
	Int	Syntactic	Binary	Whether the return type is int or not
	CString	Syntactic	Binary	Whether the function is declared in <code>string.h</code> or not
	InsideLoop	Syntactic	Binary	Whether the function is called in a loop or not
	#Args	Syntactic	Numeric	The (normalized) number of arguments
	DefParam	Semantic	Binary	Whether a parameter are defined in a loop or not
	UseRet	Semantic	Binary	Whether the return value is used in a loop or not
	UptParam	Semantic	Binary	Whether a parameter is update via the library call
	Escape	Semantic	Binary	Whether the return value escapes the caller
	GVar	Semantic	Binary	Whether a parameters points to a global variable
	Input	Semantic	Binary	Whether a parameters are determined by external inputs
	FinInterval	Semantic	Binary	Whether a parameter have a finite interval value
	#AbsLoc	Semantic	Numeric	The (normalized) number of abstract locations accessed
	#ArgString	Semantic	Numeric	The (normalized) number of string arguments

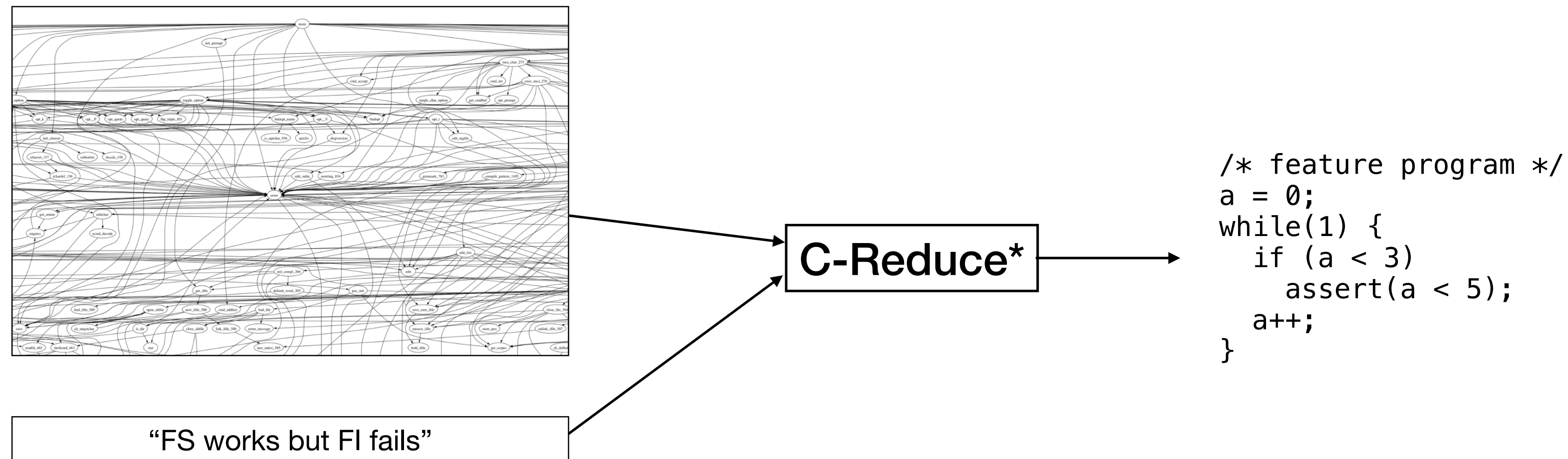
Type	#	Features
A	1	local variable
	2	global variable
	3	structure field
	4	location created by dynamic memory allocation
	5	defined at one program point
	6	location potentially generated in loop
	7	assigned a constant expression (e.g., $x = 1$)
	8	compared with a constant expression (e.g., $x < 1$)
	9	compared with another variable (e.g., $x < y$)
	10	negated in a conditional expression (e.g., $!x < y$)
	11	directly used in malloc (e.g., $y = \text{malloc}(x)$)
	12	indirectly used in malloc (e.g., $y = \text{malloc}(x)$)
	13	directly used in realloc (e.g., $y = \text{realloc}(x, n)$)
	14	indirectly used in realloc (e.g., $y = \text{realloc}(x, n)$)
	15	directly returned from malloc (e.g., $y = \text{malloc}(x)$)
	16	indirectly returned from malloc (e.g., $y = \text{malloc}(x)$)
	17	directly returned from realloc (e.g., $y = \text{realloc}(x, n)$)
	18	indirectly returned from realloc (e.g., $y = \text{realloc}(x, n)$)
	19	incremented by one (e.g., $x = x + 1$)
	20	incremented by a constant expr. (e.g., $x = x + 1$)
	21	incremented by a variable (e.g., $x = x + x$)
	22	decremented by one (e.g., $x = x - 1$)
	23	decremented by a constant expr. (e.g., $x = x - 1$)
	24	decremented by a variable (e.g., $x = x - x$)
	25	multiplied by a constant (e.g., $x = x * 2$)
	26	multiplied by a variable (e.g., $x = x * x$)
	27	incremented pointer (e.g., $p++$)
	28	used as an array index (e.g., $a[x]$)
	29	used in an array expr. (e.g., $x[e]$)
	30	returned from an unknown library function
	31	modified inside a recursive function
	32	modified inside a local loop
	33	read inside a local loop
B	34	$1 \wedge 8 \wedge (11 \vee 12)$
	35	$2 \wedge 8 \wedge (11 \vee 12)$
	36	$1 \wedge (11 \vee 12) \wedge (19 \vee 20)$
	37	$2 \wedge (11 \vee 12) \wedge (19 \vee 20)$
	38	$1 \wedge (11 \vee 12) \wedge (15 \vee 16)$
	39	$2 \wedge (11 \vee 12) \wedge (15 \vee 16)$
	40	$(11 \vee 12) \wedge 29$
	41	$(15 \vee 16) \wedge 29$
	42	$1 \wedge (19 \vee 20) \wedge 33$
	43	$2 \wedge (19 \vee 20) \wedge 33$
	44	$1 \wedge (19 \vee 20) \wedge \neg 33$
	45	$2 \wedge (19 \vee 20) \wedge \neg 33$

i	Description of feature $f_i(P, (x, y))$. k represents a constant.
1	P contains an assignment $x = y + k$ or $y = x + k$.
2	P contains a guard $x \leq y + k$ or $y \leq x + k$.
3	P contains a malloc of the form $x = \text{malloc}(y)$ or $y = \text{malloc}(x)$.
4	P contains a command $x = \text{strlen}(y)$ or $y = \text{strlen}(x)$.
5	P sets x to $\text{strlen}(y)$ or y to $\text{strlen}(x)$ indirectly, as in $t = \text{strlen}(y); x = t$.
6	P contains an expression of the form $x[y]$ or $y[x]$.
7	P contains an expression that multiplies x or y by a constant different from 1.
8	P contains an expression that multiplies x or y by a variable.
9	P contains an expression that divides x or y by a variable.
10	P contains an expression that has x or y as an operand of bitwise operations.
11	P contains an assignment that updates x or y using non-Octagonal expressions.
12	x and y have the same name in different scopes.
13	x and y are both global variables in P .
14	x or y is a global variable in P .
15	x or y is a field of a structure in P .
16	x and y represent sizes of some arrays in P .
17	x and y are temporary variables in P .
18	x or y is a local variable of a recursive function in P .
19	x or y is tested for the equality with ± 1 in P .
20	x and y represent sizes of some global arrays in P .
21	x or y stores the result of a library call in P .
22	x and y are local variables of different functions in P .
23	$\{x, y\}$ consists of a local variable and the size of a local array in different functions in P .
24	$\{x, y\}$ consists of a local variable and a temporary variable in different functions in P .
25	$\{x, y\}$ consists of a global variable and the size of a local array in P .
26	$\{x, y\}$ consists of a temporary variable and the size of a local array in P .
27	$\{x, y\}$ consists of local and global variables not accessed by the same function in P .
28	x or y is a self-updating global variable in P .
29	x or y has a finite interval value.
30	x or y is the size of a constant string in P .

Type	#	Features
A	1	leaf function
	2	function containing malloc
	3	function containing realloc
	4	function containing a loop
	5	function containing an if statement
	6	function containing a switch statement
	7	function using a string-related library function
	8	write to a global variable
	9	read a global variable
	10	write to a structure field
	11	read from a structure field
	12	directly return a constant expression
	13	indirectly return a constant expression
	14	directly return an allocated memory
	15	indirectly return an allocated memory
	16	directly return a reallocated memory
	17	indirectly return a reallocated memory
	18	return expression involves field access
	19	return value depends on a structure field
	20	return void
	21	directly invoked with a constant
	22	constant is passed to an argument
	23	invoked with an unknown value
	24	functions having no arguments
	25	functions having one argument
	26	functions having more than one argument
	27	functions having an integer argument
	28	functions having a pointer argument
	29	functions having a structure as an argument
B	30	$2 \wedge (21 \vee 22) \wedge (14 \vee 15)$
	31	$2 \wedge (21 \vee 22) \wedge \neg(14 \vee 15)$
	32	$2 \wedge 23 \wedge (14 \vee 15)$
	33	$2 \wedge 23 \wedge \neg(14 \vee 15)$
	34	$2 \wedge (21 \vee 22) \wedge (16 \vee 17)$
	35	$2 \wedge (21 \vee 22) \wedge \neg(16 \vee 17)$
	36	$2 \wedge 23 \wedge (16 \vee 17)$
	37	$2 \wedge 23 \wedge \neg(16 \vee 17)$
	38	$(21 \vee 22) \wedge \neg 23$

특징 자동 생성

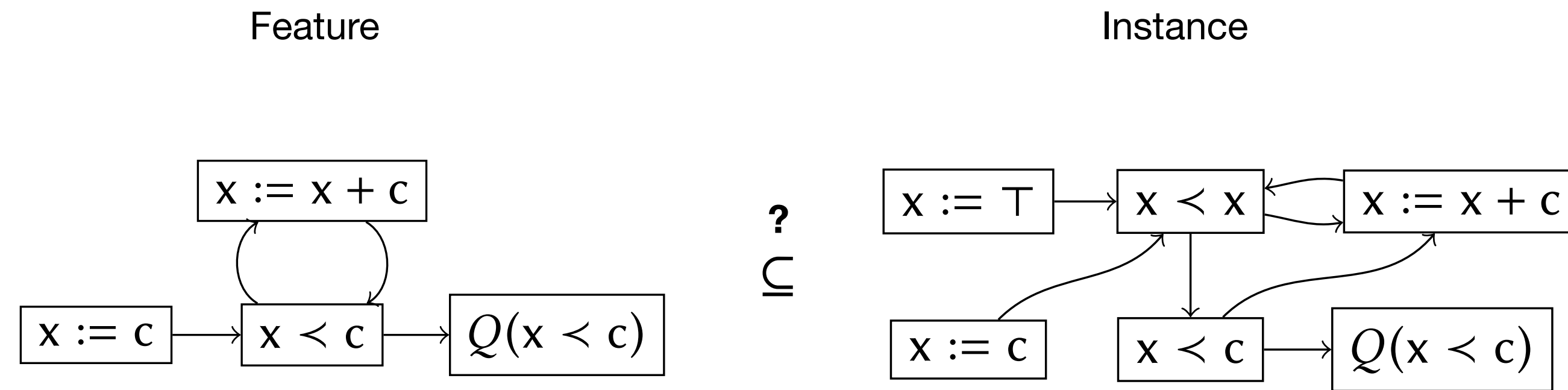
- 핵심 아이디어: 특징을 나타내는 프로그램
 - 왜 특정 분석 기술 (flow-sensitivity, relational analysis, etc) 이 먹히는가?
- 특징 프로그램 생성: 이미 존재하는 프로그램 축약기 이용



*<https://embed.cs.utah.edu/creduce>

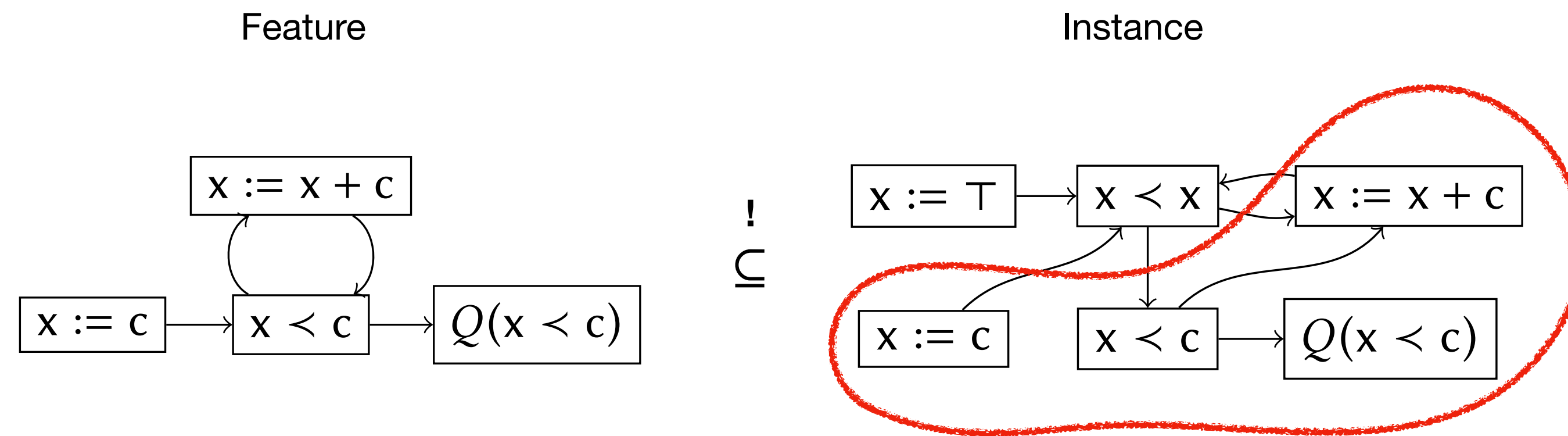
특징 추출

- 특징 프로그램과 대상 프로그램을 그래프로 표현하여 포함관계를 계산
 - 그래프: 요약된 데이터 흐름을 표현



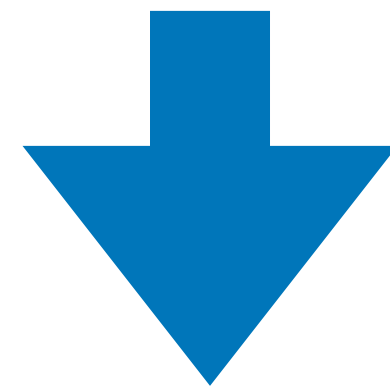
특징 추출

- 특징 프로그램과 대상 프로그램을 그래프로 표현하여 포함관계를 계산
 - 그래프: 요약된 데이터 흐름을 표현

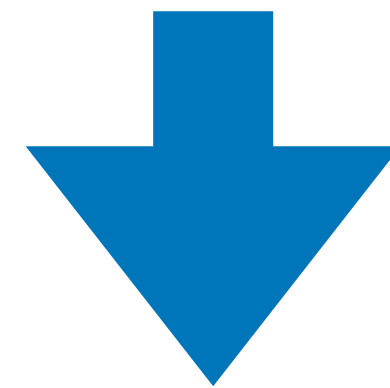
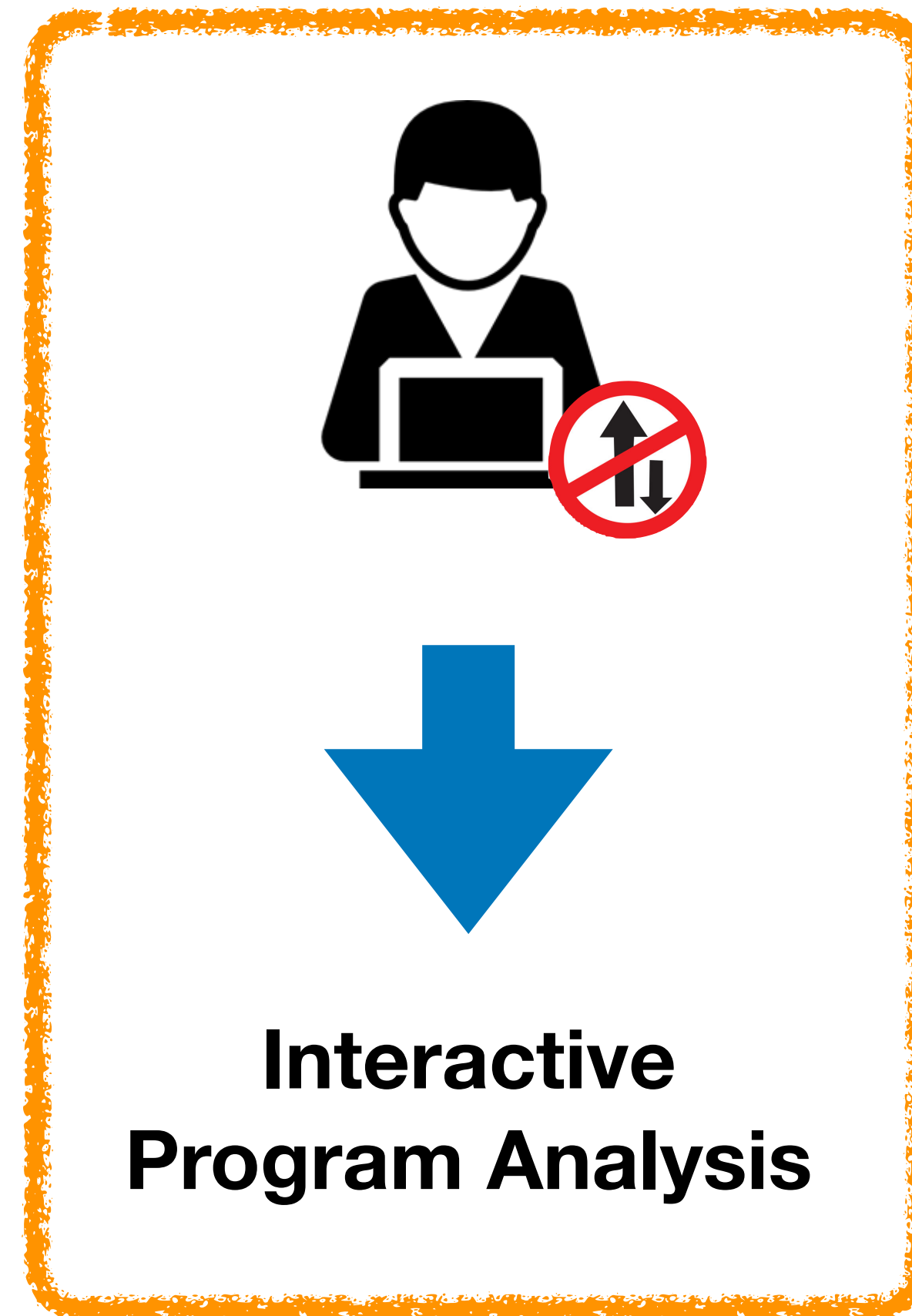


$$Node_F \subseteq Node_I \wedge Edge_F \subseteq Edge_I^*$$

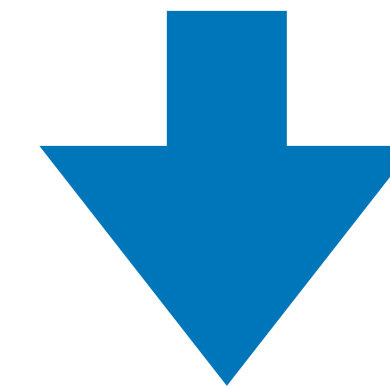
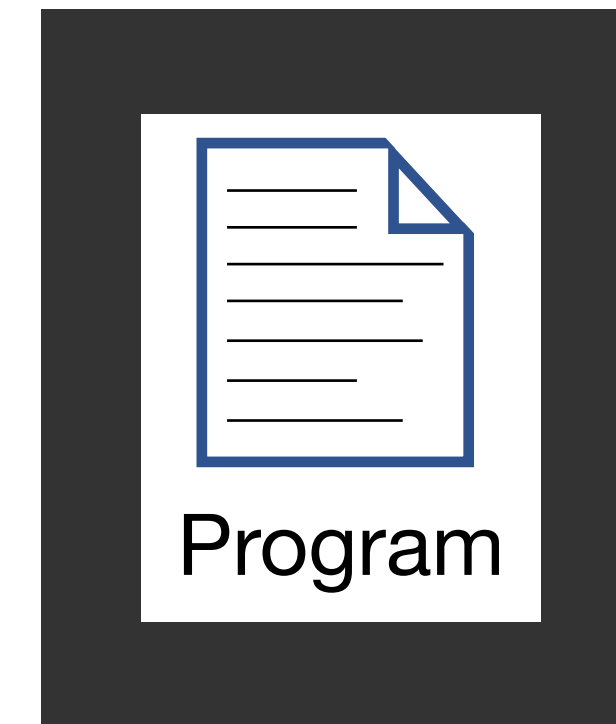
Outline



**Adaptive
Program Analysis**



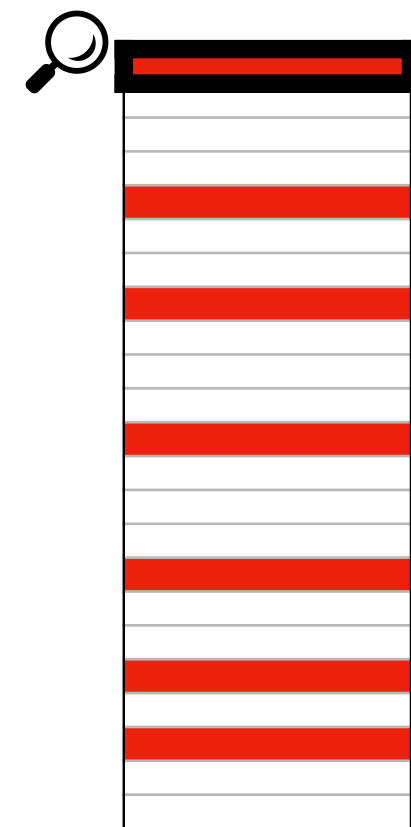
**Interactive
Program Analysis**



**Continuous
Program Analysis**

Outline

Bingo: Interactive Alarm Ranking System [PLDI'18]



Old Alarm Ranking

+

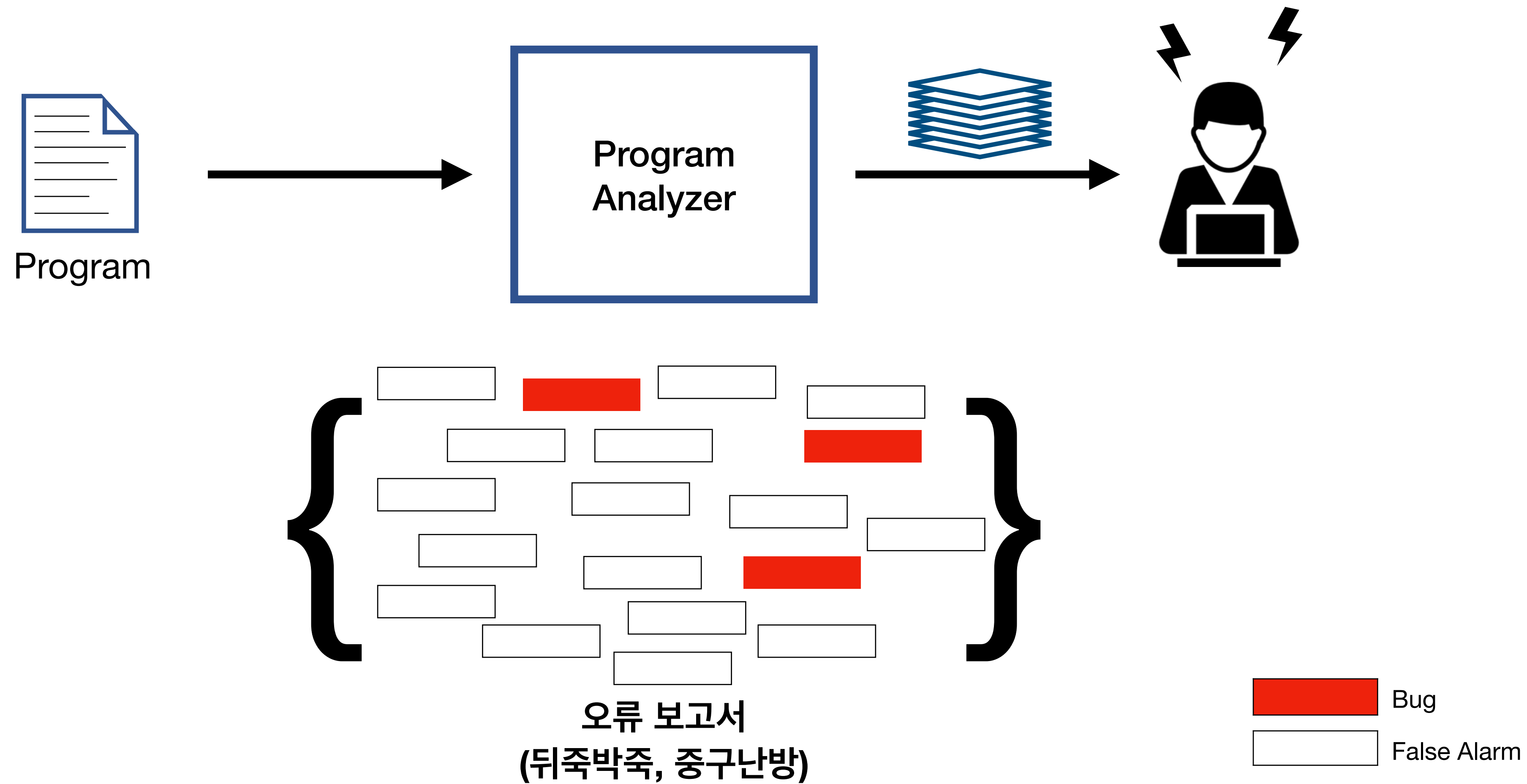


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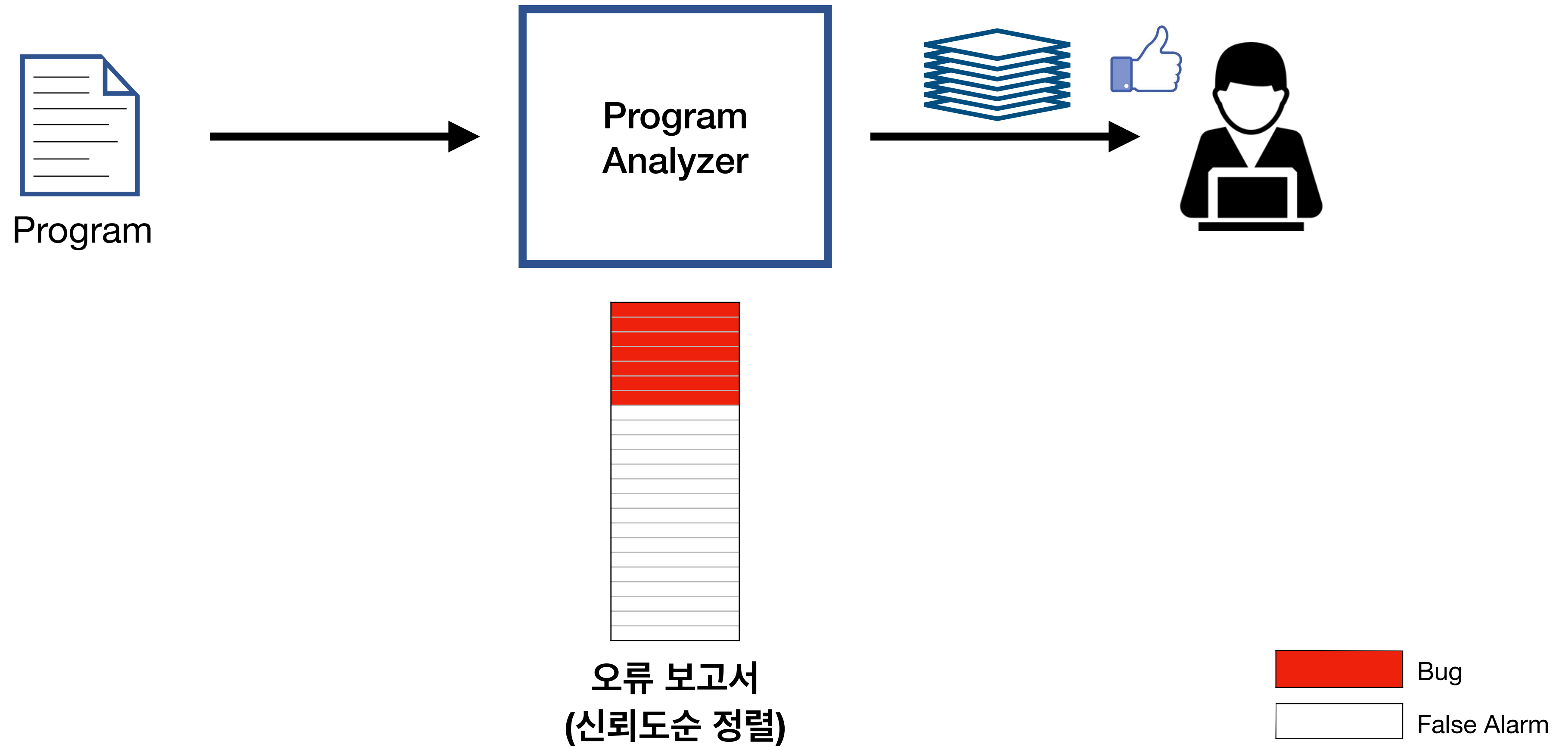


New Alarm Ranking

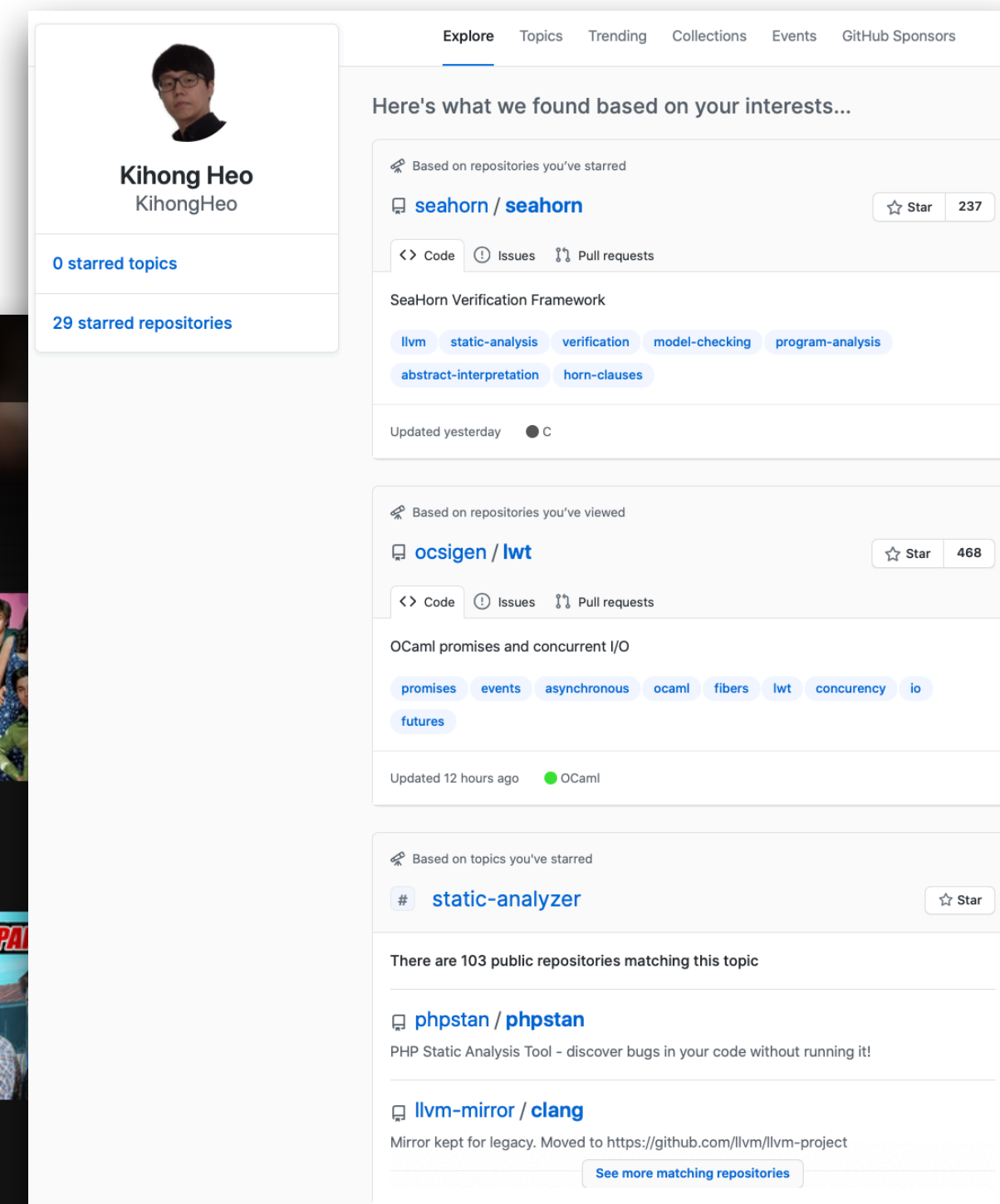
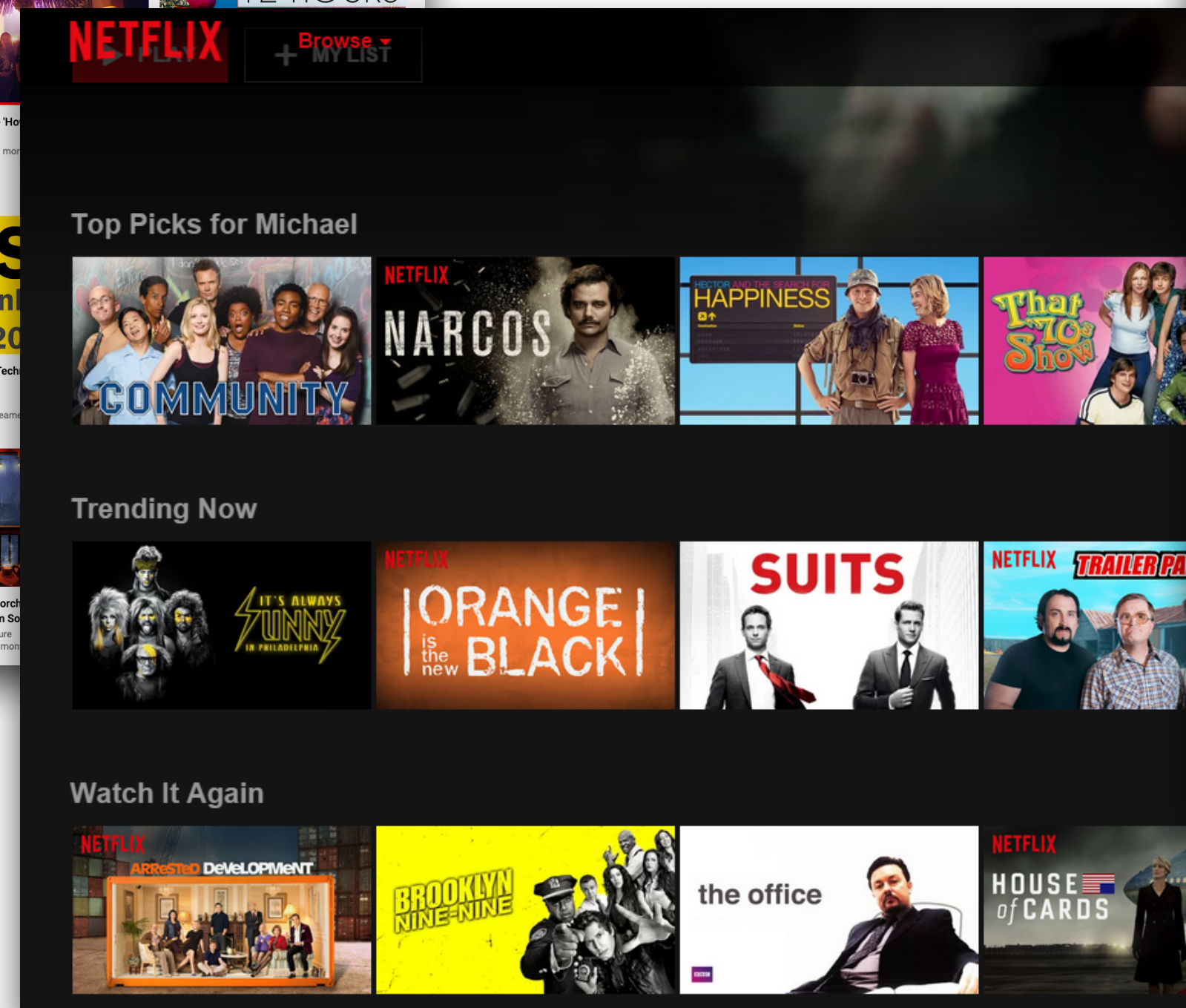
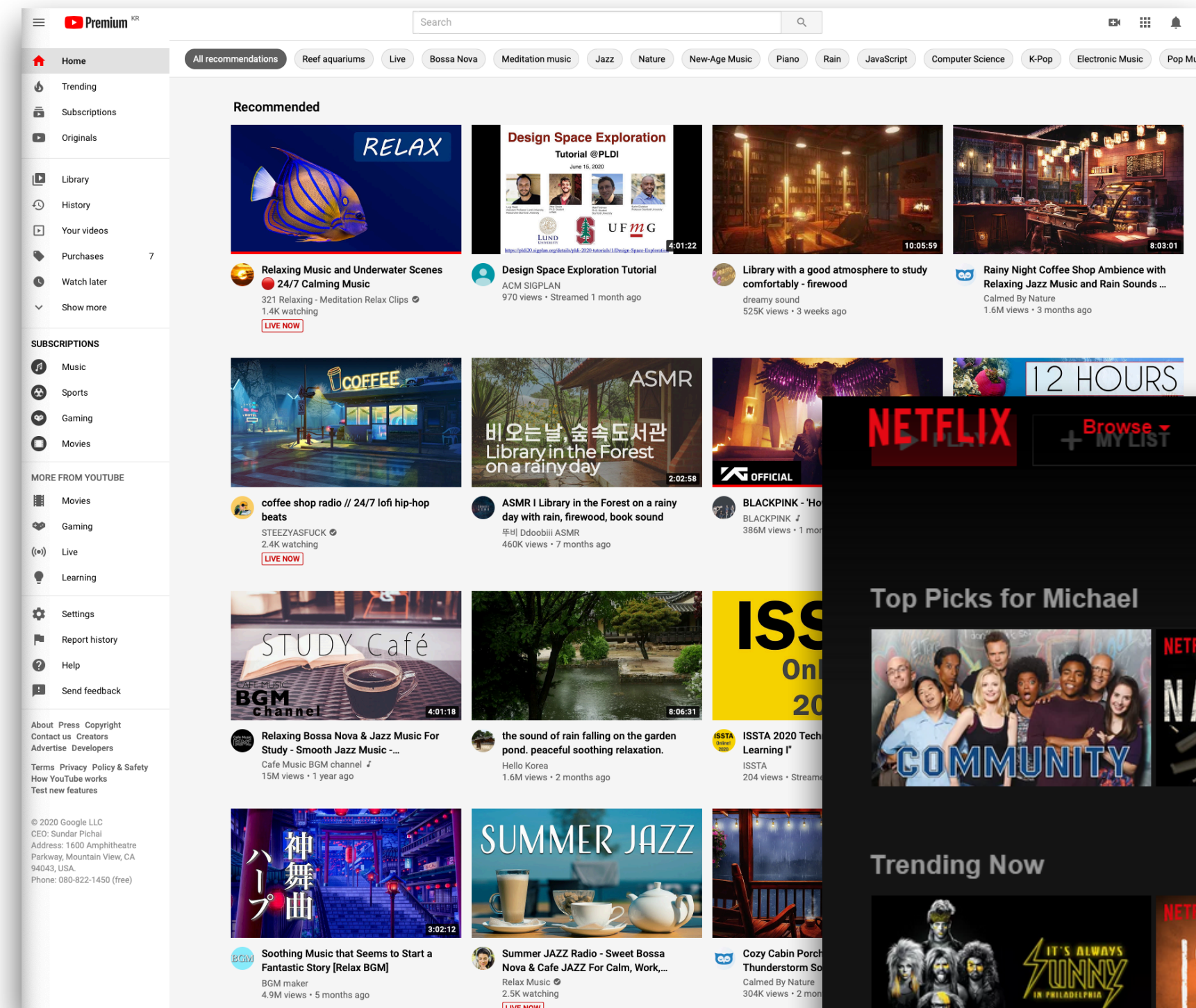
문제점



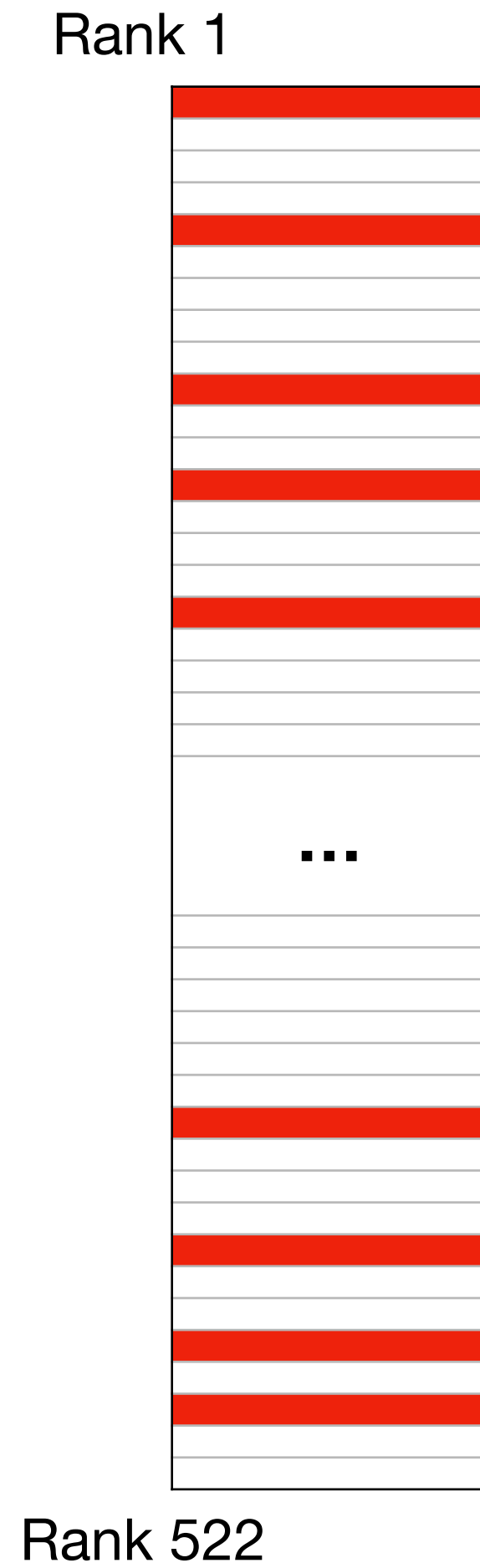
목표



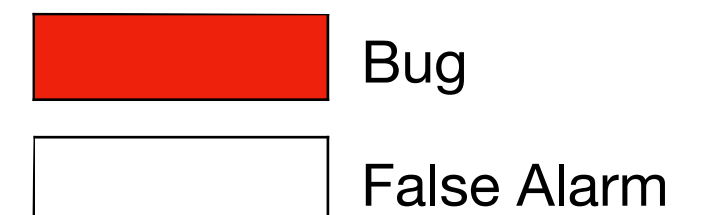
상호작용 시스템 (다른 분야)



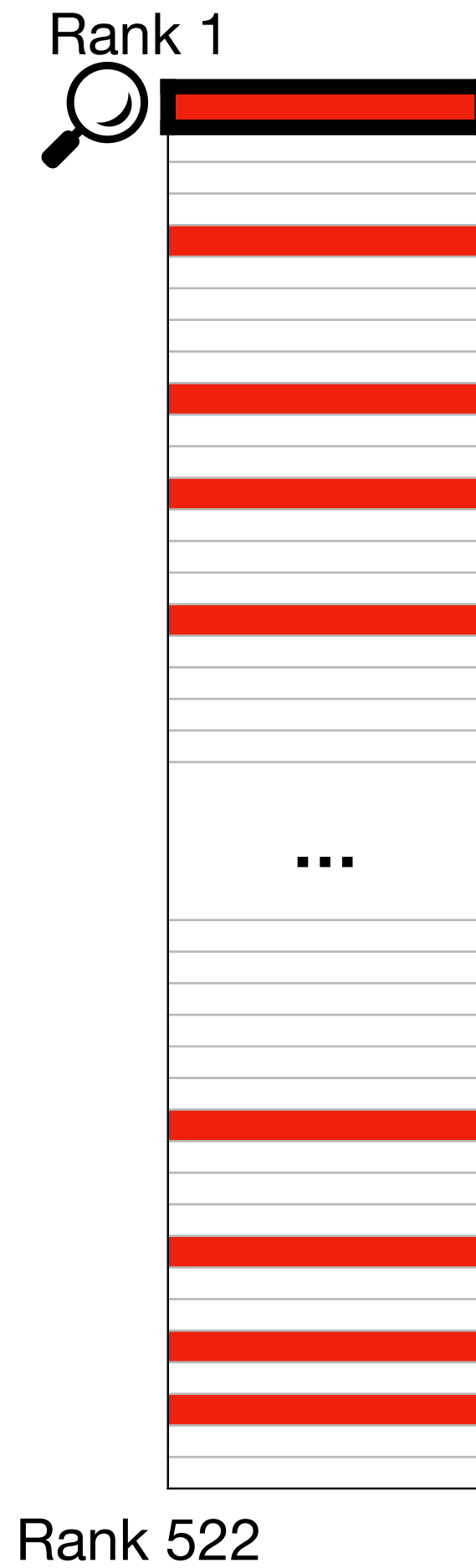
반응형 오류 보고



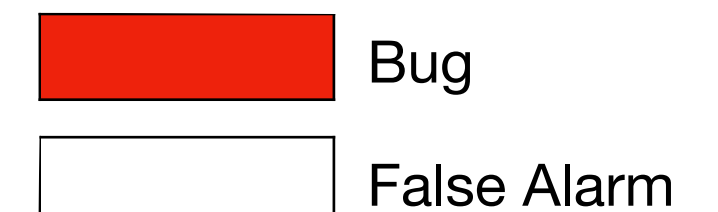
152KLOC
75 Datarace Bugs
522 Total Alarms



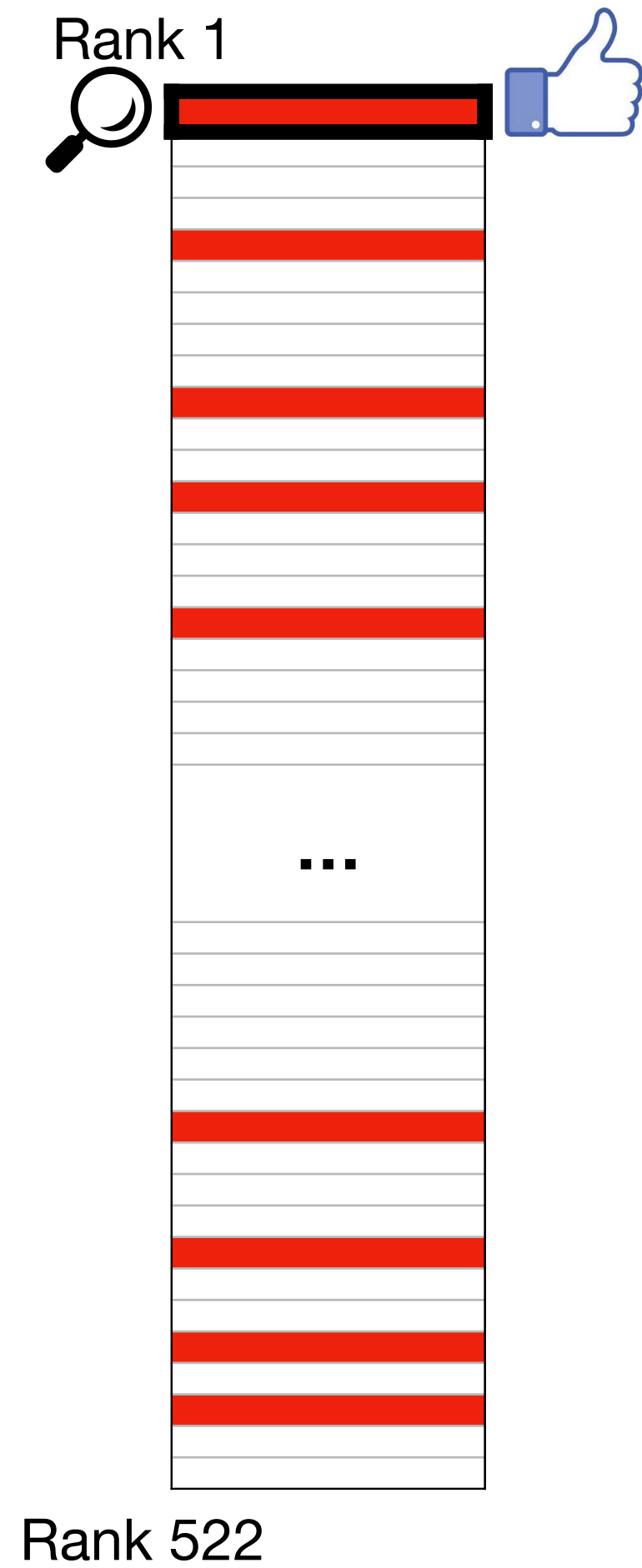
반응형 오류 보고



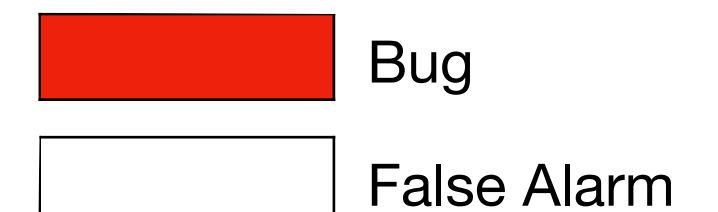
152KLOC
75 Datarace Bugs
522 Total Alarms



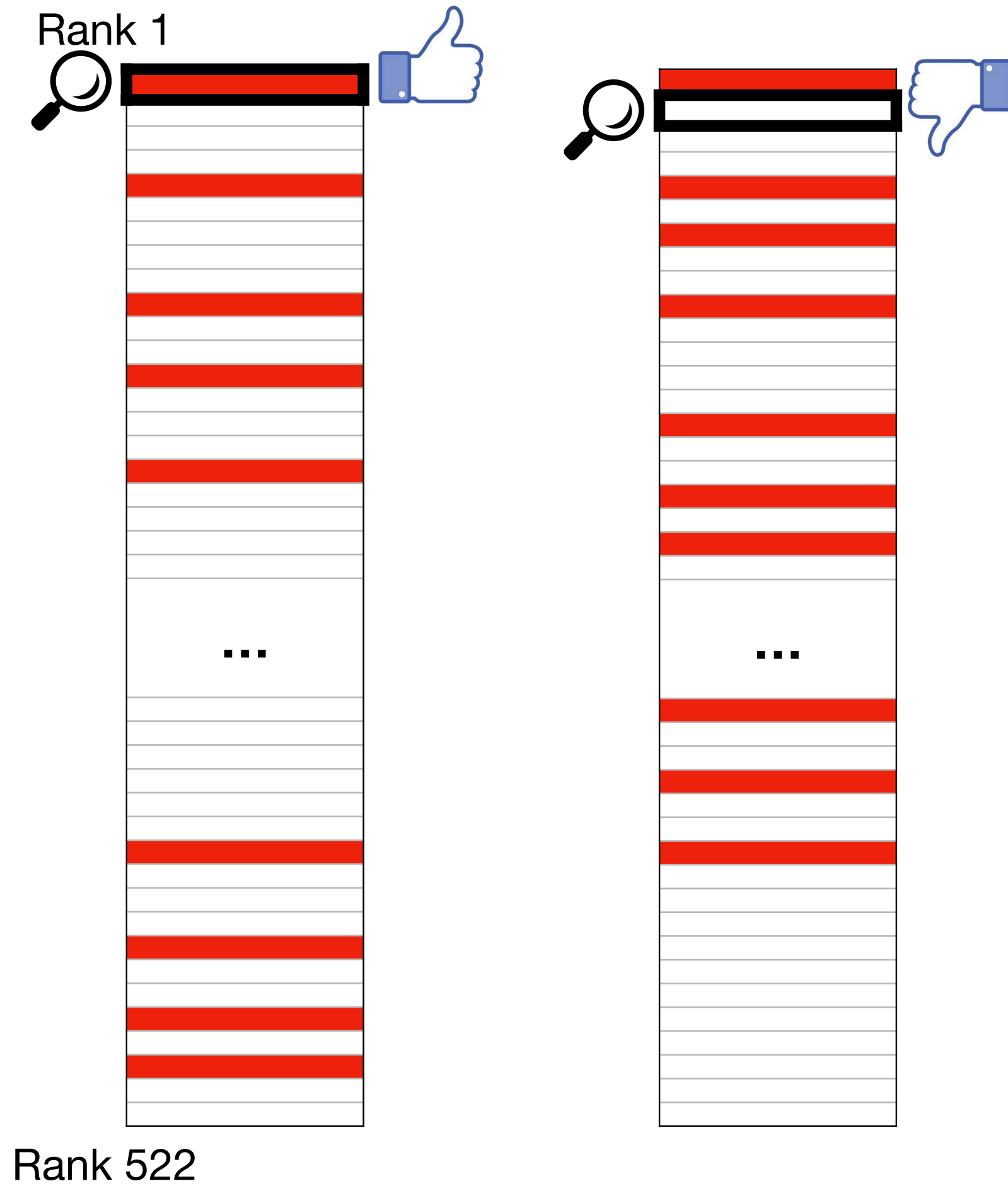
반응형 오류 보고





152KLOC
75 Datarace Bugs
522 Total Alarms



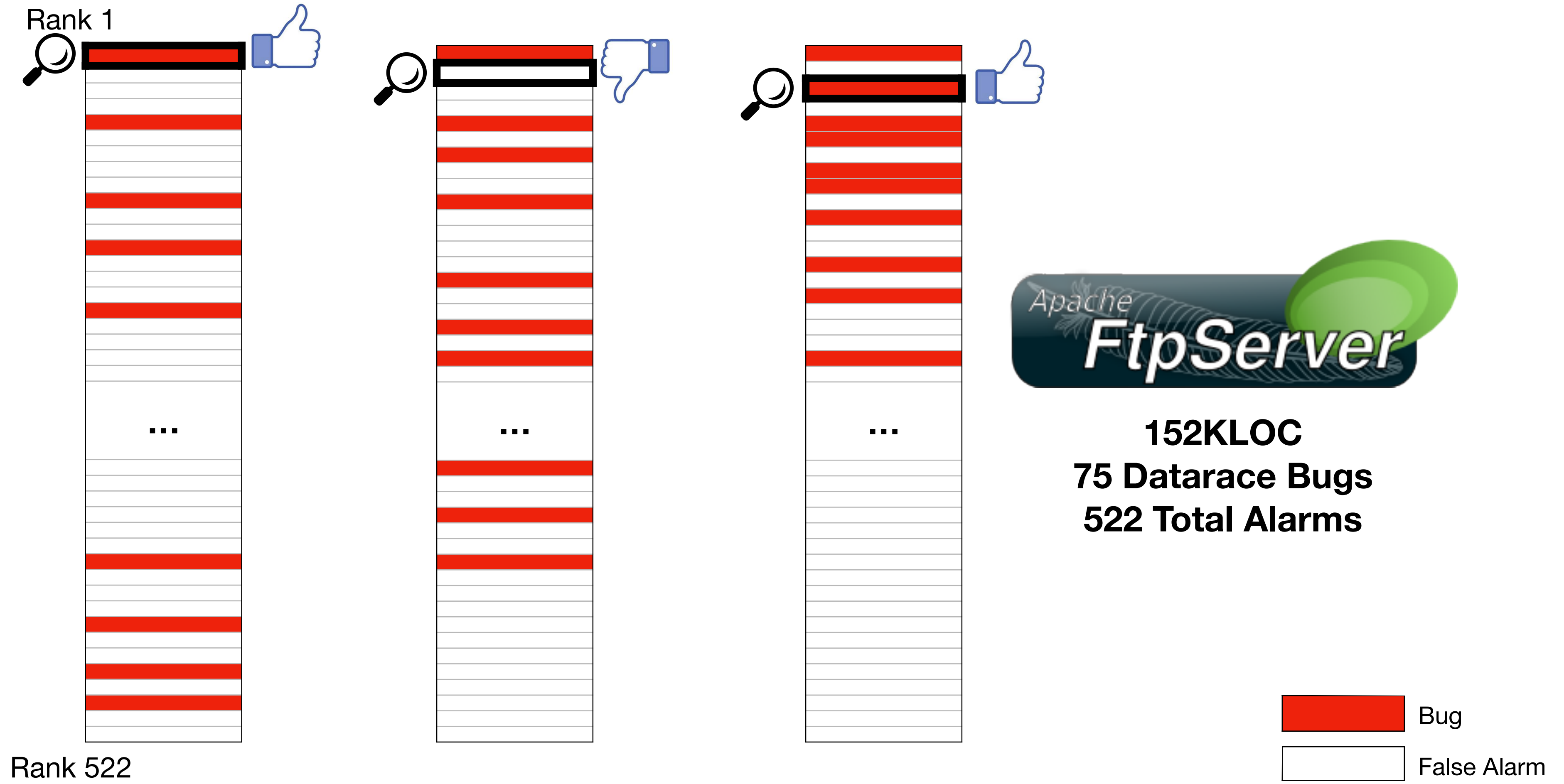
반응형 오류 보고



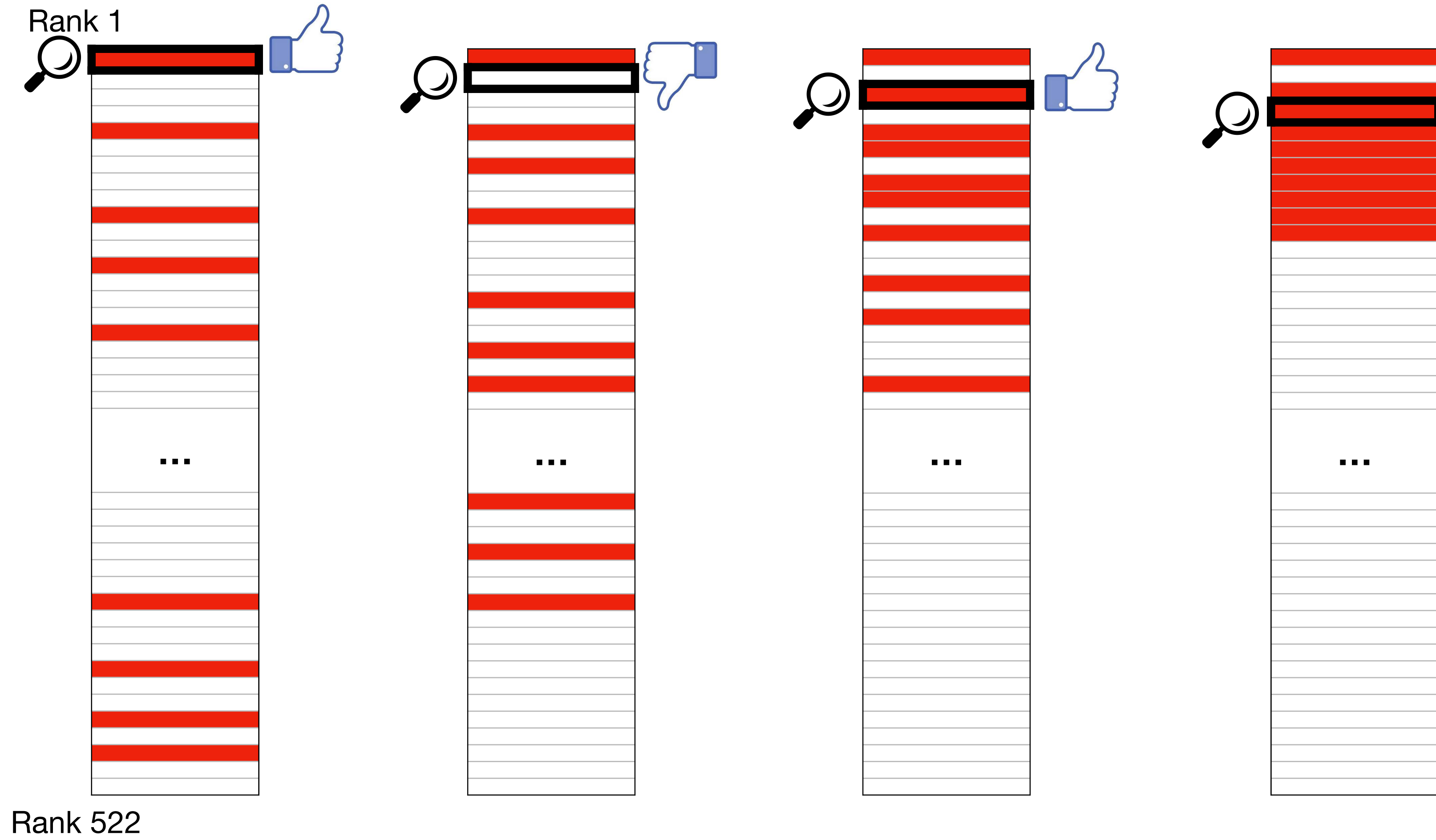
152KLOC
75 Datarace Bugs
522 Total Alarms

 Bug
 False Alarm

반응형 오류 보고



반응형 오류 보고

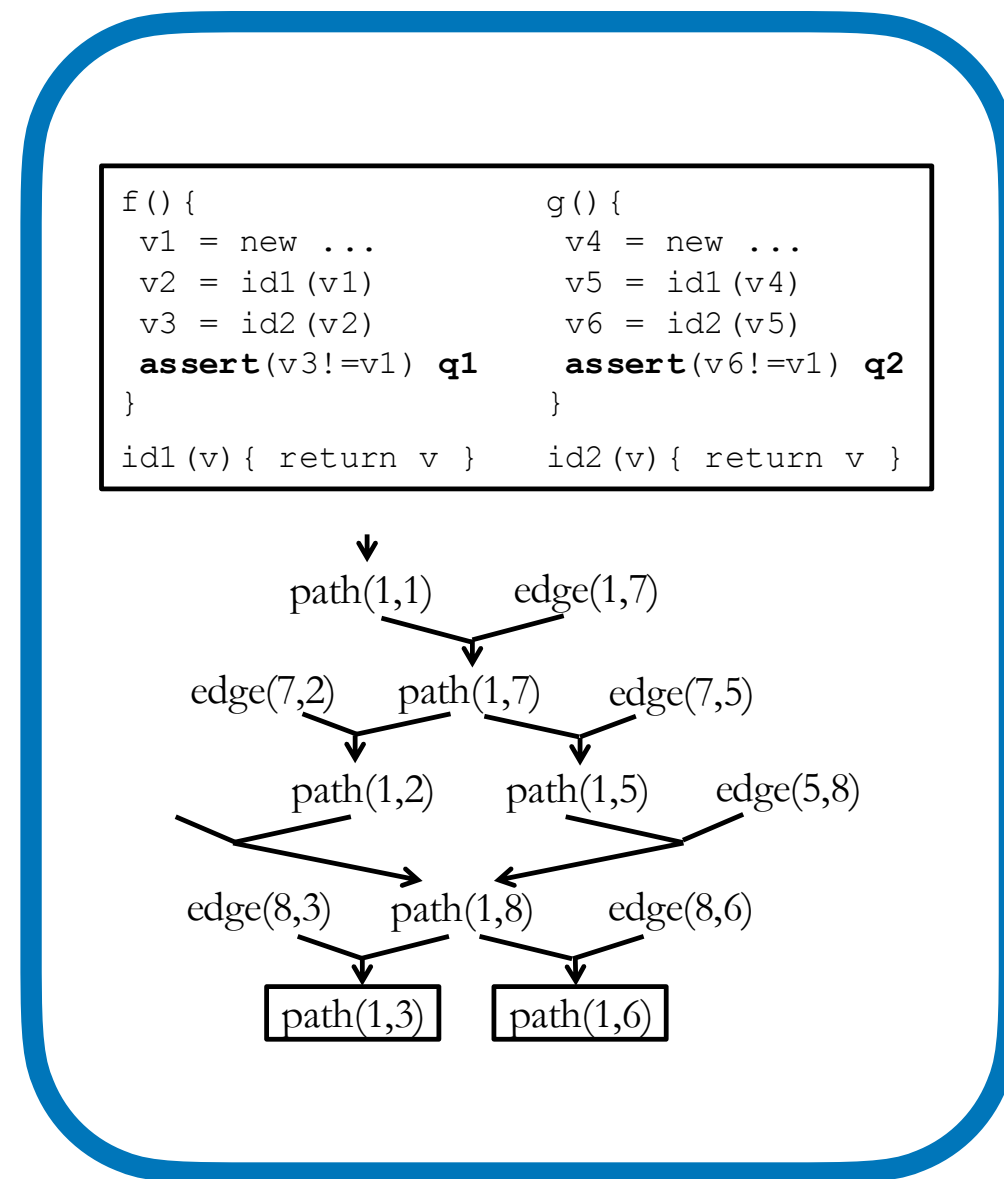


반응형 오류 보고

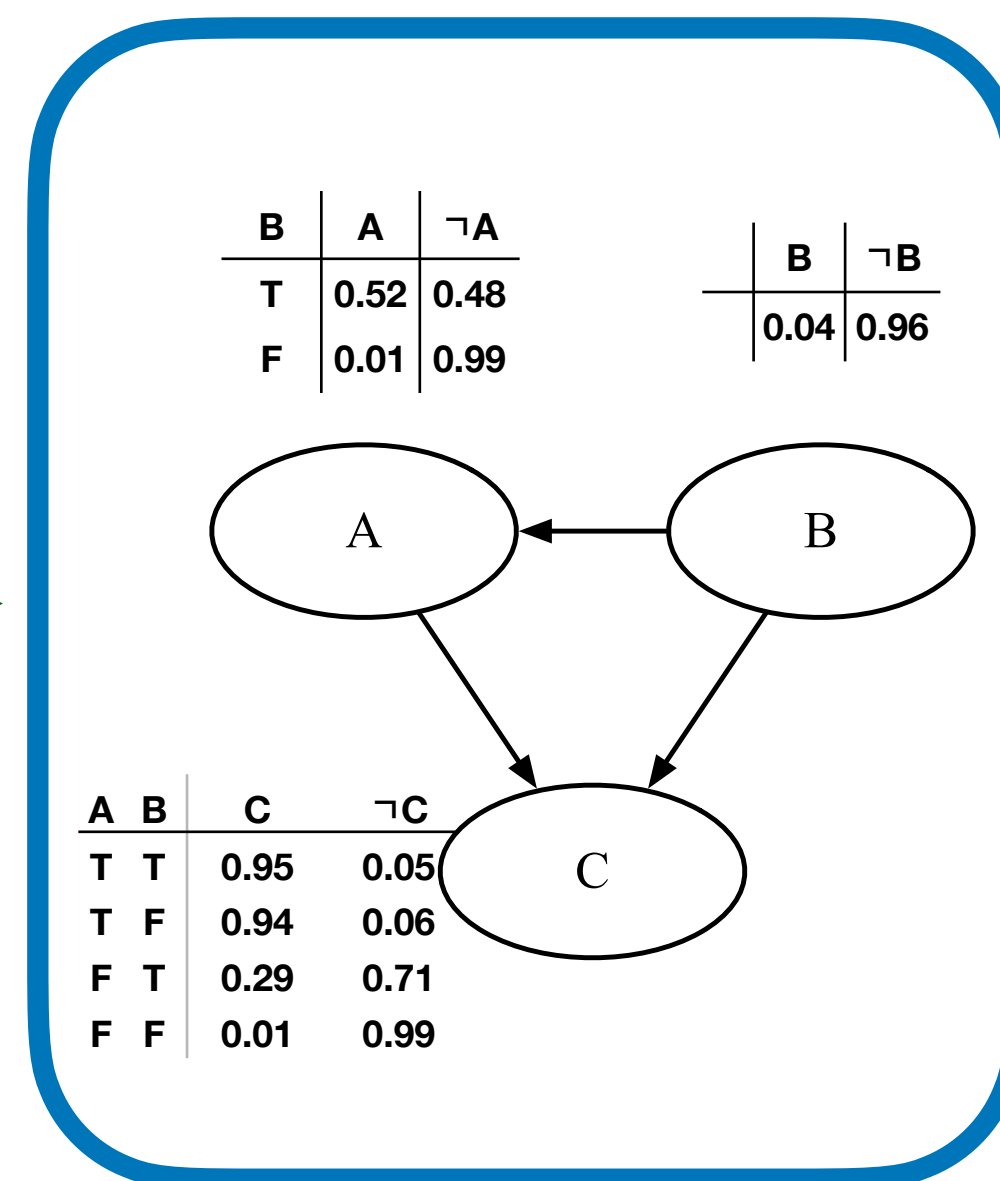


핵심 기술

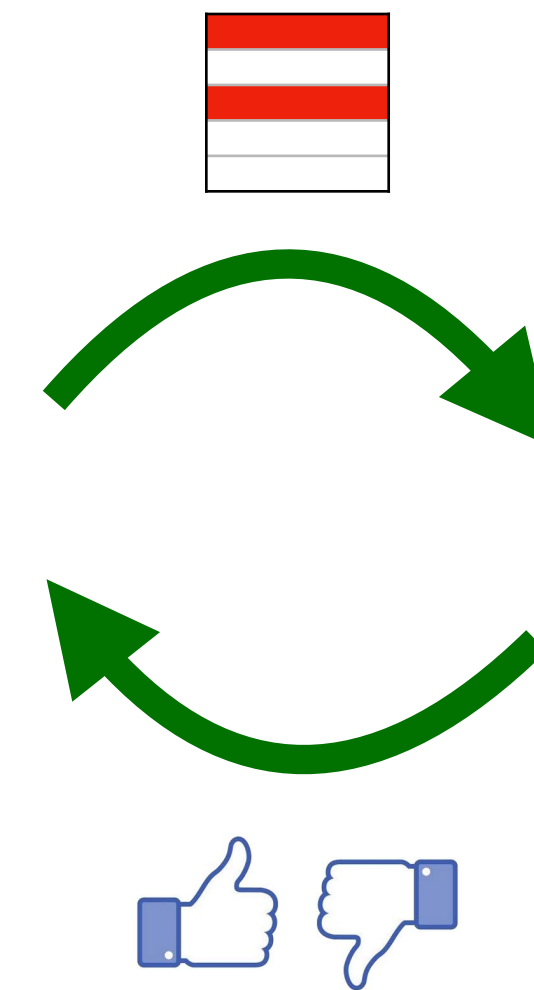
인간-분석 상호 작용 + 베이저안 추론 (Bayesian inference)



분석 결과



확률 모델
(e.g., Bayesian Network)



사용자

분석 예제: Datarace

Analysis Inputs:

$\text{Next}(p_1, p_2)$, $\text{Alias}(p_1, p_2)$, $\text{Unguarded}(p_1, p_2)$.

Analysis Outputs:

$\text{Parallel}(p_1, p_2)$, $\text{Race}(p_1, p_2)$

Analysis Rules:

r₁: $\text{Parallel}(p_1, p_3) :- \text{Parallel}(p_1, p_2), \text{Next}(p_2, p_3), \text{Unguarded}(p_1, p_3)$.

r₂: $\text{Parallel}(p_1, p_2) :- \text{Parallel}(p_2, p_1)$.

r₃: $\text{Race}(p_1, p_2) :- \text{Parallel}(p_1, p_2), \text{Alias}(p_1, p_2)$.

분석 예제: Datarace

p_i is a program point

Analysis Inputs:

$\text{Next}(p_1, p_2)$, $\text{Alias}(p_1, p_2)$, $\text{Unguarded}(p_1, p_2)$.

Program point p_2 is
an immediate successor of p_1

p_1 and p_2 may access
the same memory location

p_1 and p_2 are not guarded by
the same lock

Analysis Rules:

r_1 : $\text{Parallel}(p_1, p_3) :- \text{Parallel}(p_1, p_2), \text{Next}(p_2, p_3), \text{Unguarded}(p_1, p_3)$.

r_2 : $\text{Parallel}(p_1, p_2) :- \text{Parallel}(p_2, p_1)$.

r_3 : $\text{Race}(p_1, p_2) :- \text{Parallel}(p_1, p_2), \text{Alias}(p_1, p_2)$.

분석 예제: Datarace

Analysis Inputs:

$\text{Next}(p_1, p_2)$, $\text{Alias}(p_1, p_2)$, $\text{Unguarded}(p_1, p_2)$.

Analysis Outputs:

$\text{Parallel}(p_1, p_2)$, $\text{Race}(p_1, p_2)$

Program point p_1 and p_2 can be executed in parallel

Race condition between p_1 and p_2

r_1 : $\text{Parallel}(p_1, p_2) \text{ :- } \text{Parallel}(p_1, p_2), \text{Next}(p_2, p_3), \text{Unguarded}(p_1, p_3)$.

r_2 : $\text{Parallel}(p_1, p_2) \text{ :- } \text{Parallel}(p_2, p_1)$.

r_3 : $\text{Race}(p_1, p_2) \text{ :- } \text{Parallel}(p_1, p_2), \text{Alias}(p_1, p_2)$.

분석 예제: Datarace

Analysis Inputs:

$\text{Next}(p_1, p_2)$, $\text{Alias}(p_1, p_2)$, $\text{Unguarded}(p_1, p_2)$.

Analysis Outputs:

$\text{Parallel}(p_1, p_2)$, $\text{Race}(p_1, p_2)$

Analysis Rules:

r_1 : $\text{Parallel}(p_1, p_3) :- \text{Parallel}(p_1, p_2), \text{Next}(p_2, p_3), \text{Unguarded}(p_1, p_3)$.

r_2 : $\text{Parallel}(p_1, p_2) :- \text{Parallel}(p_2, p_1)$.

r_3 : $\text{Race}(p_1, p_2) :- \text{Parallel}(p_1, p_2), \text{Alias}(p_1, p_2)$.

Thread 1

```
...  
x = y + 1; // L1  
...
```

Thread 2

```
...  
z = y + 1; // L2  
x = z + 1; // L3  
...
```

분석 예제: Datarace

Analysis Inputs:

$\text{Next}(p_1, p_2)$, $\text{Alias}(p_1, p_2)$, $\text{Unguarded}(p_1, p_2)$.

Analysis Outputs:

$\text{Parallel}(p_1, p_2)$, $\text{Race}(p_1, p_2)$

Analysis Rules:

r₁: $\text{Parallel}(p_1, p_3) \text{ :- } \text{Parallel}(p_1, p_2), \text{Next}(p_2, p_3), \text{Unguarded}(p_1, p_3)$.

r₂: $\text{Parallel}(p_1, p_2) \text{ :- } \text{Parallel}(p_2, p_1)$.

r₃: $\text{Race}(p_1, p_2) \text{ :- } \text{Parallel}(p_1, p_2), \text{Alias}(p_1, p_2)$.

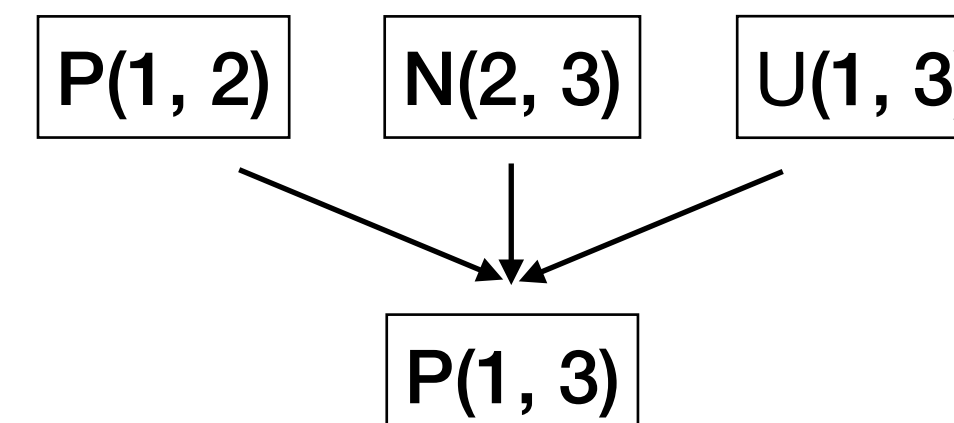
Thread 1

```
...  
x = y + 1; // L1  
...
```

Thread 2

```
...  
z = y + 1; // L2  
x = z + 1; // L3  
...
```

Derivation



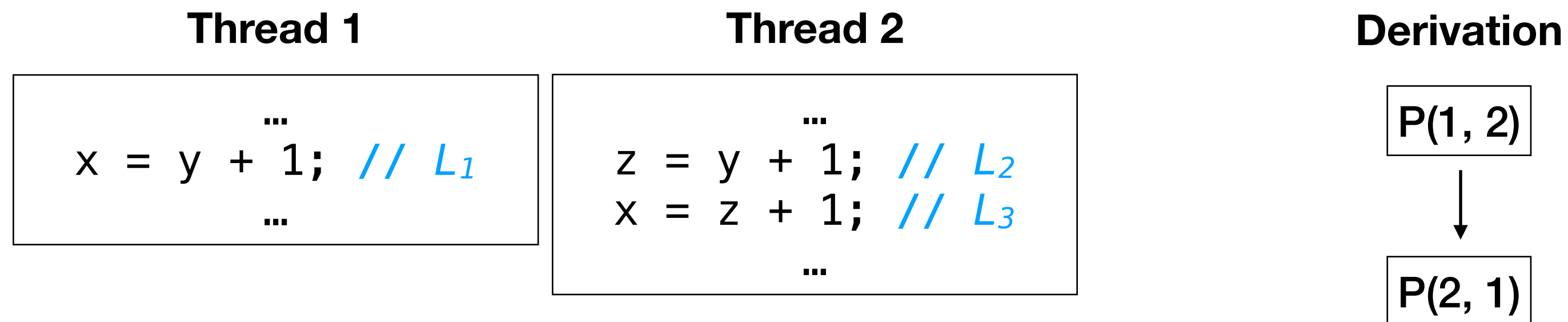
분석 예제: Datarace

Analysis Inputs:
Next(p_1, p_2), Alias(p_1, p_2), Unguarded(p_1, p_2).

Analysis Outputs:
Parallel(p_1, p_2), Race(p_1, p_2)

Analysis Rules:

- r₁: Parallel(p_1, p_3) :- Parallel(p_1, p_2), Next(p_2, p_3), Unguarded(p_1, p_3).
- r₂: Parallel(p_1, p_2) :- Parallel(p_2, p_1).
- r₃: Race(p_1, p_2) :- Parallel(p_1, p_2), Alias(p_1, p_2).



분석 예제: Datarace

Analysis Inputs:

$\text{Next}(p_1, p_2)$, $\text{Alias}(p_1, p_2)$, $\text{Unguarded}(p_1, p_2)$.

Analysis Outputs:

$\text{Parallel}(p_1, p_2)$, $\text{Race}(p_1, p_2)$

Analysis Rules:

r_1 : $\text{Parallel}(p_1, p_3) \text{ :- } \text{Parallel}(p_1, p_2), \text{Next}(p_2, p_3), \text{Unguarded}(p_1, p_3)$.

r_2 : $\text{Parallel}(p_1, p_2) \text{ :- } \text{Parallel}(p_2, p_1)$.

r_3 : $\text{Race}(p_1, p_2) \text{ :- } \text{Parallel}(p_1, p_2), \text{Alias}(p_1, p_2)$.

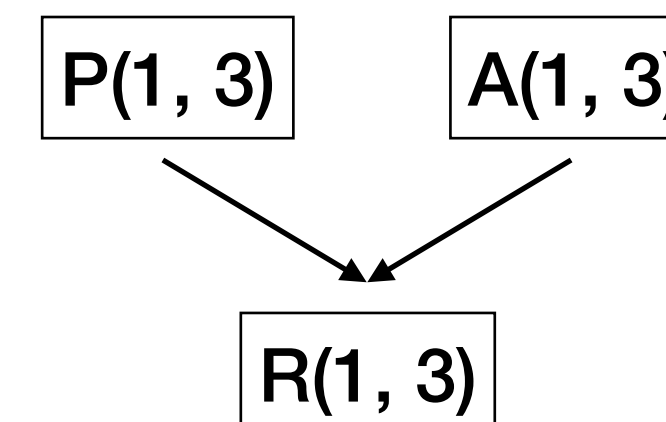
Thread 1

```
...  
x = y + 1; // L1  
...
```

Thread 2

```
...  
z = y + 1; // L2  
x = z + 1; // L3  
...
```

Derivation



예제 프로그램

```
public class RequestHandler {
    private FtpRequest request;

    public FtpRequest getRequest() {
        return request;          //L0
    }

    public void close() {
        synchronized (this) {    //L1
            if (isClosed) return; //L2
            isClosed = true;      //L3
        }
        controlSocket.close();    //L4
        controlSocket = null;      //L5
        request.clear();          //L6
        request = null;           //L7
    }
}
```

Analysis Rules:

- r₁: $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$
- r₂: $P(p_1, p_2) :- P(p_2, p_1).$
- r₃: $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$

*Apache FTP Server

예제 프로그램

```
public class RequestHandler {
  private FtpRequest request;

  public FtpRequest getRequest() {
    return request; //L0
  }

  public void close() {
    synchronized (this) { //L1
      if (isClosed) return; //L2
      isClosed = true; //L3
    }
    controlSocket.close(); //L4
    controlSocket = null; //L5
    request.clear(); //L6
    request = null; //L7
  }
}
```

Analysis Rules:

- r₁: $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$
- r₂: $P(p_1, p_2) :- P(p_2, p_1).$
- r₃: $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$

Datarace

***Apache FTP Server**

예제 프로그램

```
public class RequestHandler {
  private FtpRequest request;

  public FtpRequest getRequest() {
    return request;          //L0
  }

  public void close() {
    synchronized (this) {   //L1
      if (isClosed) return; //L2
      isClosed = true;      //L3
    }
    controlSocket.close();  //L4
    controlSocket = null;   //L5
    request.clear();        //L6
    request = null;         //L7
  }
}
```

Analysis Rules:

- r₁: $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$
- r₂: $P(p_1, p_2) :- P(p_2, p_1).$
- r₃: $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$

False alarm

False alarm

*Apache FTP Server

정적 분석

Program

```
controlSocket.close(); //L4  
controlSocket = null; //L5  
request.clear(); //L6  
request = null; //L7
```

Analysis Rules

```
r1:  $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$   
r2:  $P(p_1, p_2) :- P(p_2, p_1).$   
r3:  $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$ 
```


정적 분석

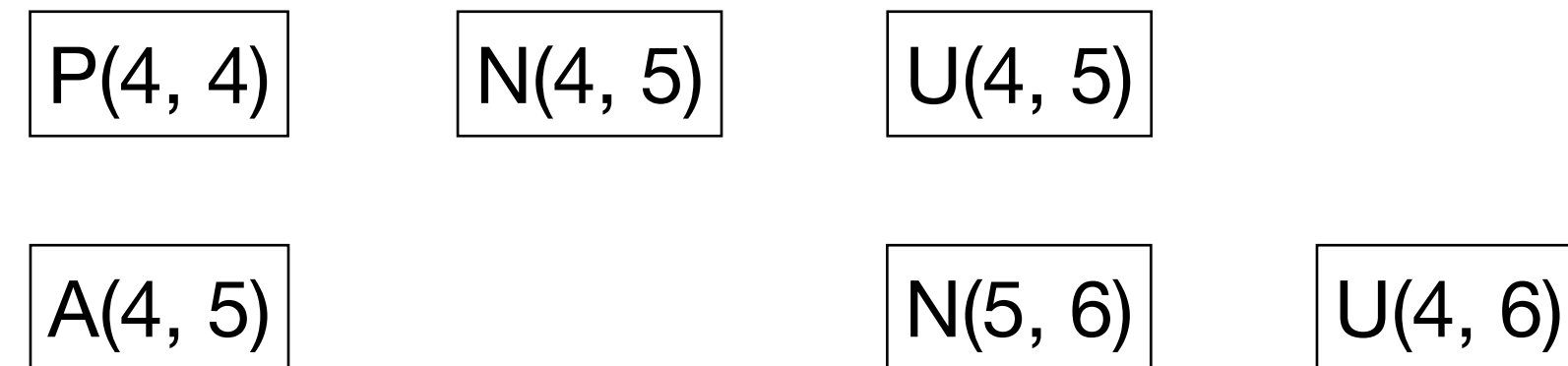
Program

```
controlSocket.close(); //L4  
controlSocket = null; //L5  
request.clear(); //L6  
request = null; //L7
```

Analysis Rules

```
r1:  $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$   
r2:  $P(p_1, p_2) :- P(p_2, p_1).$   
r3:  $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$ 
```

Derivation Graph



1. 입력부터 시작

정적 분석

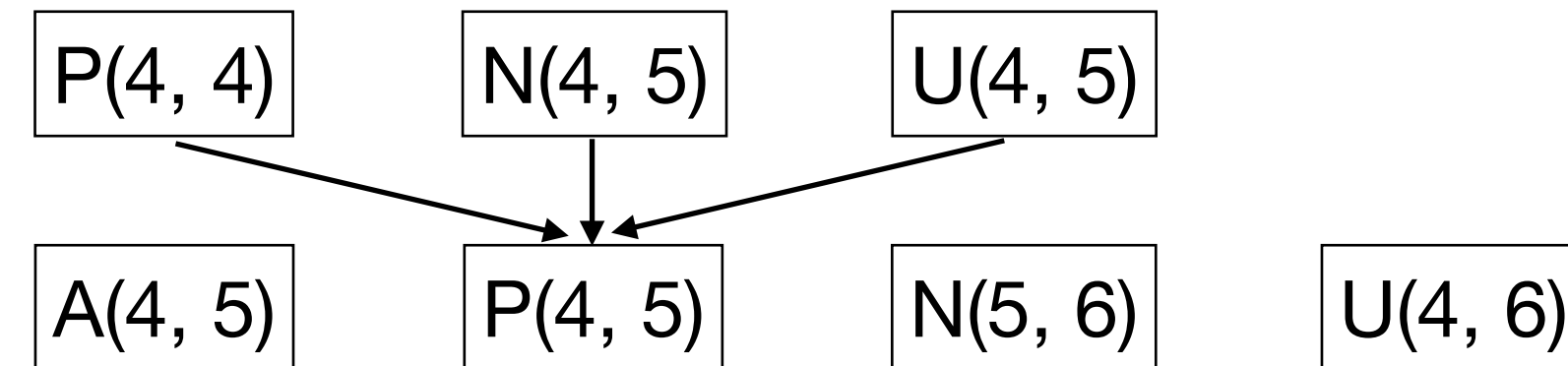
Program

```
controlSocket.close(); //L4  
controlSocket = null; //L5  
request.clear(); //L6  
request = null; //L7
```

Analysis Rules

```
r1:  $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$   
r2:  $P(p_1, p_2) :- P(p_2, p_1).$   
r3:  $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$ 
```

Derivation Graph



2. 입력에 규칙을 적용

정적 분석

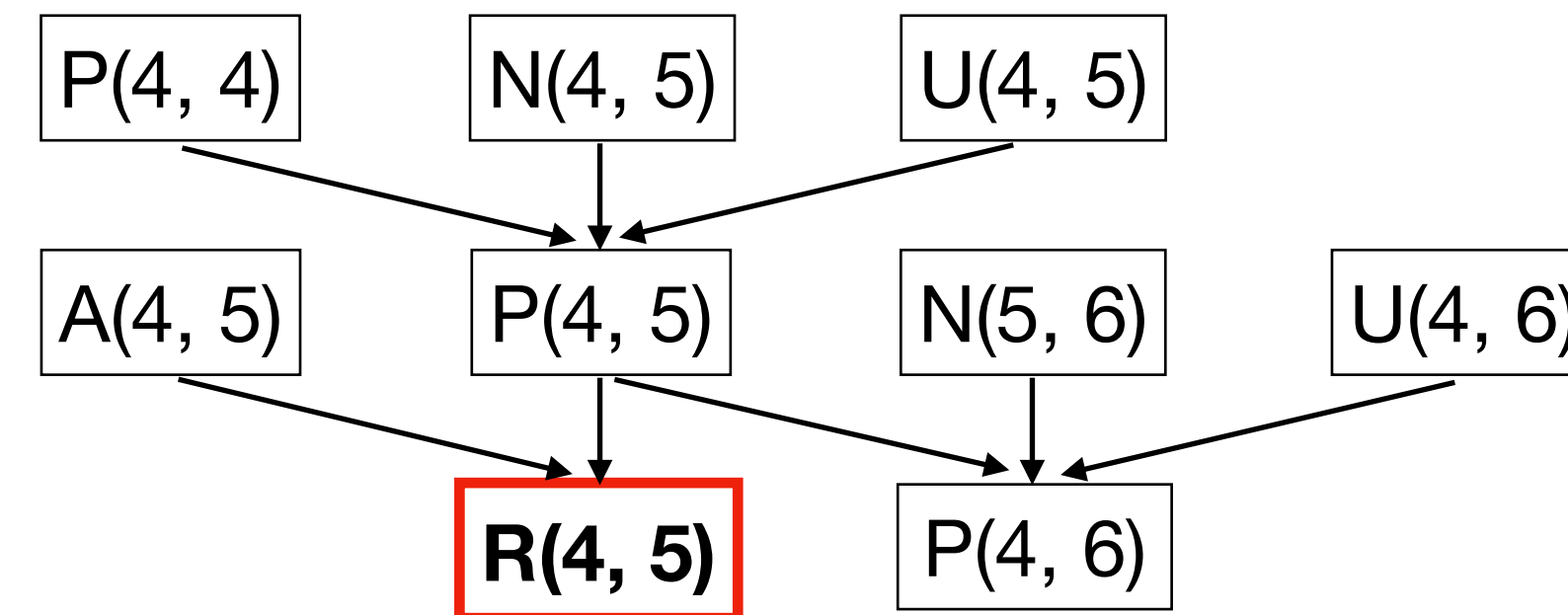
Program

```
controlSocket.close(); //L4  
controlSocket = null; //L5  
request.clear(); //L6  
request = null; //L7
```

Analysis Rules

```
r1:  $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$   
r2:  $P(p_1, p_2) :- P(p_2, p_1).$   
r3:  $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$ 
```

Derivation Graph



3. 모든 중간결과에 다시
규칙을 적용

정적 분석

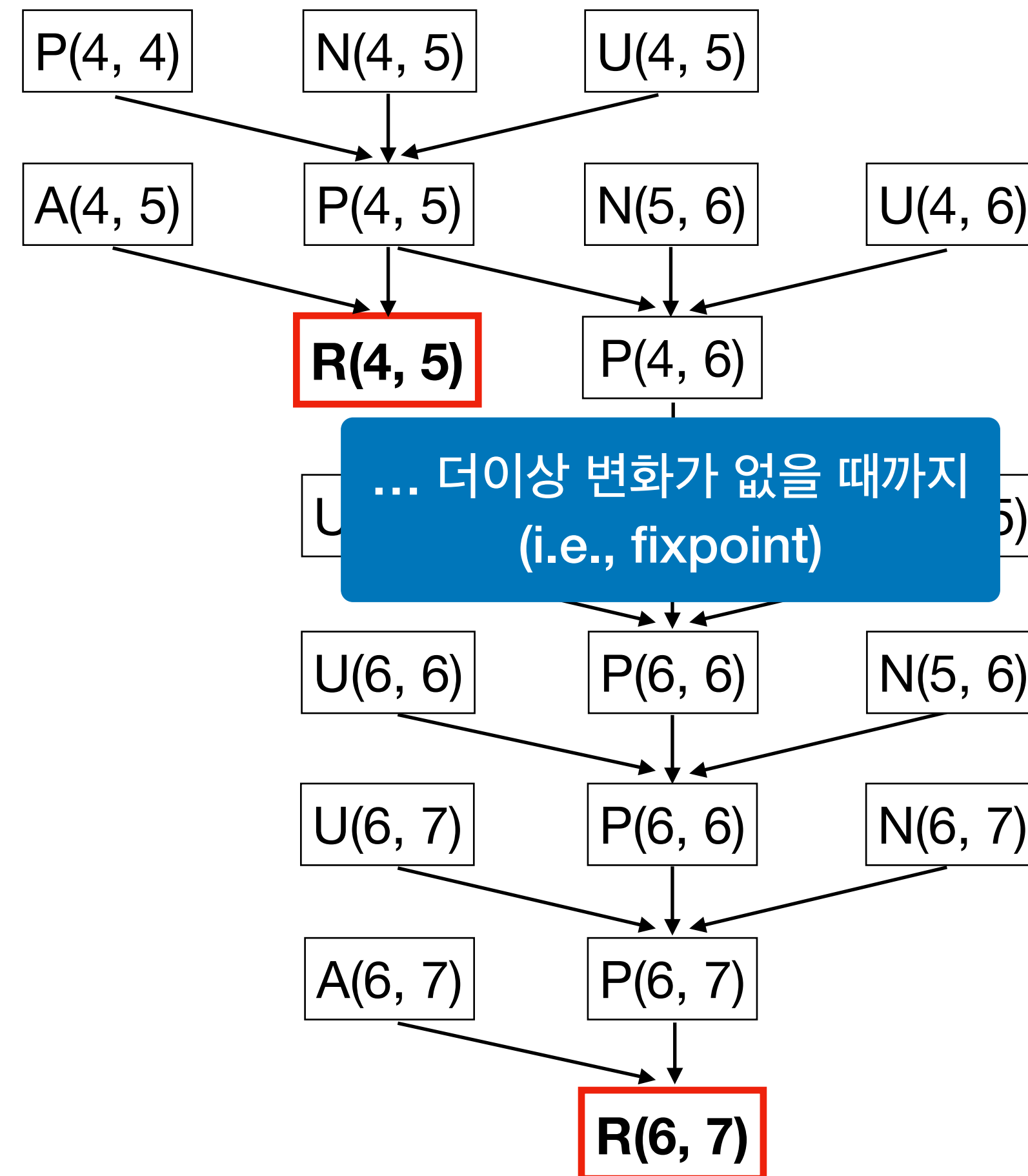
Program

```
controlSocket.close(); //L4
controlSocket = null; //L5
request.clear(); //L6
request = null; //L7
```

Analysis Rules

```
r1: P(p1, p3) :- P(p1, p2), N(p2, p3), U(p1, p3).
r2: P(p1, p2) :- P(p2, p1).
r3: R(p1, p2) :- P(p1, p2), A(p1, p2).
```

Derivation Graph

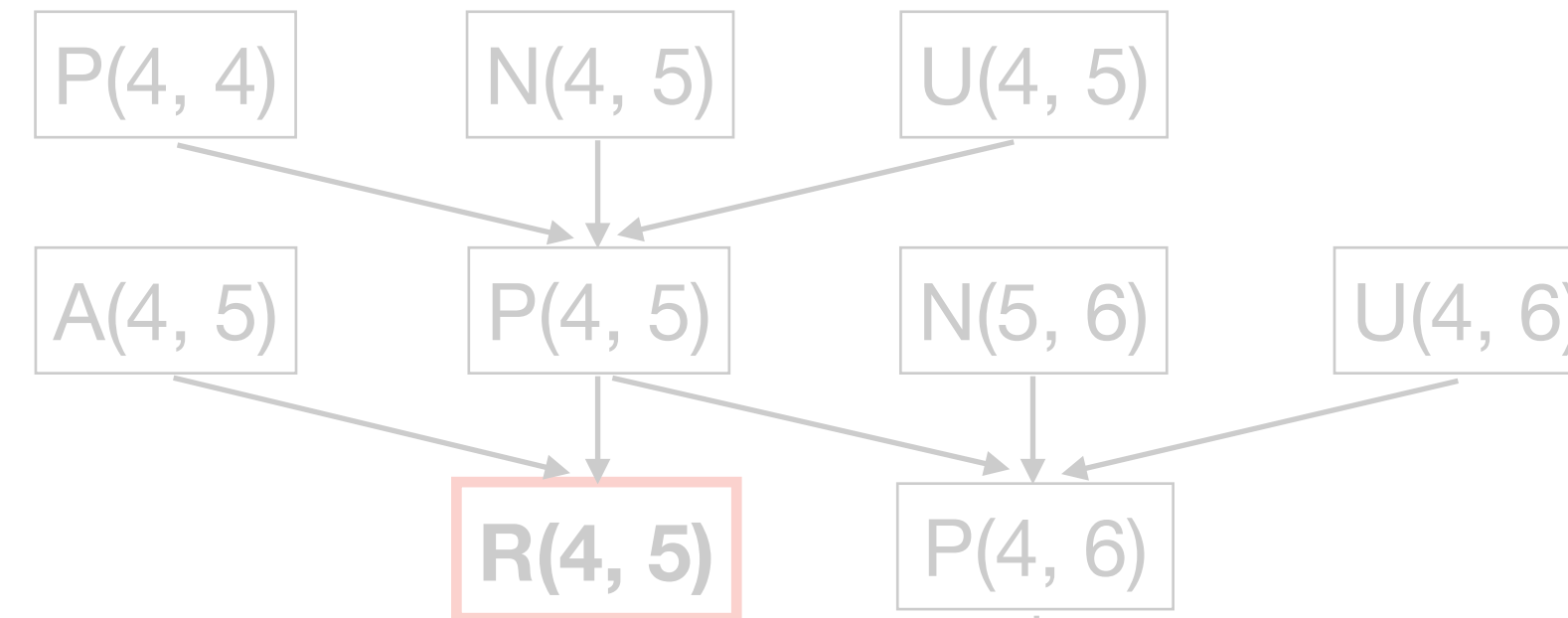


정적 분석

Program

```
controlSocket.close(); //L4
controlSocket = null; //L5
request.clear(); //L6
request = null; //L7
```

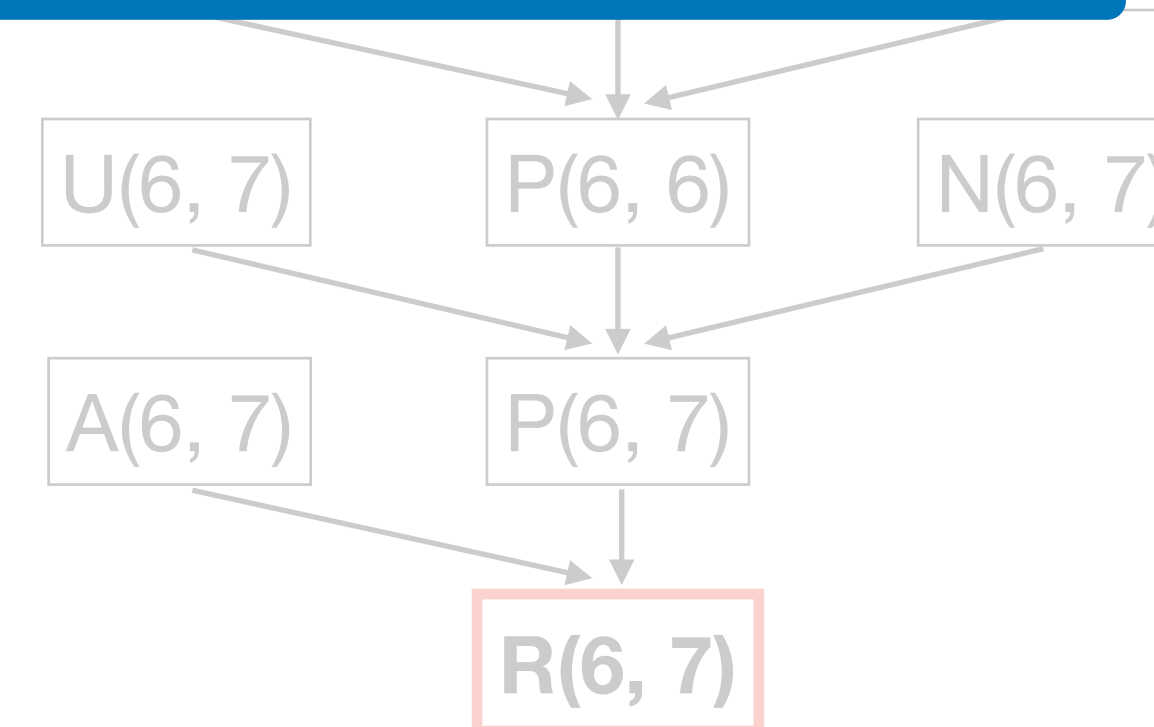
Derivation Graph



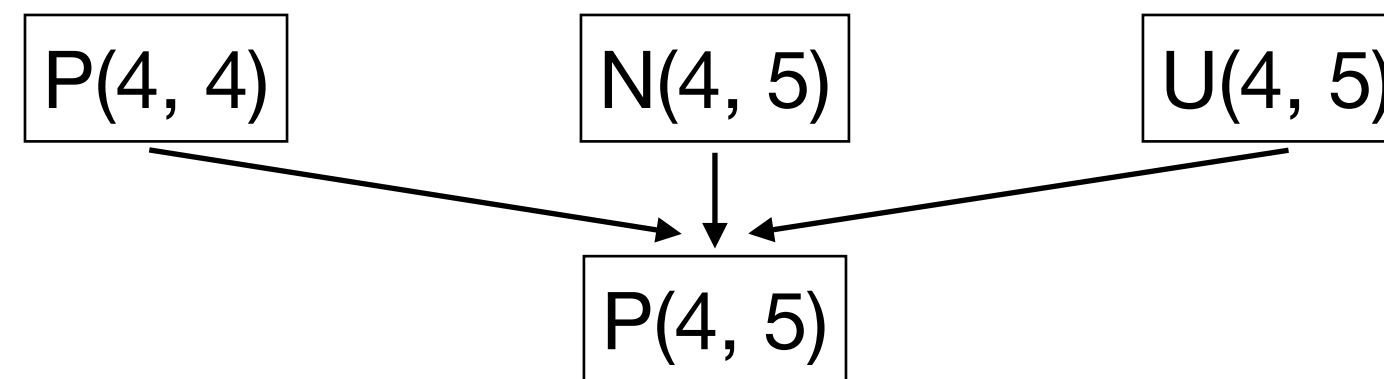
Analysis Rules

```
r1: P(p1, p3)
r2: P(p1, p2) :- P(p2, p1).
r3: R(p1, p2) :- P(p1, p2), A(p1, p2).
```

Q: 경보의 확률을 어떻게 구할 것인가?

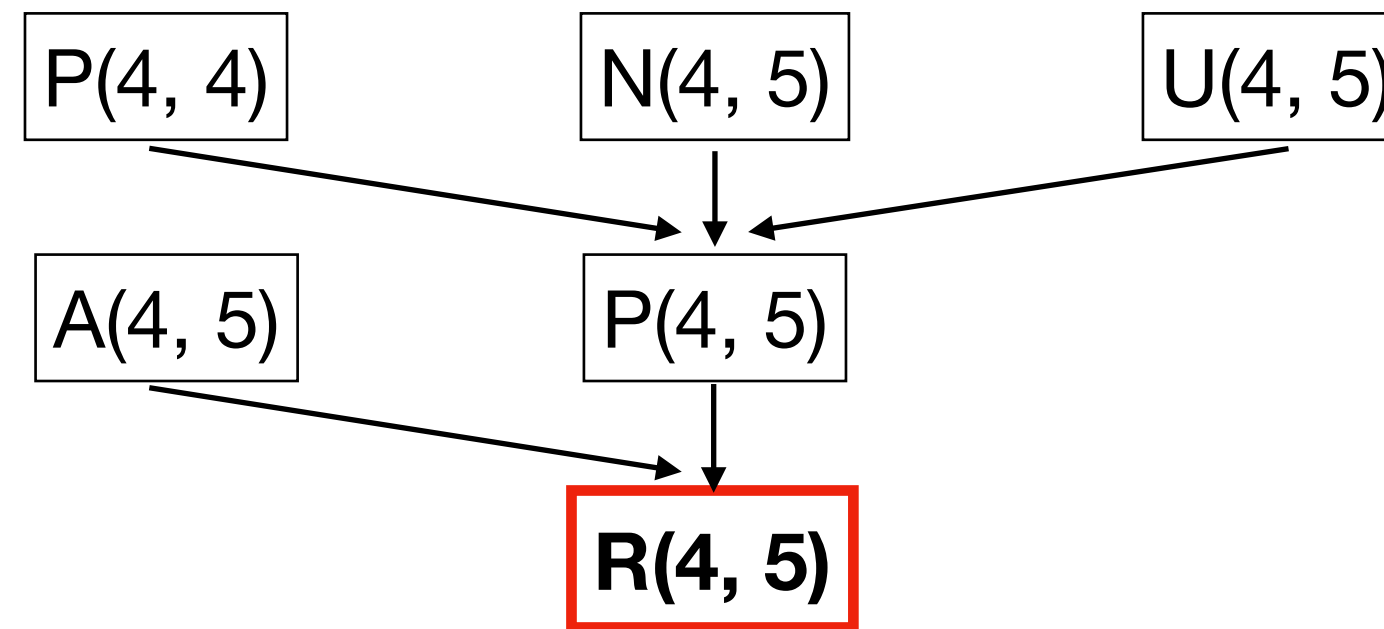


베이지안 네트워크



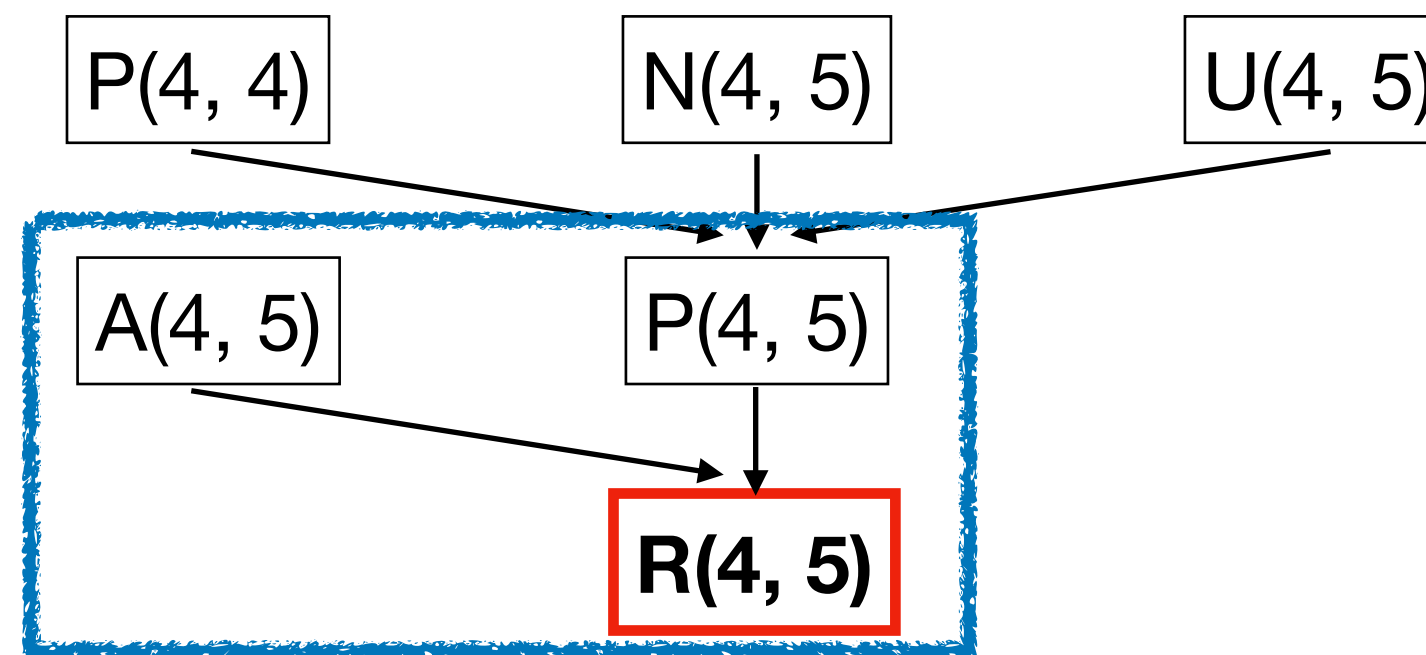
Logical Rule	Probabilistic Rule																				
<p>r₁: $P(p_1, p_3) :- P(p_1, p_2), N(p_2, p_3), U(p_1, p_3).$</p> <p>r₂: $P(p_1, p_2) :- P(p_2, p_1).$</p> <p>r₃: $R(p_1, p_2) :- P(p_1, p_2), A(p_1, p_2).$</p>	<table border="1"> <thead> <tr> <th>P(4,4)</th> <th>N(4,5)</th> <th>U(4,5)</th> <th>$Pr(P(4,5) \dots)$</th> </tr> </thead> <tbody> <tr> <td>TRUE</td> <td>TRUE</td> <td>TRUE</td> <td>0.95*</td> </tr> <tr> <td>TRUE</td> <td>TRUE</td> <td>FALSE</td> <td>0</td> </tr> <tr> <td colspan="4" style="text-align: center;">...</td> </tr> <tr> <td>FALSE</td> <td>FALSE</td> <td>FALSE</td> <td>0</td> </tr> </tbody> </table>	P(4,4)	N(4,5)	U(4,5)	$Pr(P(4,5) \dots)$	TRUE	TRUE	TRUE	0.95*	TRUE	TRUE	FALSE	0	...				FALSE	FALSE	FALSE	0
P(4,4)	N(4,5)	U(4,5)	$Pr(P(4,5) \dots)$																		
TRUE	TRUE	TRUE	0.95*																		
TRUE	TRUE	FALSE	0																		
...																					
FALSE	FALSE	FALSE	0																		
	*computed by an offline learning																				

Marginal Inference



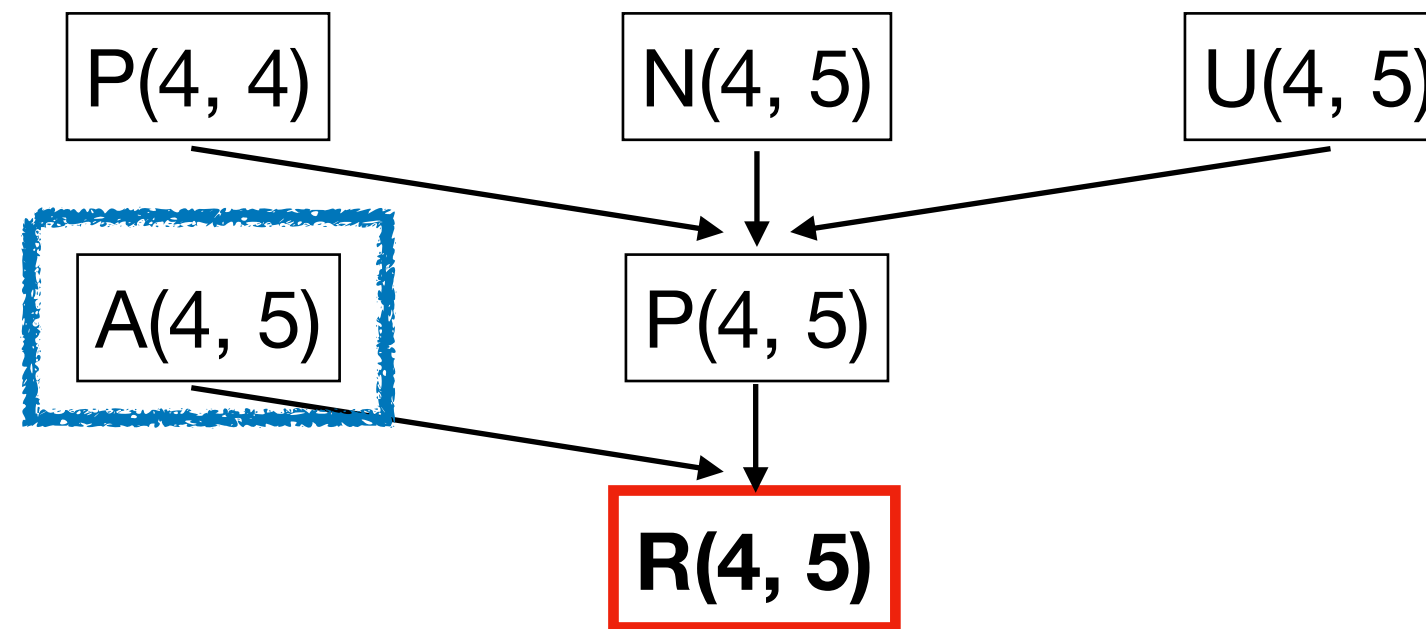
$$Pr(R(4,5)) =$$

Marginal Inference



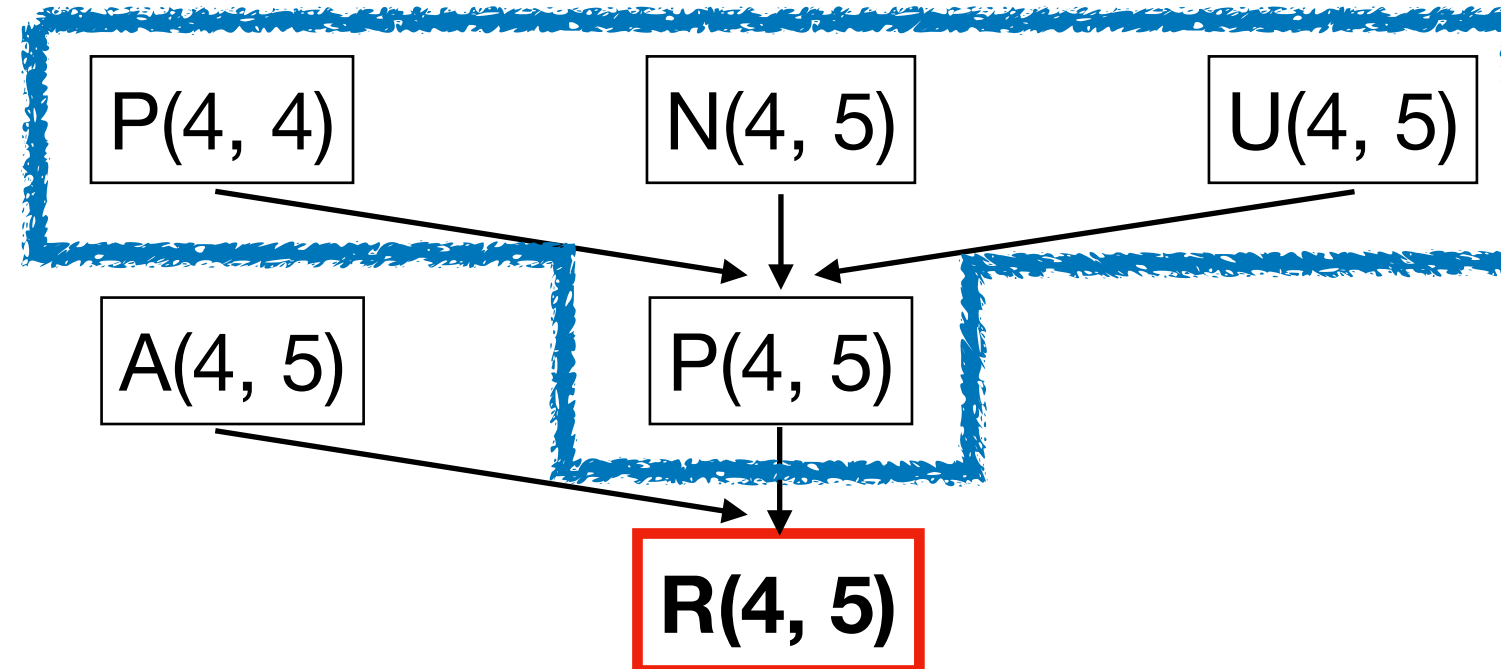
$$Pr(R(4,5)) = \cancel{Pr(R(4,5) | P(4,4), N(4,5), U(4,5))} \times Pr(R(4,5) | A(4,5), P(4,5))$$

Marginal Inference



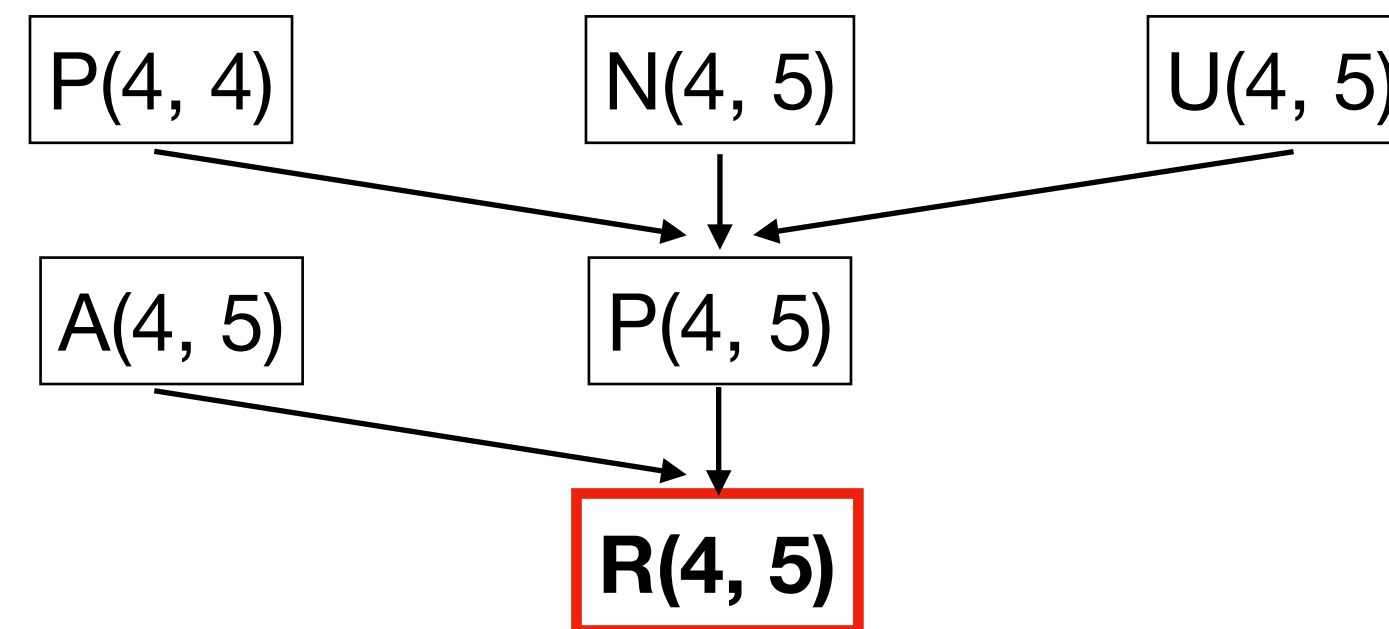
$$\begin{aligned} Pr(R(4,5)) &= Pr(R(4,5) \mid A(4,5), P(4,5)) \\ &\times Pr(A(4,5)) \\ &\times \end{aligned}$$

Marginal Inference



$$\begin{aligned} Pr(R(4,5)) &= Pr(R(4,5) \mid A(4,5), P(4,5)) \\ &\times Pr(A(4,5)) \\ &\times Pr(P(4,5) \mid \dots) \\ &\times \end{aligned}$$

Marginal Inference



$$\begin{aligned} Pr(R(4,5)) &= Pr(R(4,5) \mid A(4,5), P(4,5)) \\ &\times Pr(A(4,5)) \\ &\times Pr(P(4,5) \mid \dots) \\ &\times \dots \\ &= 0.398 \end{aligned}$$

by an off-the-shelf marginal inference solver

순위 기반 오류 보고서

```

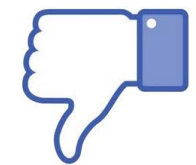
public class RequestHandler {
    private FtpRequest request;

    public FtpRequest getRequest() {
        return request; //L0
    }

    public void close() {
        synchronized (this) { //L1
            if (isClosed) return; //L2
            isClosed = true; //L3
        }
        controlSocket.close(); //L4
        controlSocket = null; //L5
        request.clear(); //L6
        request = null; //L7
    }
}

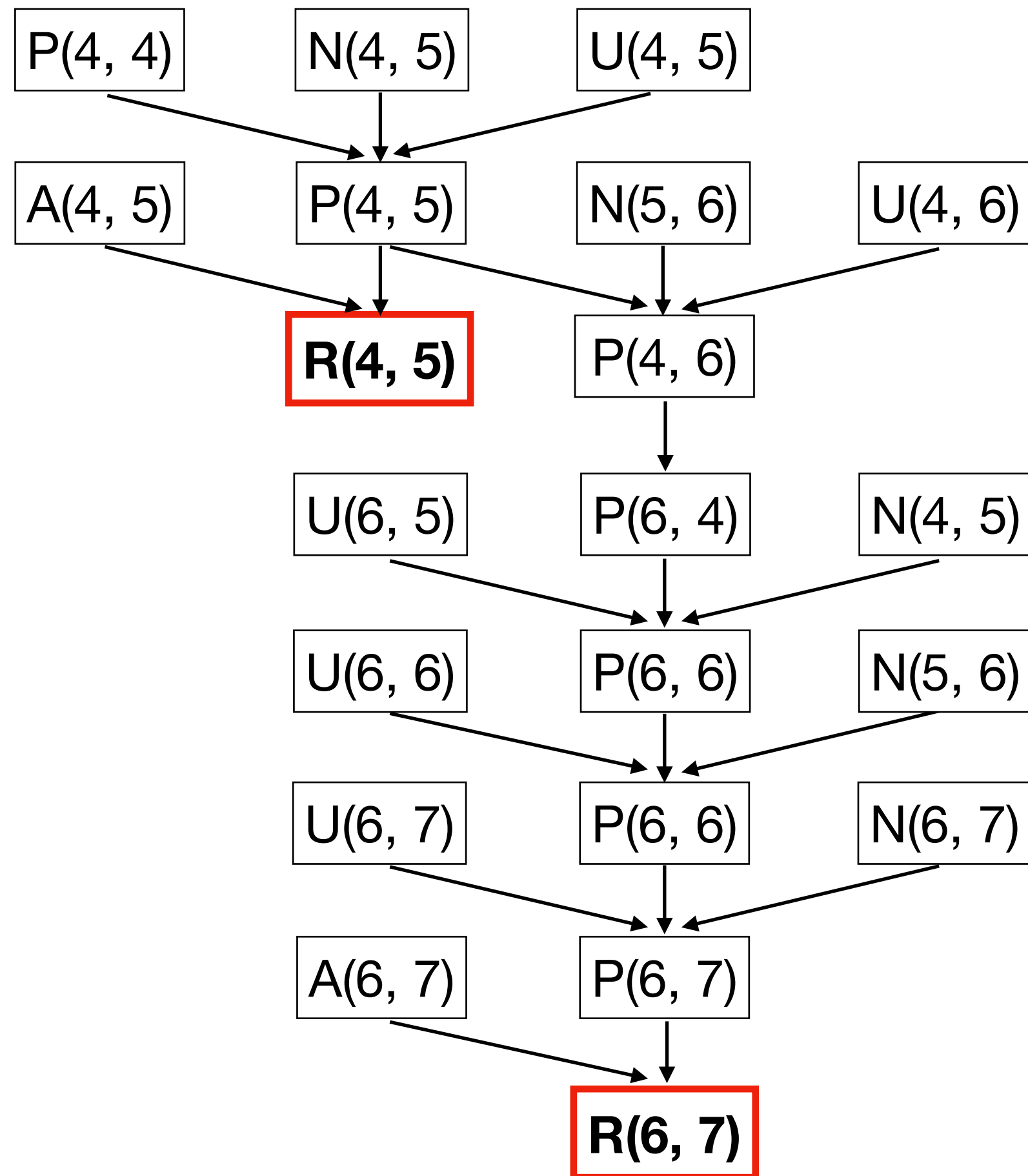
```

Ranking	Alarm	Confidence
1	R(4, 5)	0.398
2	R(5, 5)	0.378
3	R(6, 7)	0.324
4	R(7, 7)	0.308
5	R(0, 7)	0.279

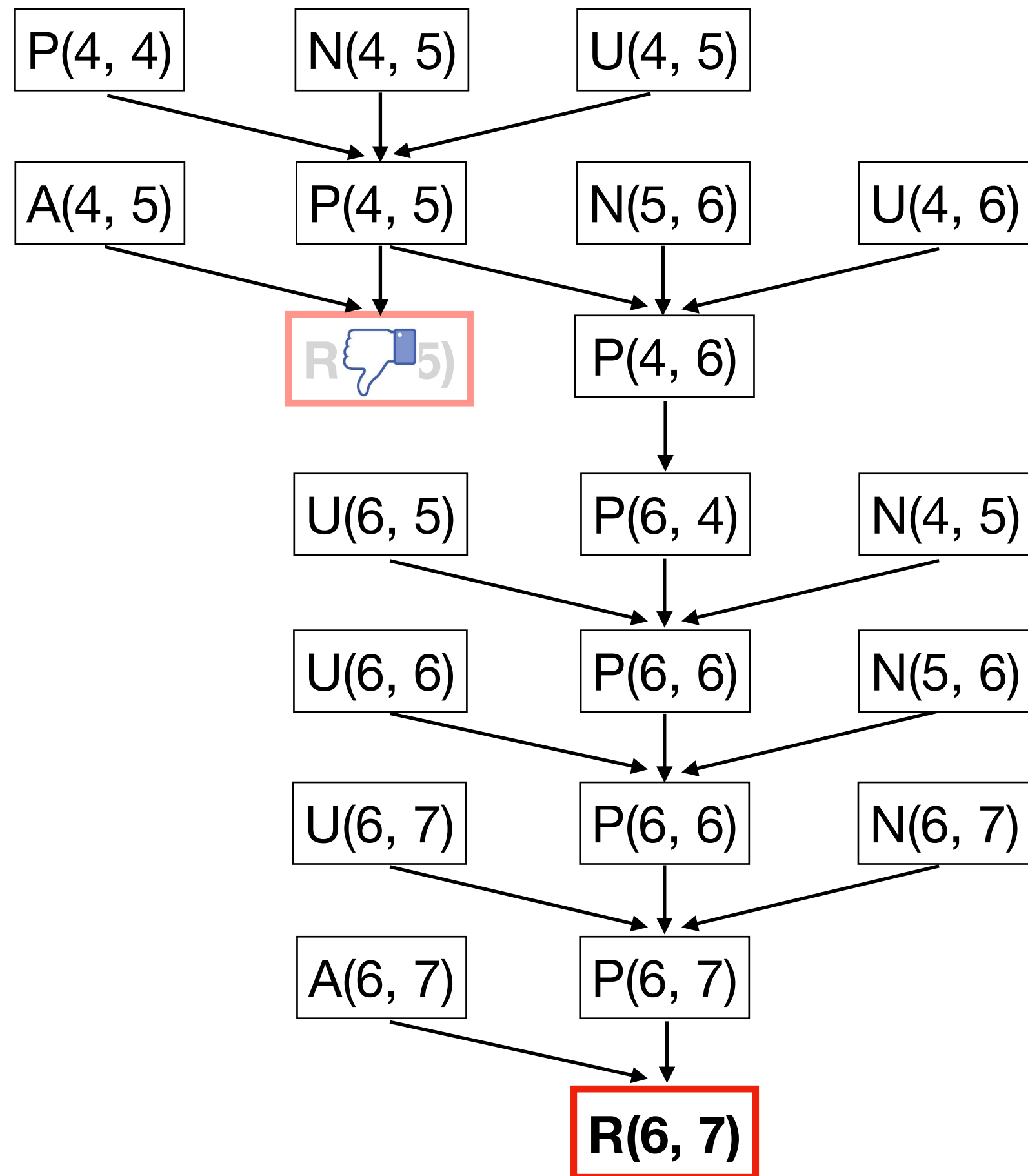


Q: What are the probabilities of the other alarms when R(4,5) is false?

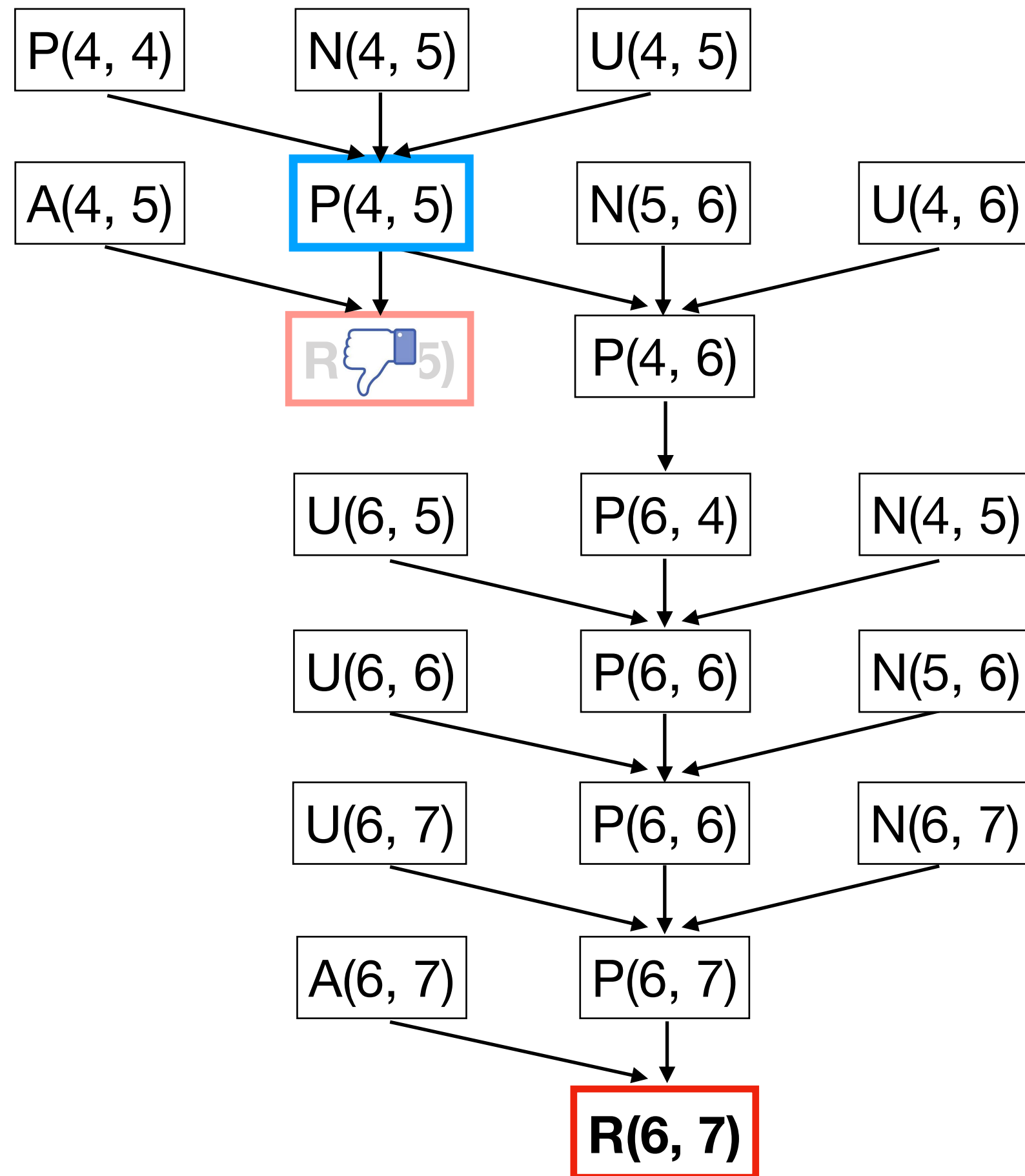
경보의 확률



경보의 확률

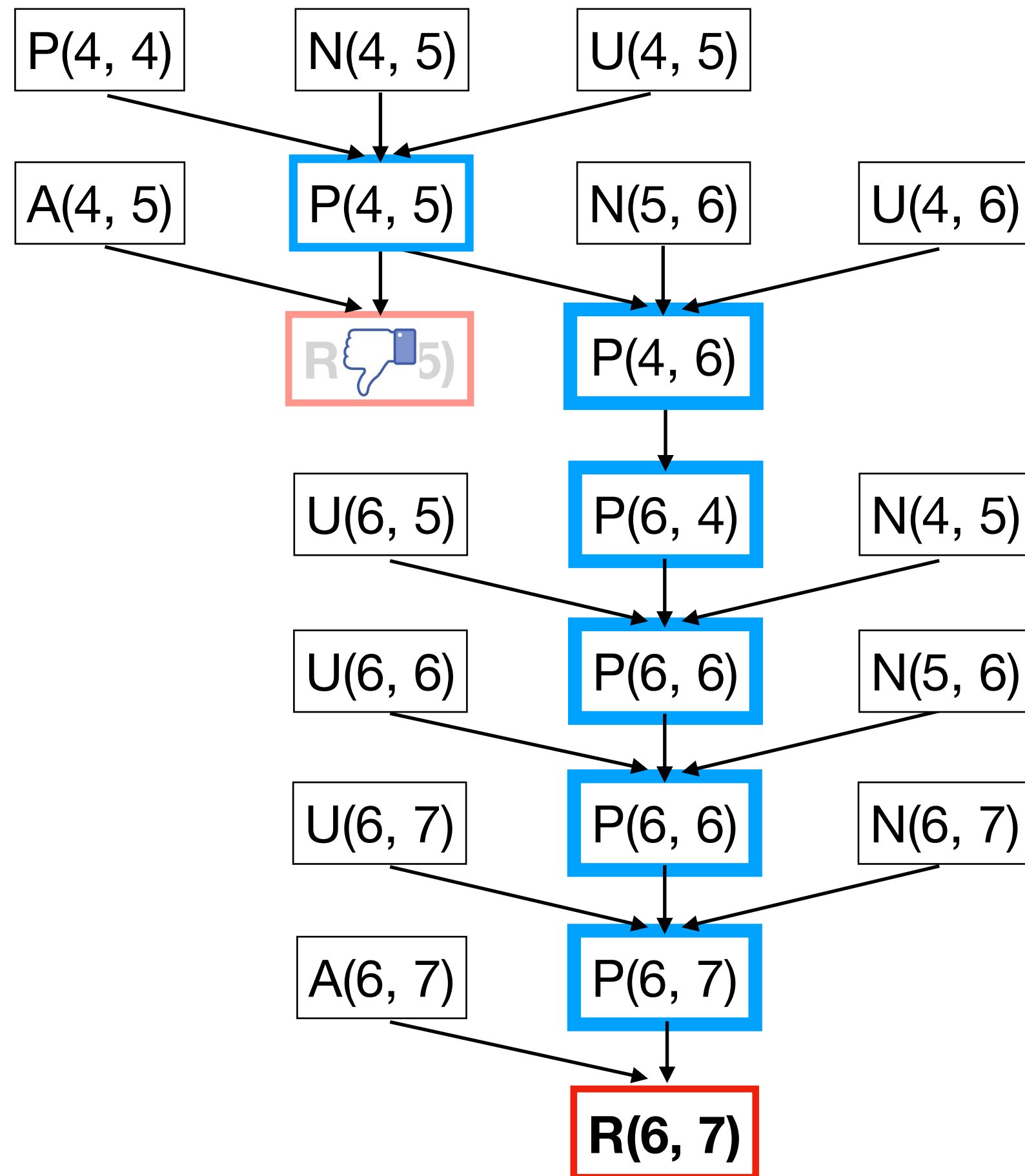


경보의 확률



$$\begin{aligned}
 &Pr(P(4,5) \mid \neg R(4,5)) \\
 &= Pr(\neg R(4,5) \mid P(4,5)) * \\
 &\quad Pr(P(4,5)) / Pr(\neg R(4,5)) \\
 &= 0.03
 \end{aligned}$$

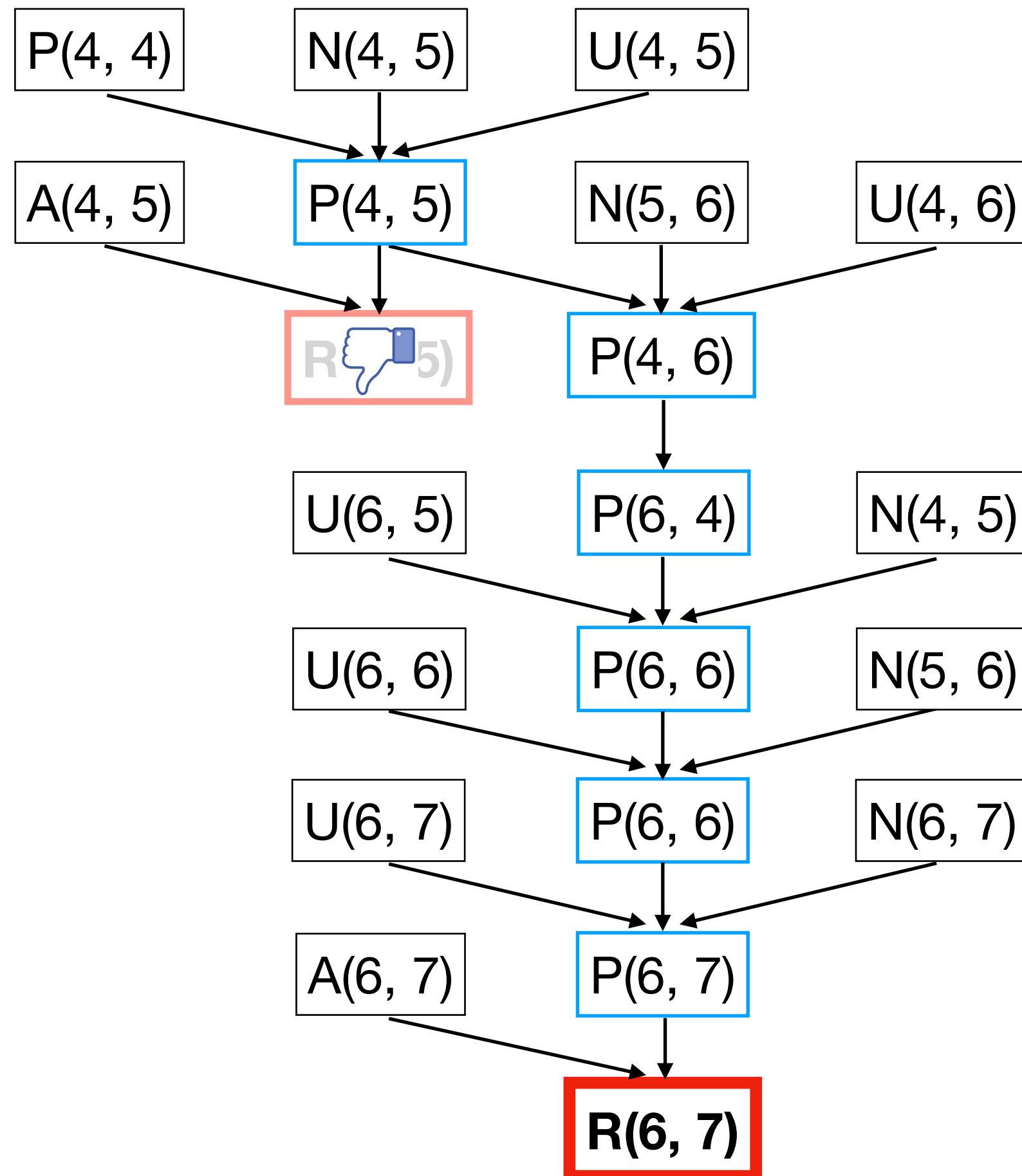
경보의 확률



$$\begin{aligned}
 &Pr(P(4,5) \mid \neg R(4,5)) \\
 &= Pr(\neg R(4,5) \mid P(4,5)) * \\
 &\quad Pr(P(4,5)) / Pr(\neg R(4,5)) \\
 &= 0.03
 \end{aligned}$$

By Bayes's Rule:
 $Pr(A|B) = Pr(B|A) * Pr(A) / Pr(B)$

경보의 확률




$$\begin{aligned}
 &Pr(P(4,5) \mid \neg R(4,5)) \\
 &= Pr(\neg R(4,5) \mid P(4,5)) * \\
 &\quad Pr(P(4,5)) / Pr(\neg R(4,5)) \\
 &= 0.03
 \end{aligned}$$

By Bayes's Rule:
 $Pr(A|B) = Pr(B|A) * Pr(A) / Pr(B)$

$$\begin{aligned}
 &Pr(R(6,7) \mid \neg R(4,5)) \\
 &= Pr(R(6,7) \mid P(4,5)) * \\
 &\quad Pr(P(4,5) \mid \neg R(4,5)) \\
 &= 0.03
 \end{aligned}$$

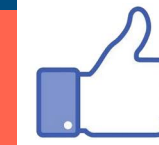
개선된 순위

Ranking	Alarm	Confidence
1	R(4, 5)	0.398
2	R(5, 5)	0.378
3	R(6, 7)	0.324
4	R(7, 7)	0.308
5	R(0, 7)	0.279



개선된 순위

Ranking	Alarm	Confidence
1	R(0, 7)	0.279
2	R(5, 5)	0.035
3	R(6, 7)	0.030
4	R(7, 7)	0.028
5	R(4, 5)	0

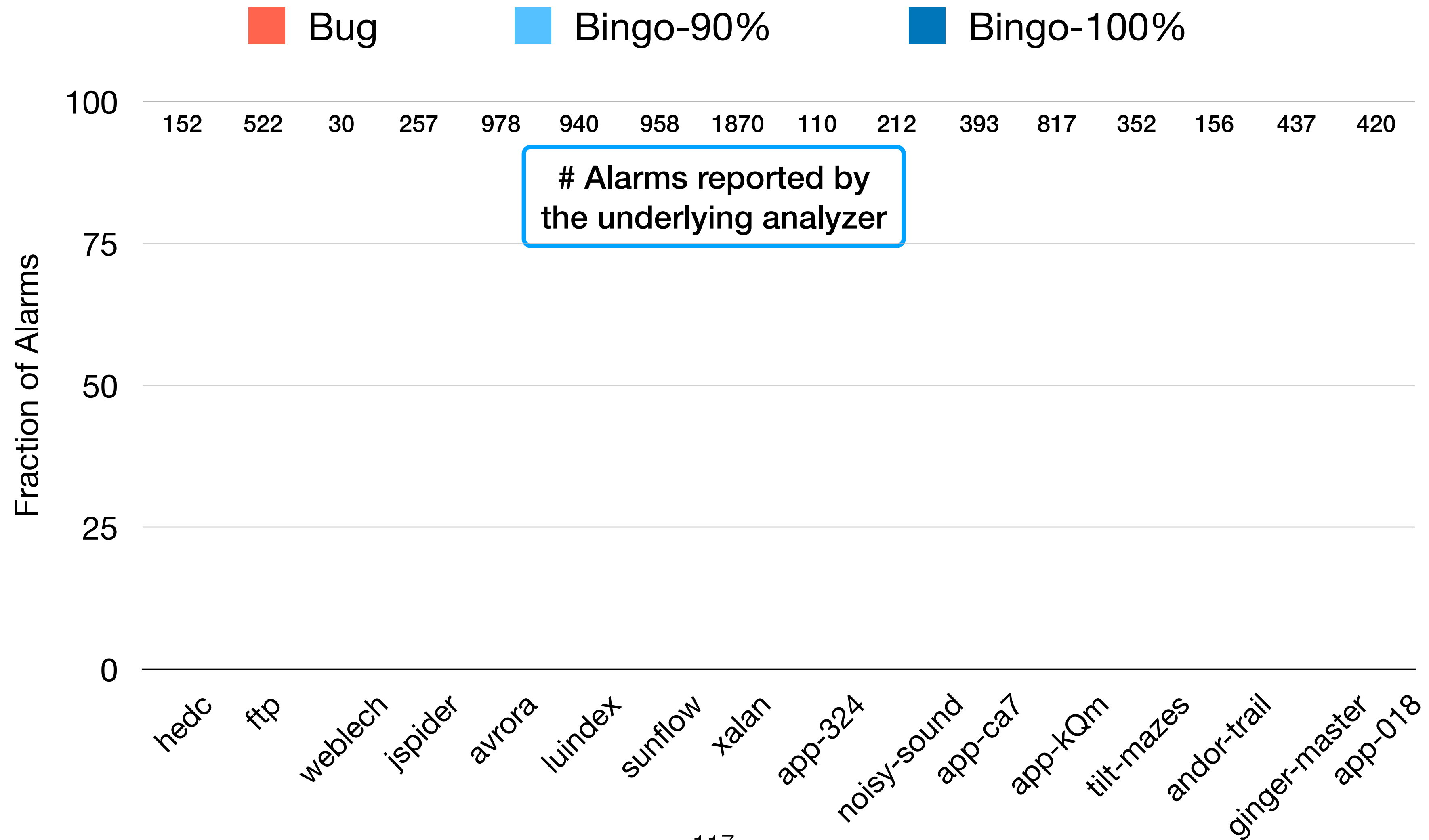


효과

40—616KLOC JAVA Programs
Datarace and Privacy leak analyses

hedc ftp weblech jspider avrora luindex sunflow xalan app-324 noisy-sound app-ca7 app-kQm tilt-mazes andor-trail ginger-master app-018

효과



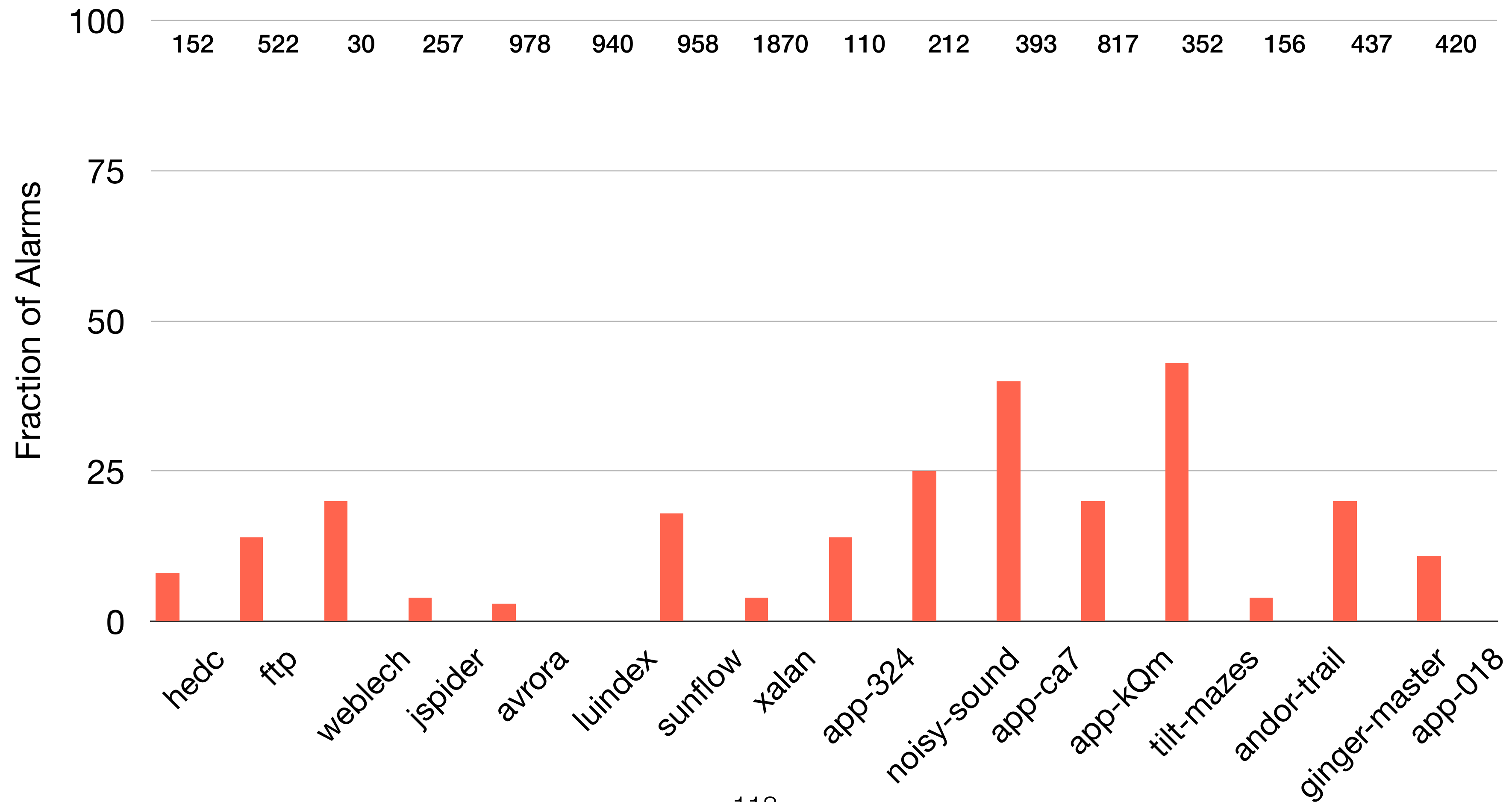
효과

Only a few of them are real bugs (12%)

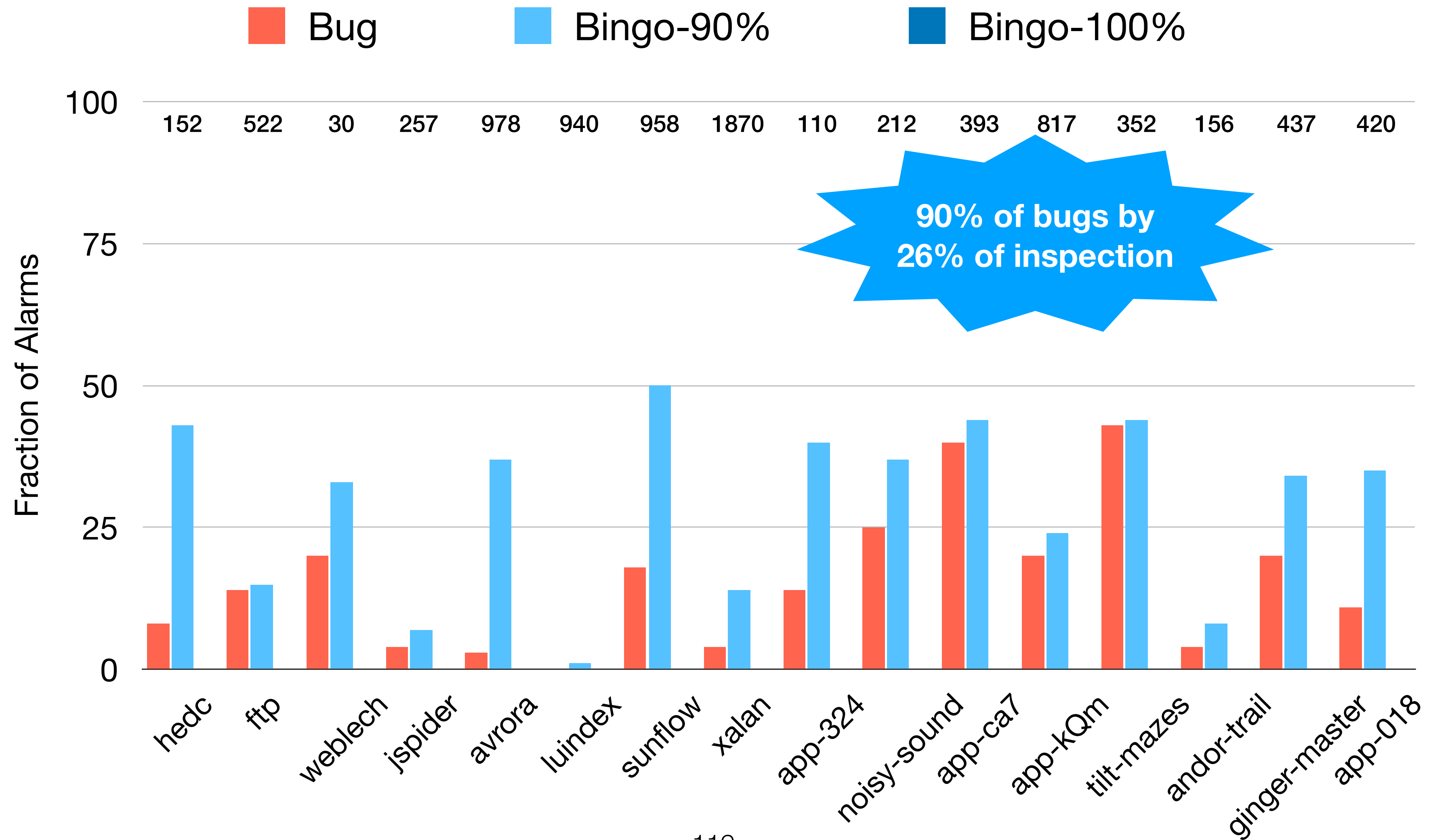
Bug

Bingo-90%

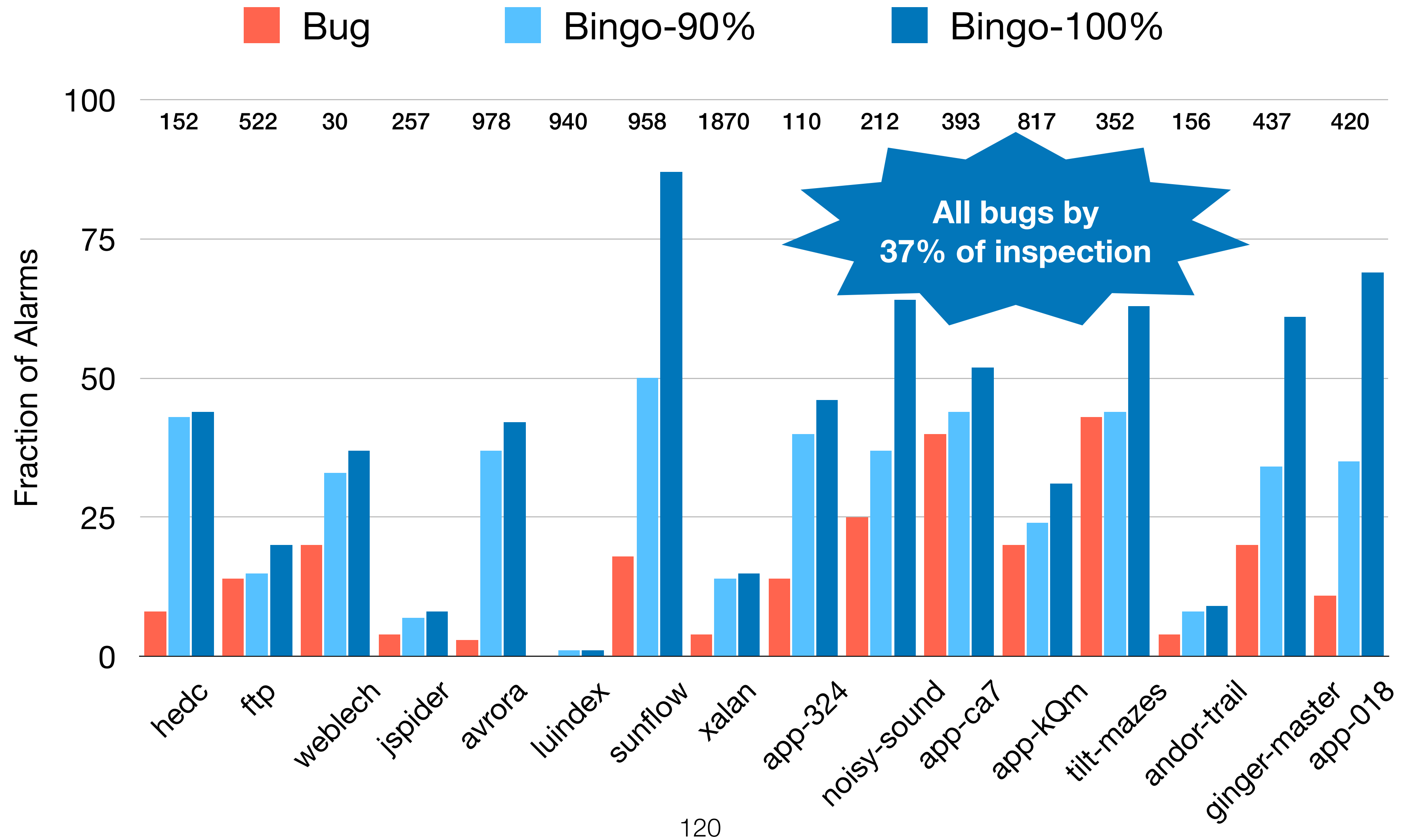
Bingo-100%



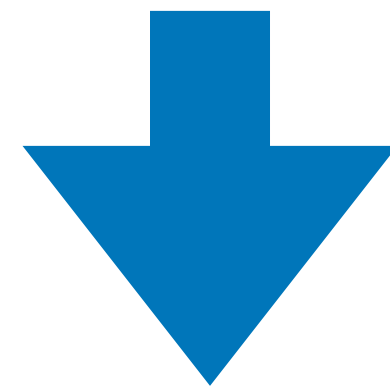
효과



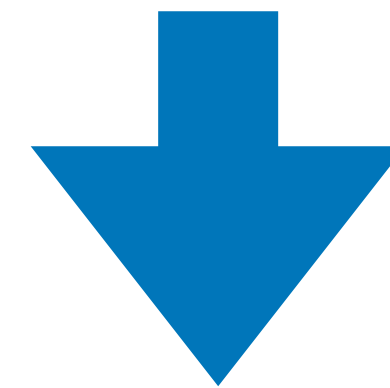
효과



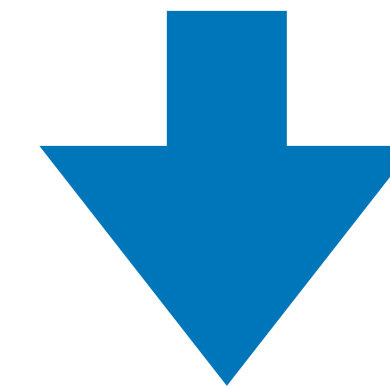
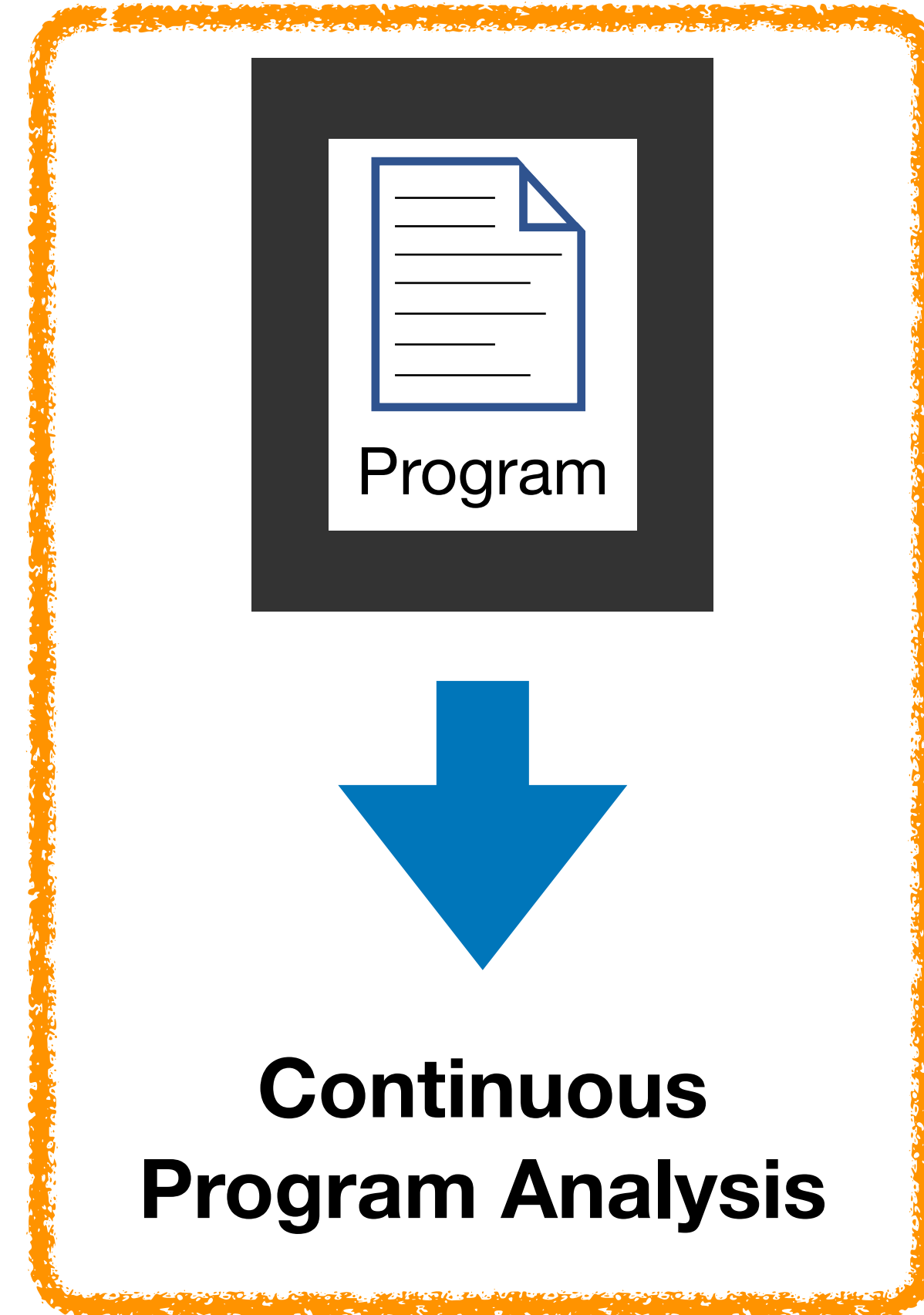
Outline



**Adaptive
Program Analysis**

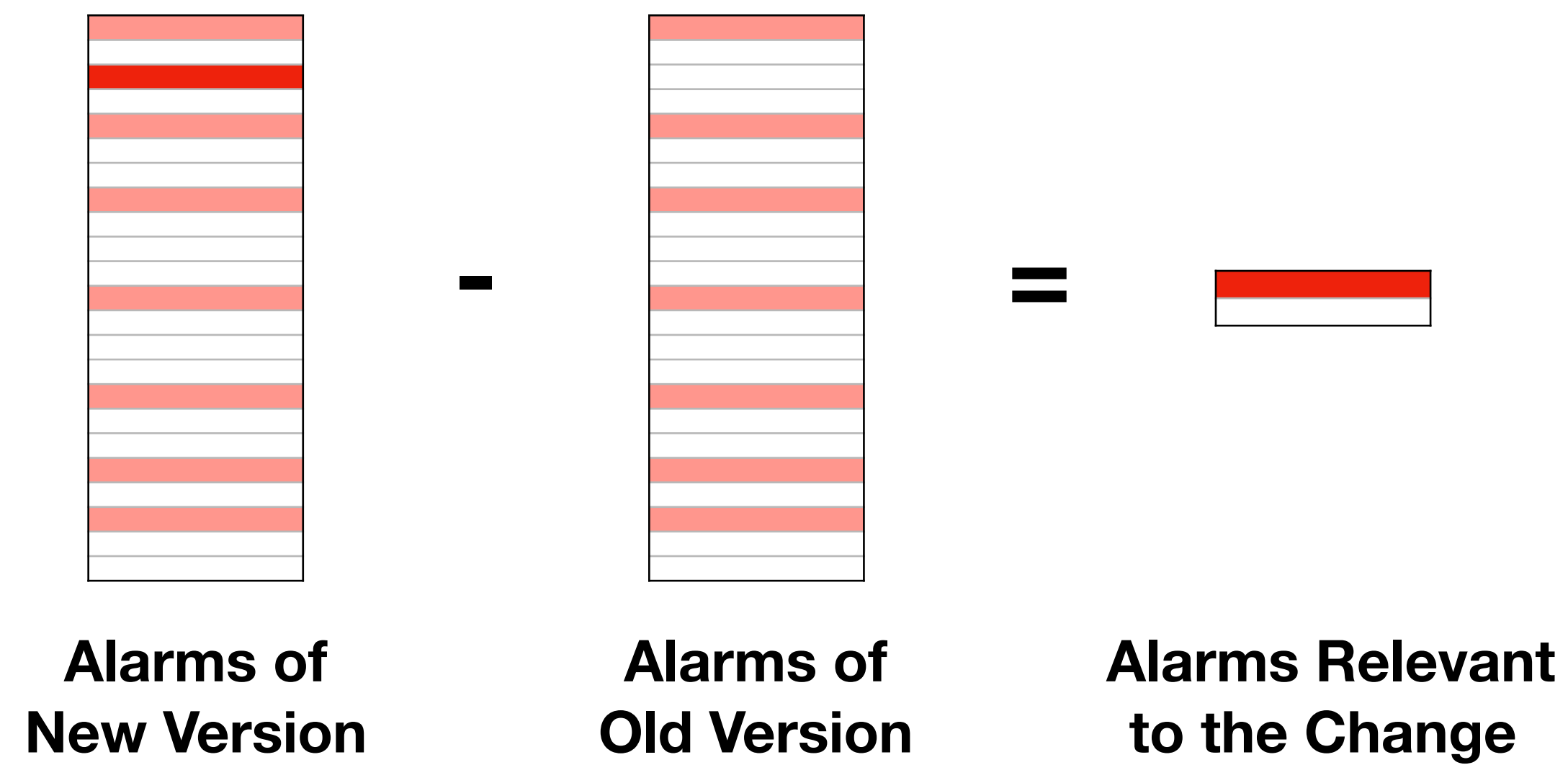


**Interactive
Program Analysis**

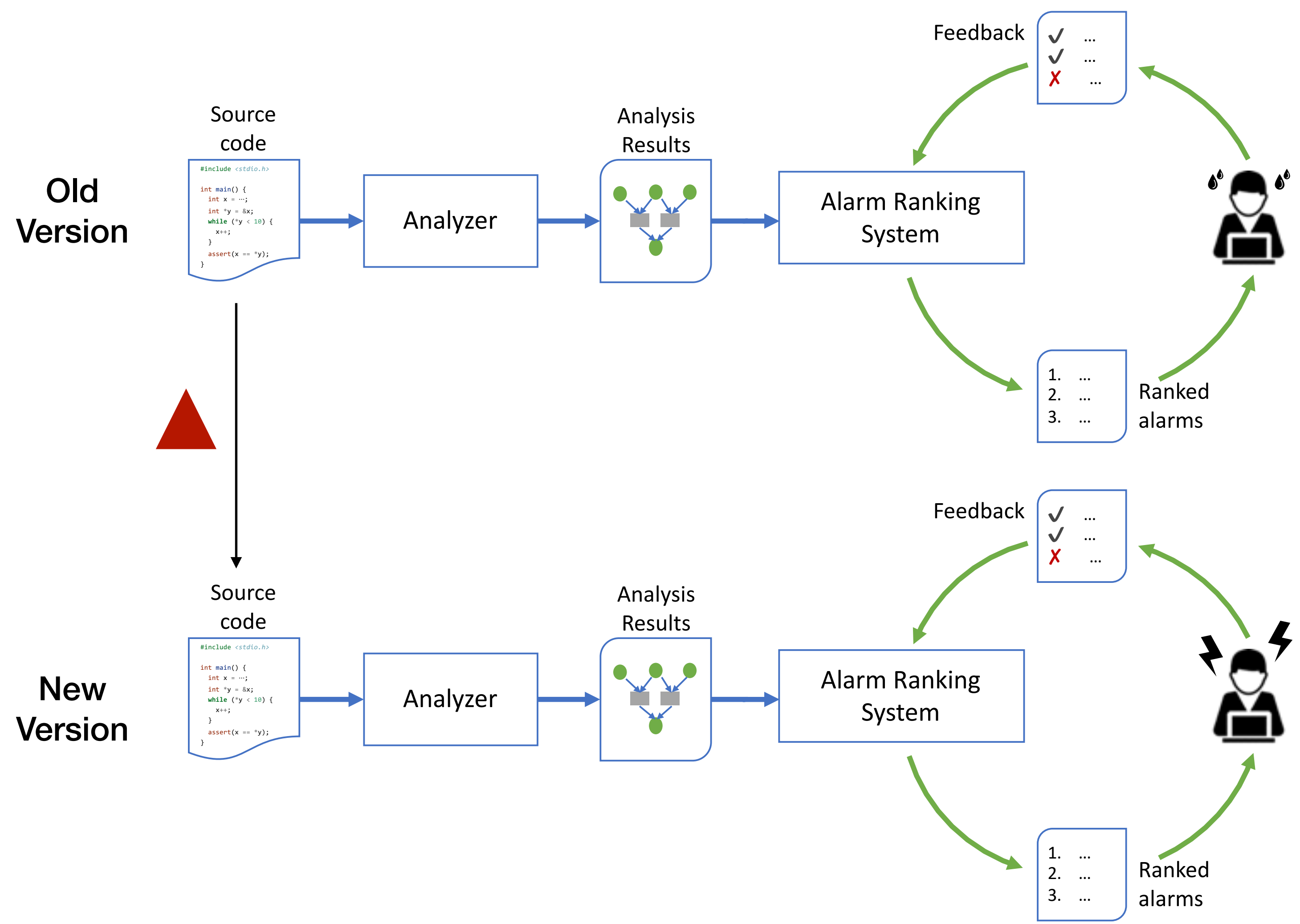


**Continuous
Program Analysis**

Drake: Continuous Alarm Masking System [PLDI'19]



일괄형 (batch-mode) 분석



연속적 (continuous) 분석

“We only display results for most analyses on **changed lines** by default; this keeps analysis results **relevant** to the code review at hand”, - Google, 2015

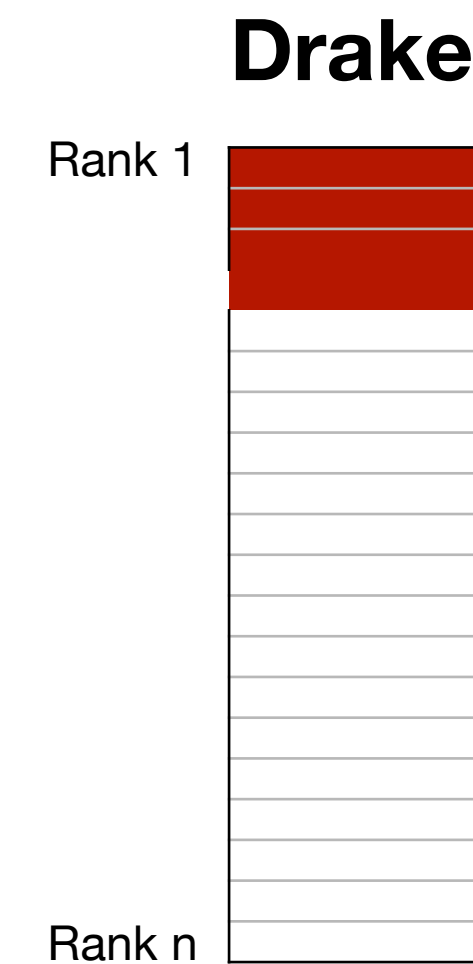
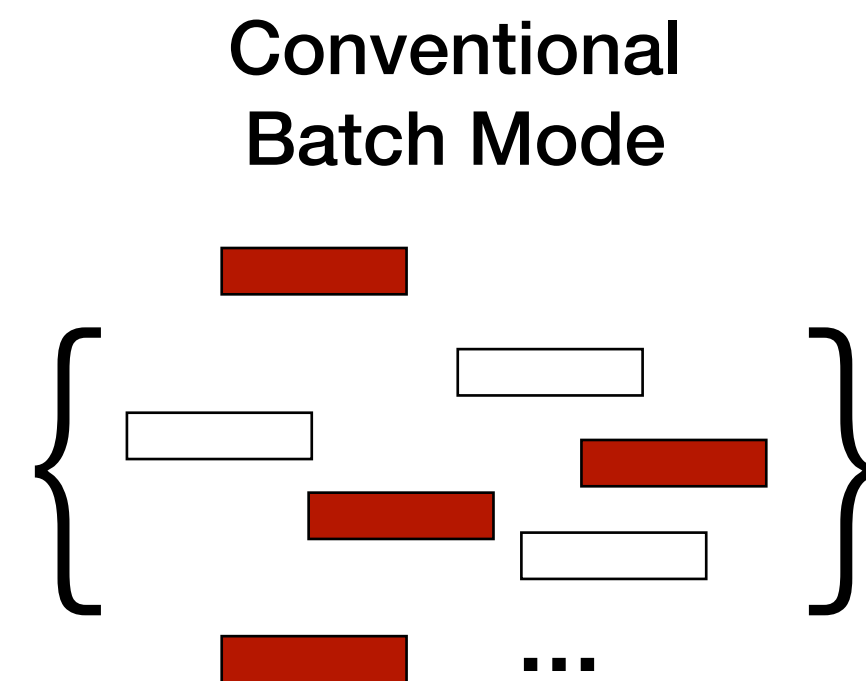
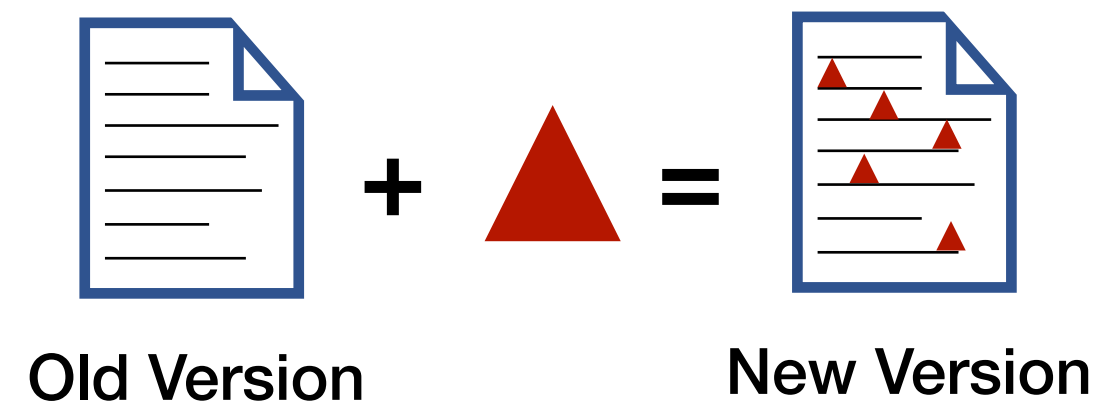
“The vast majority of Infer’s impact to this point is attributable to **continuous reasoning at diff time**”, - Facebook, 2016

“... is the ability to analyze a **changelist (a.k.a. a commit) rather than the entire codebase.** This functionality can help developers assess the quality and impact of a change ...”, - Microsoft, 2016

“In order to realize the goal, verification must continue to work with low effort **as developers change the code.** ... Neither of these approaches would work for Amazon as s2n is under **continuous development.**”, - Amazon, 2018

목표

- 코드 변화와 관련이 있는 순으로 정렬해주는 오류 보고 시스템



: Alarms relevant to the change
: Alarms NOT relevant to the change

예제

Old Version

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
4: y = opaque_dec(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm ✓
```

x and y can be any integers

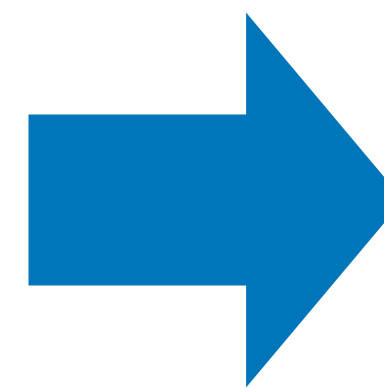
Opaque, but "--" actually

Integer overflow alarms at 5 & 6

예제

Old Version

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
-4: y = opaque_dec(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm ✓
```



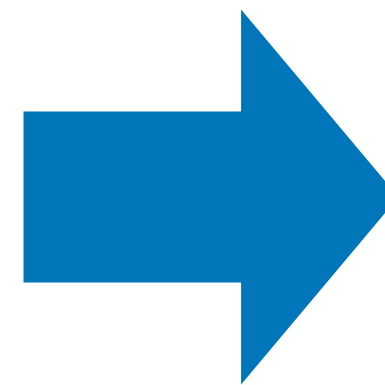
New Version

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
+4: y = identity(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm 🐛
```

예제

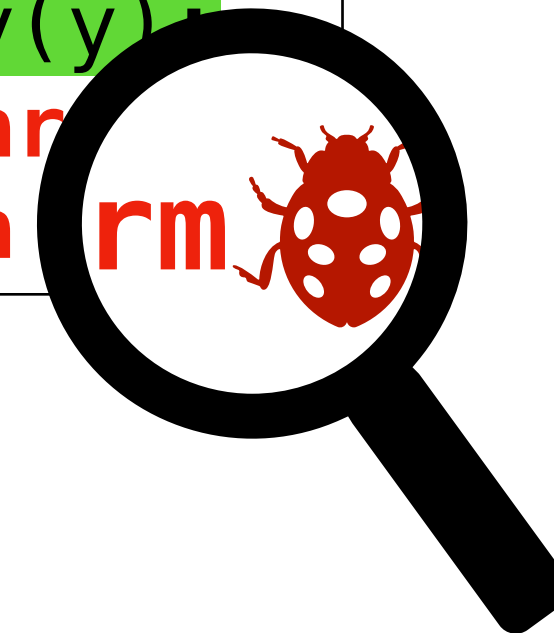
Old Version

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
-4: y = opaque_dec(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm ✓
```



New Version

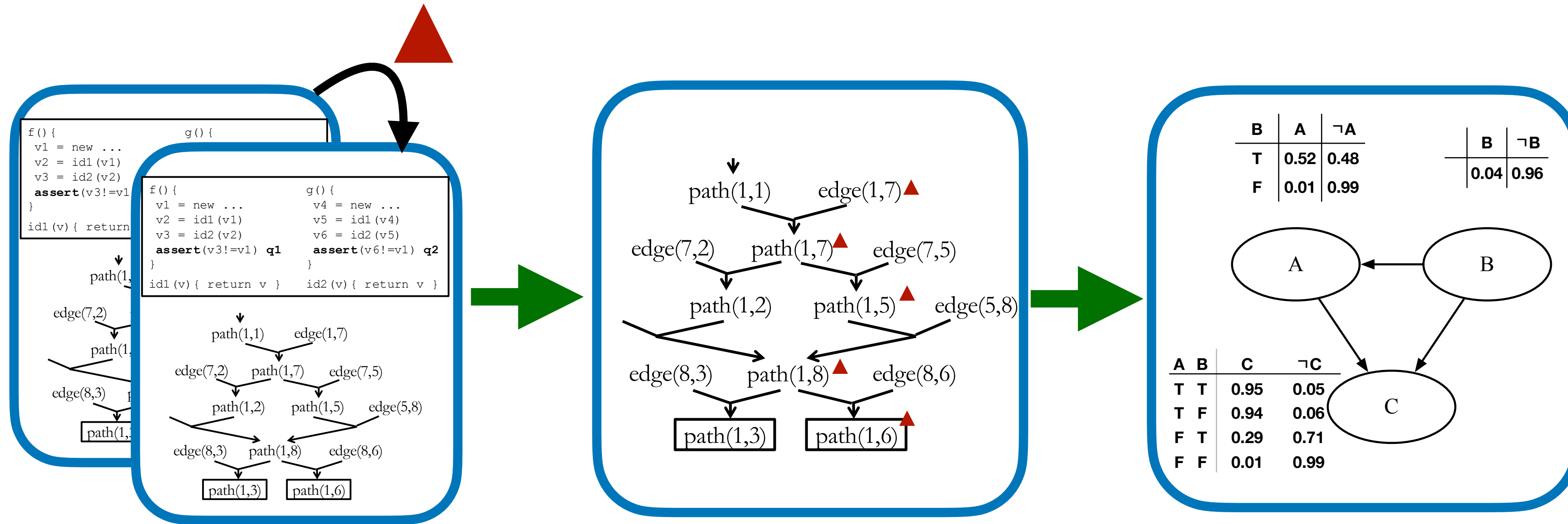
```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
+4: y = identity(y);  
5: x++; // Alarm  
6: y++; // Alarm
```



Q: How to emphasize the alarm at 6 that is relevant to this change?

핵심 기술

변화 감지 분석 결과 + 베이지안 추론 (Bayesian inference)



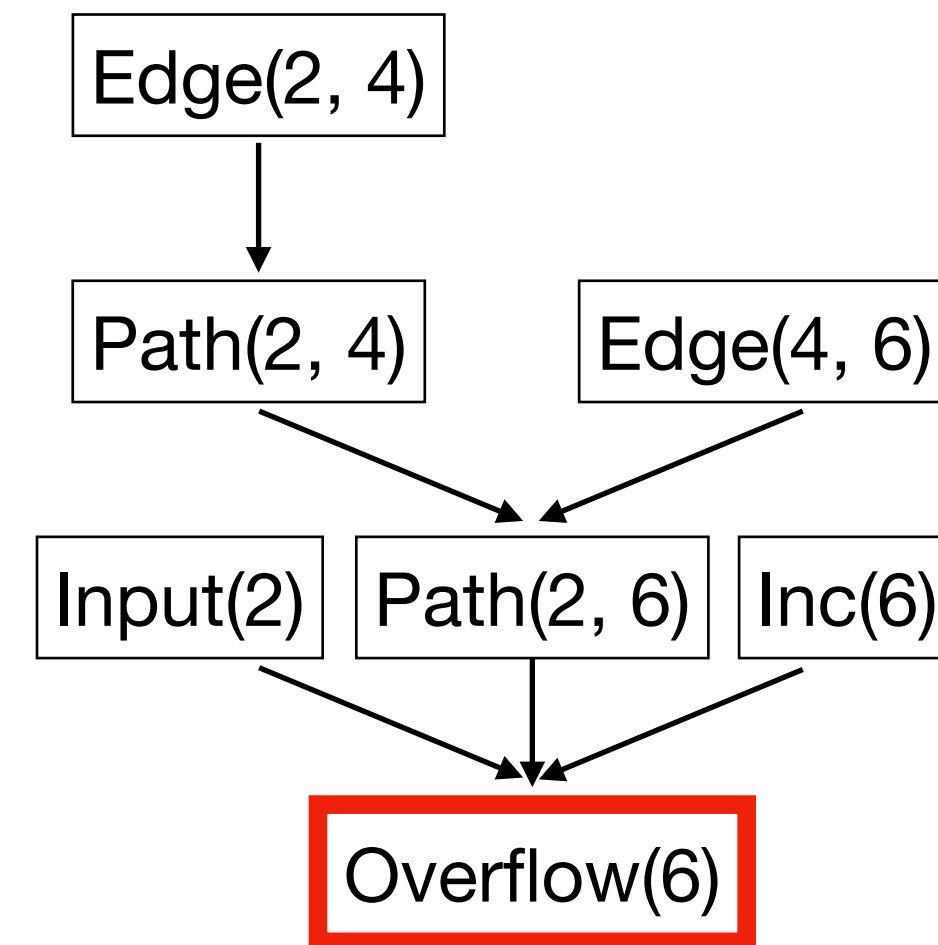
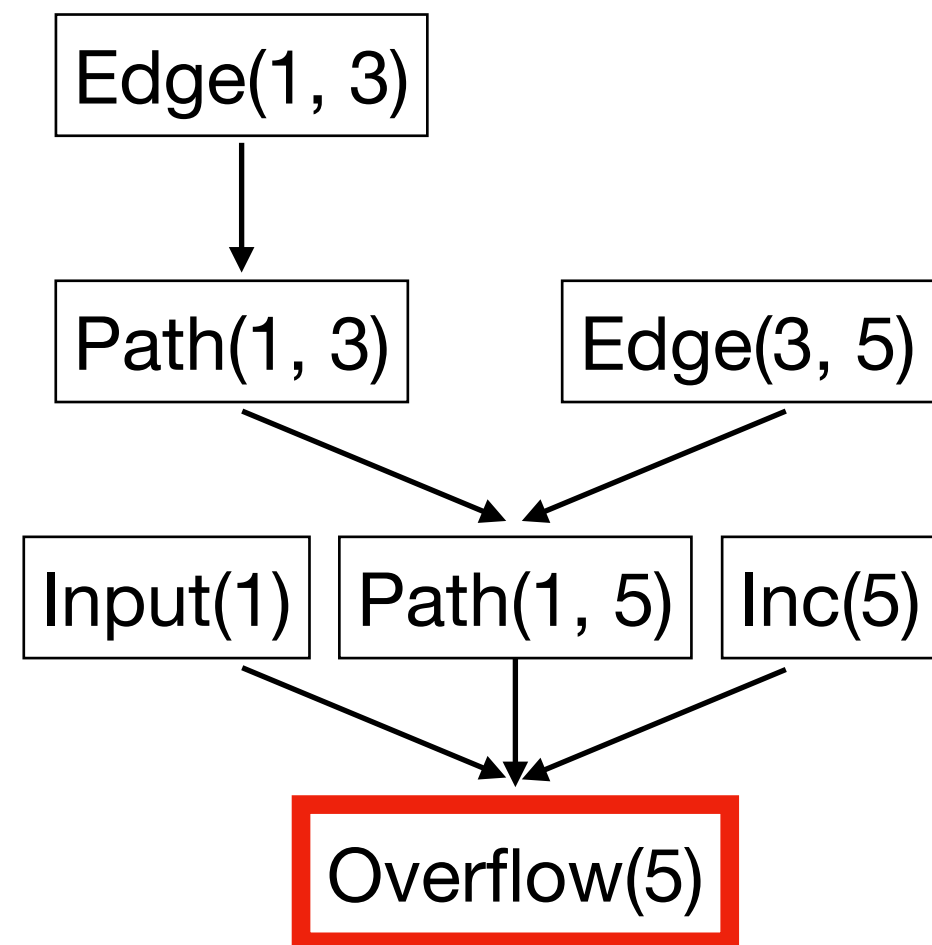
두 버전의 분석 결과

코드 변화를 감지하는 분석 결과

확률 모델
(Bayesian Network)

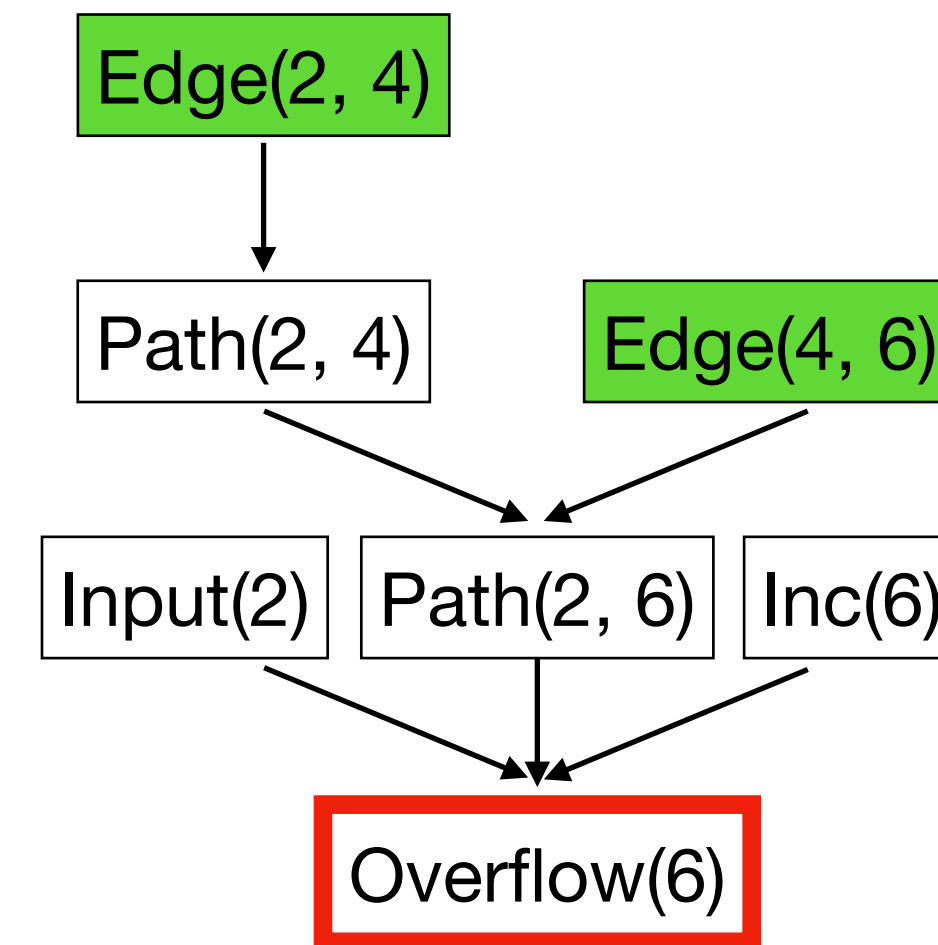
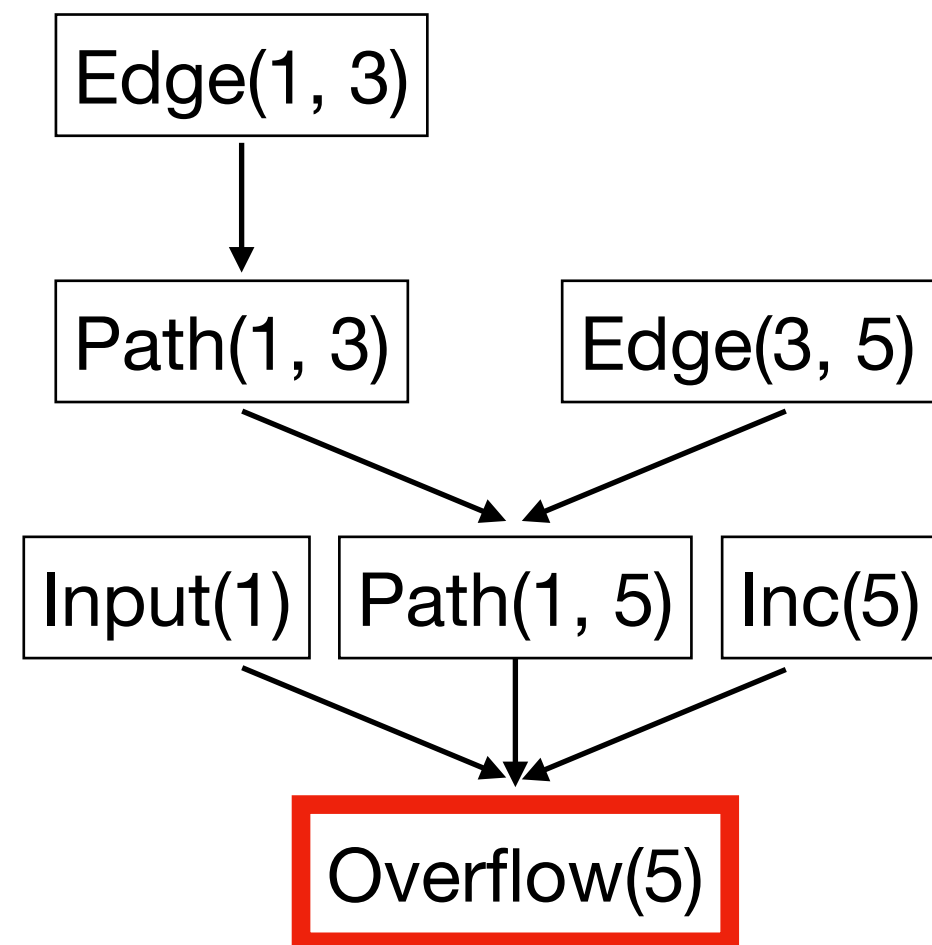
변화를 감지하는 분석 결과

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
+4: y = identity(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm 🐛
```



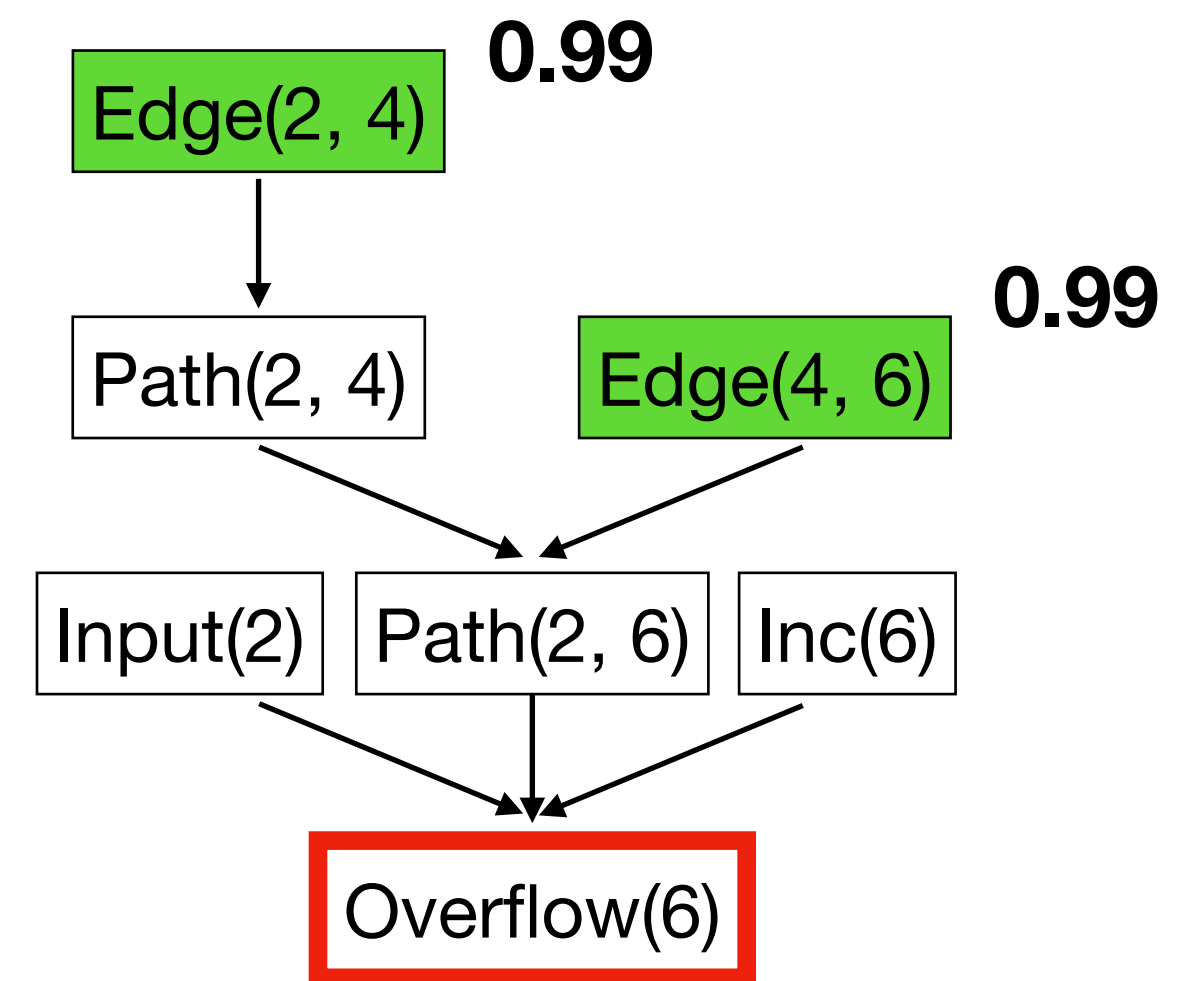
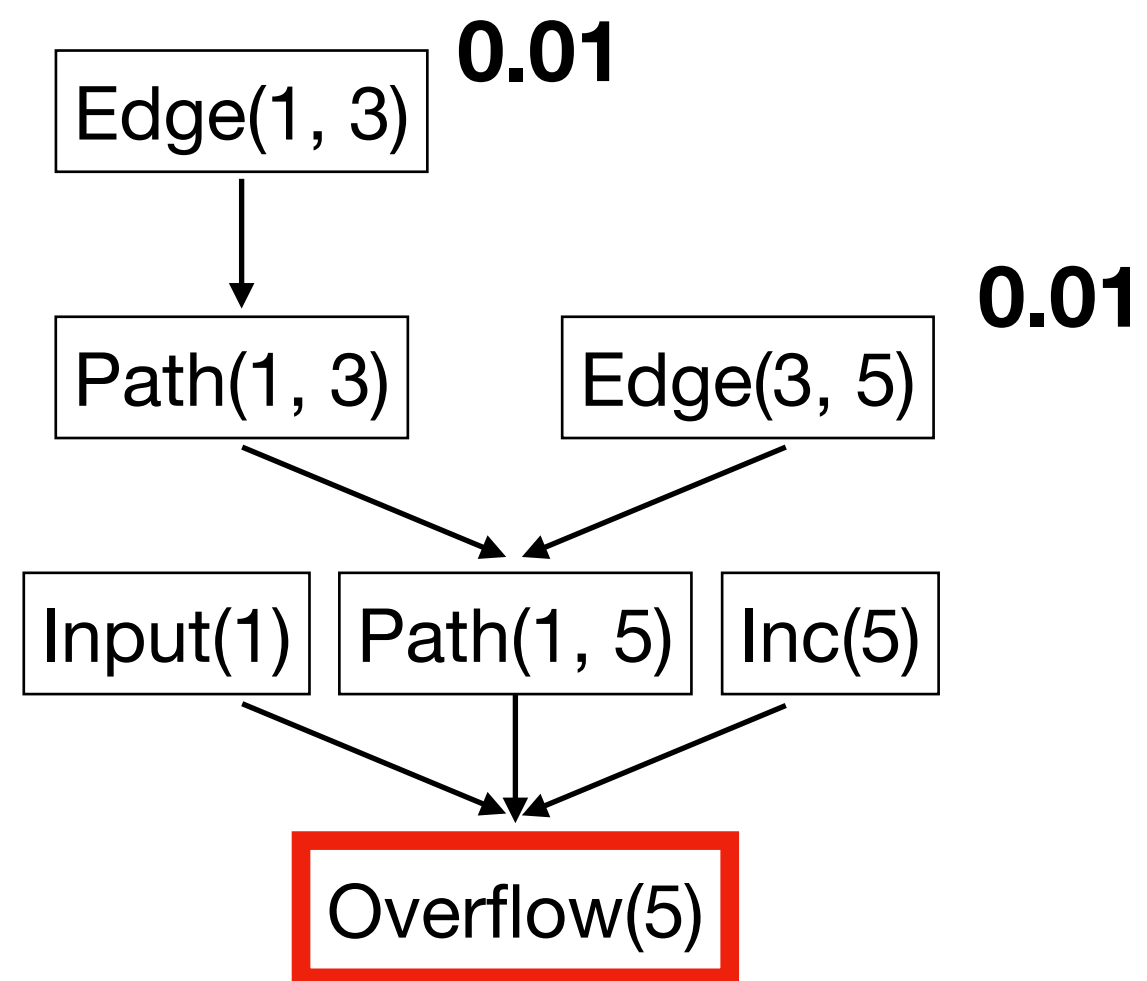
변화를 감지하는 분석 결과

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
+4: y = identity(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm 🐛
```



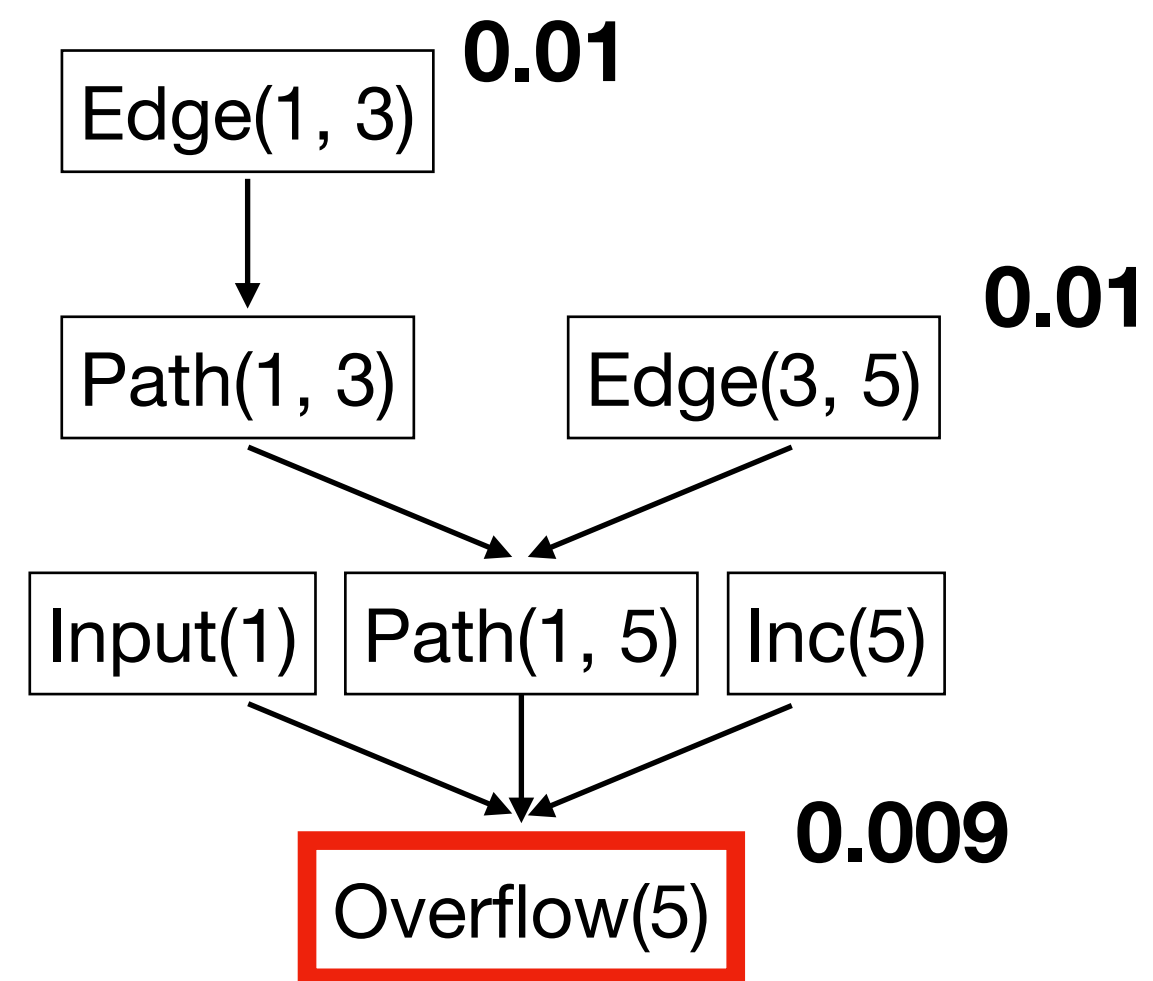
관련 점수

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
+4: y = identity(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm 🐛
```

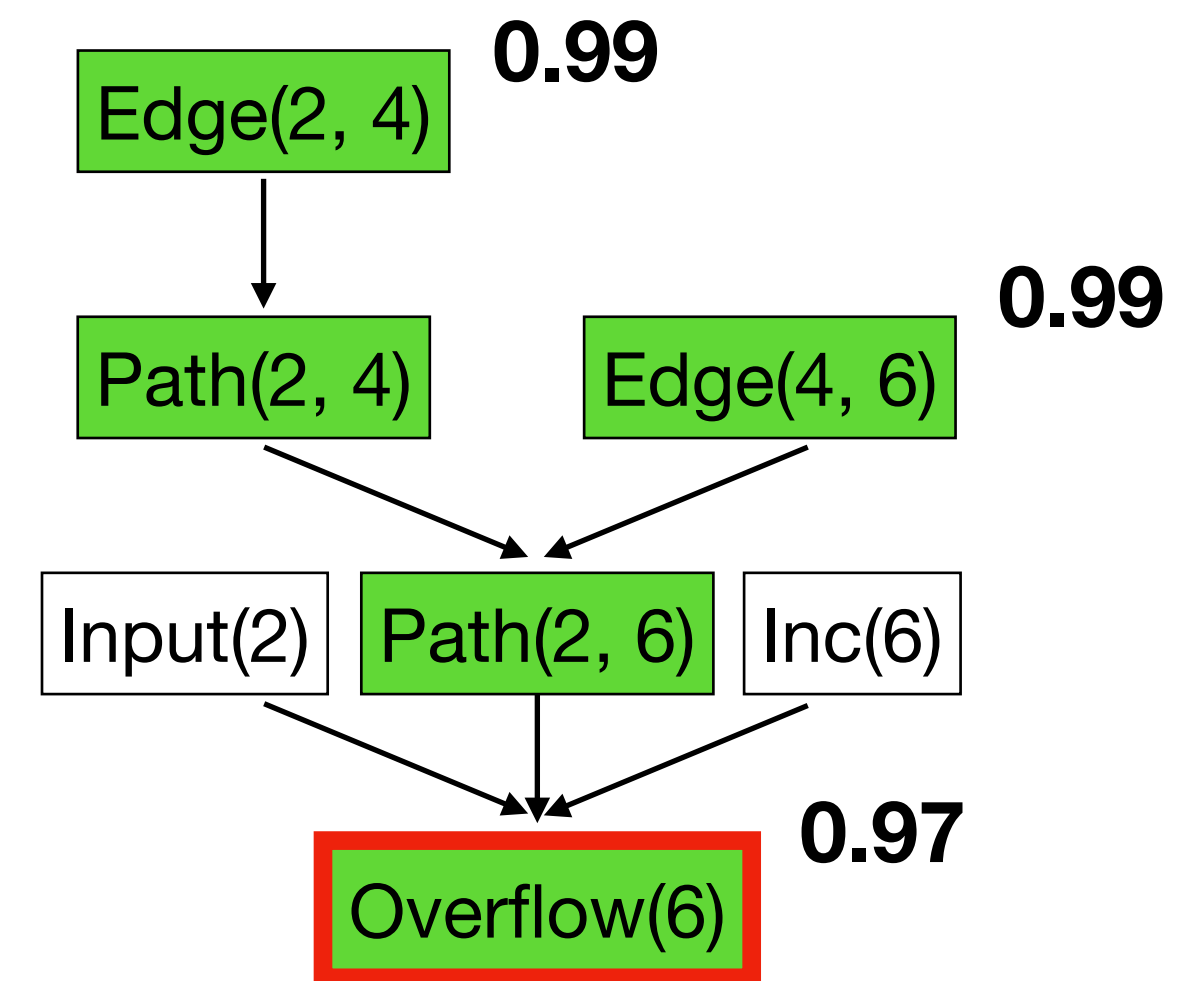


관련 점수

```
1: x = input();  
2: y = input();  
3: x = opaque_dec(x);  
+4: y = identity(y);  
5: x++; // Alarm ✓  
6: y++; // Alarm 🐛
```



<

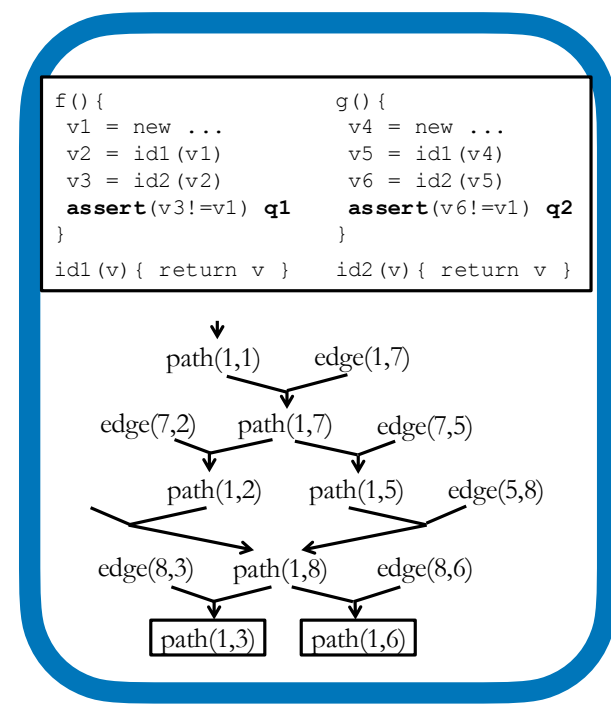


효과

13—112KLOC C Programs (old and new)
3 bugs on average
Buffer overrun and Integer overflow analyses

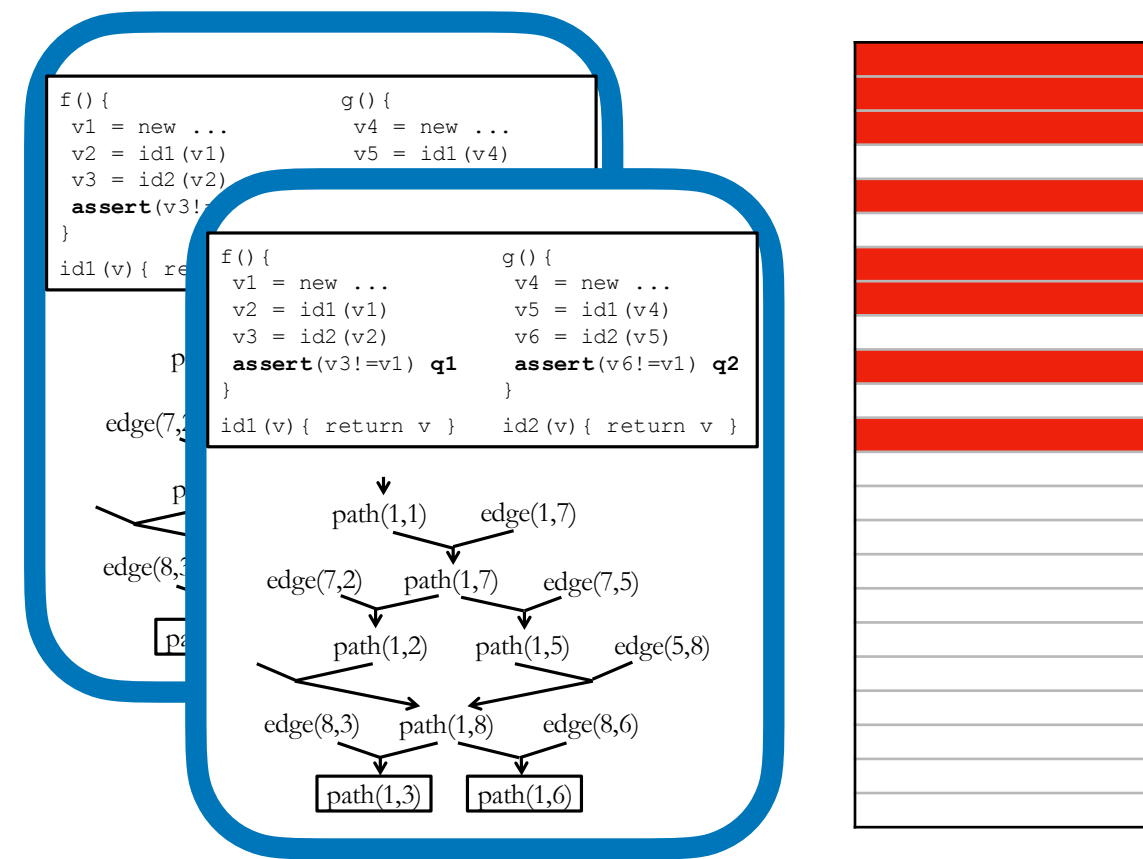
효과

평균 3개 버그를 찾기 위한 드는 노력의 평균을 측정



일괄형

563 개 경보 사이에
모든 버그가 산재



관련성 기반 순위

최대 순위 94 위 이내에
모든 버그 위치




+ 상호 작용 기반 순위

상호 작용 30 회 이내에
모든 버그 검출

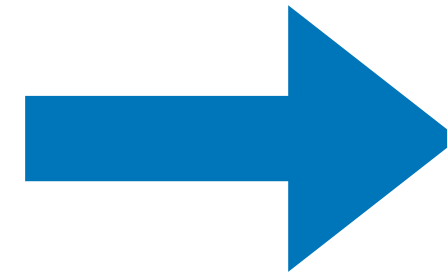
여러 응용

$Pr(a | e)$

문제	상호작용 대상	오류 검출에 드는 노력			오류 검출에 드는 노력
분석 결과 진위 여부	개발자	44% 감소	[PLDI'18]	확률 모델 학습 [ICSE'22] 	22-33% 추가 감소
분석 결과 진위 여부	이전 버전	65% 감소	[PLDI'19]		54% 추가 감소
분석 결과 진위 여부	동적 분석	35% 감소	[FSE'21]		20% 추가 감소
...

확률 모델 학습

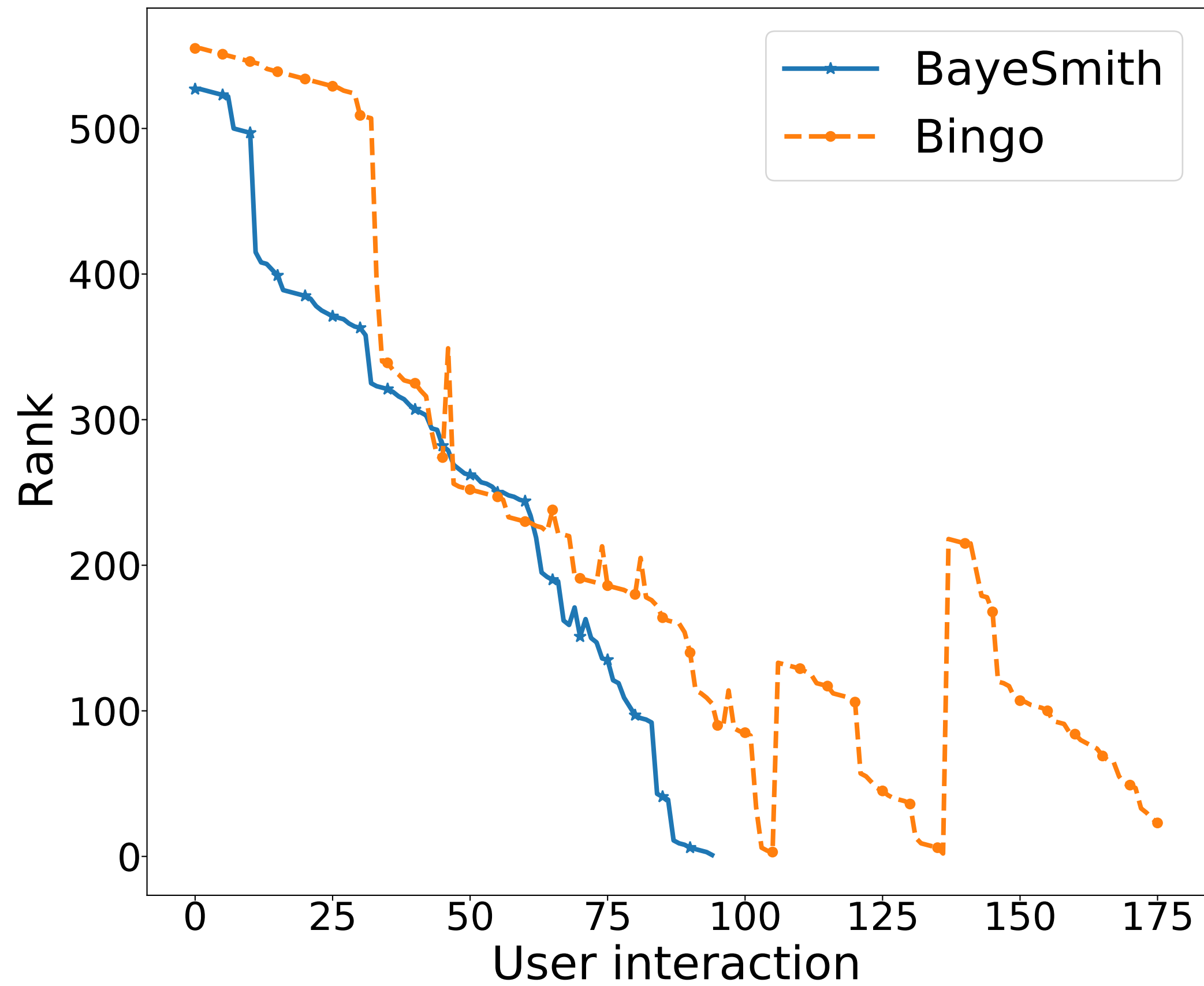
Ranking	Alarm	Confidence
1	Line 6	0.93
2	Line 7	0.92
3	Line 8	0.91
...		



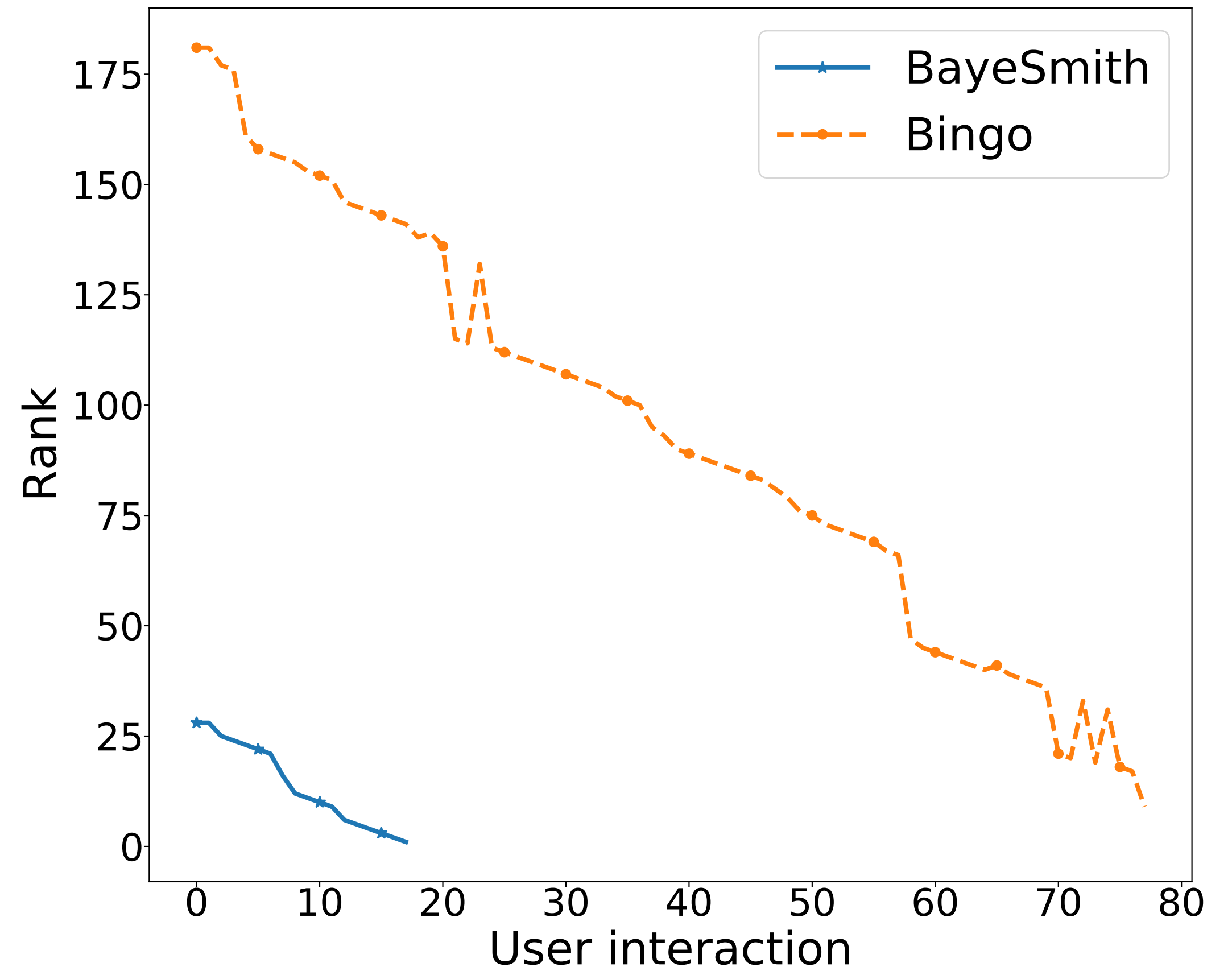
Ranking	Alarm	Confidence
...		
132	Line 7	0.41
133	Line 8	0.40
...		

잘못된 일반화 문제

sort

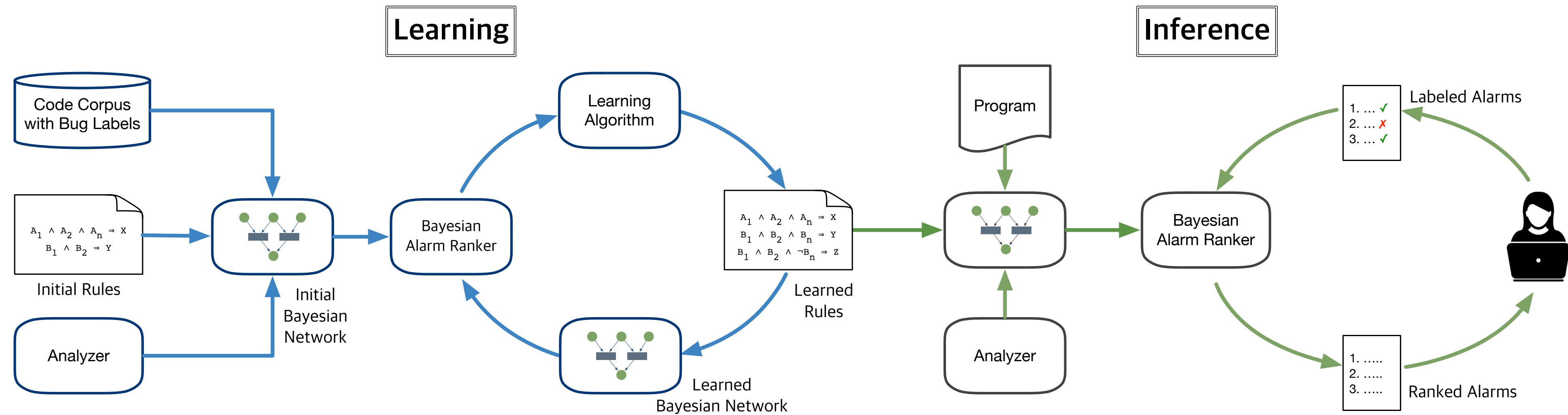


readelf



핵심 기술

- 프로그램 합성 + 베이지안 추론

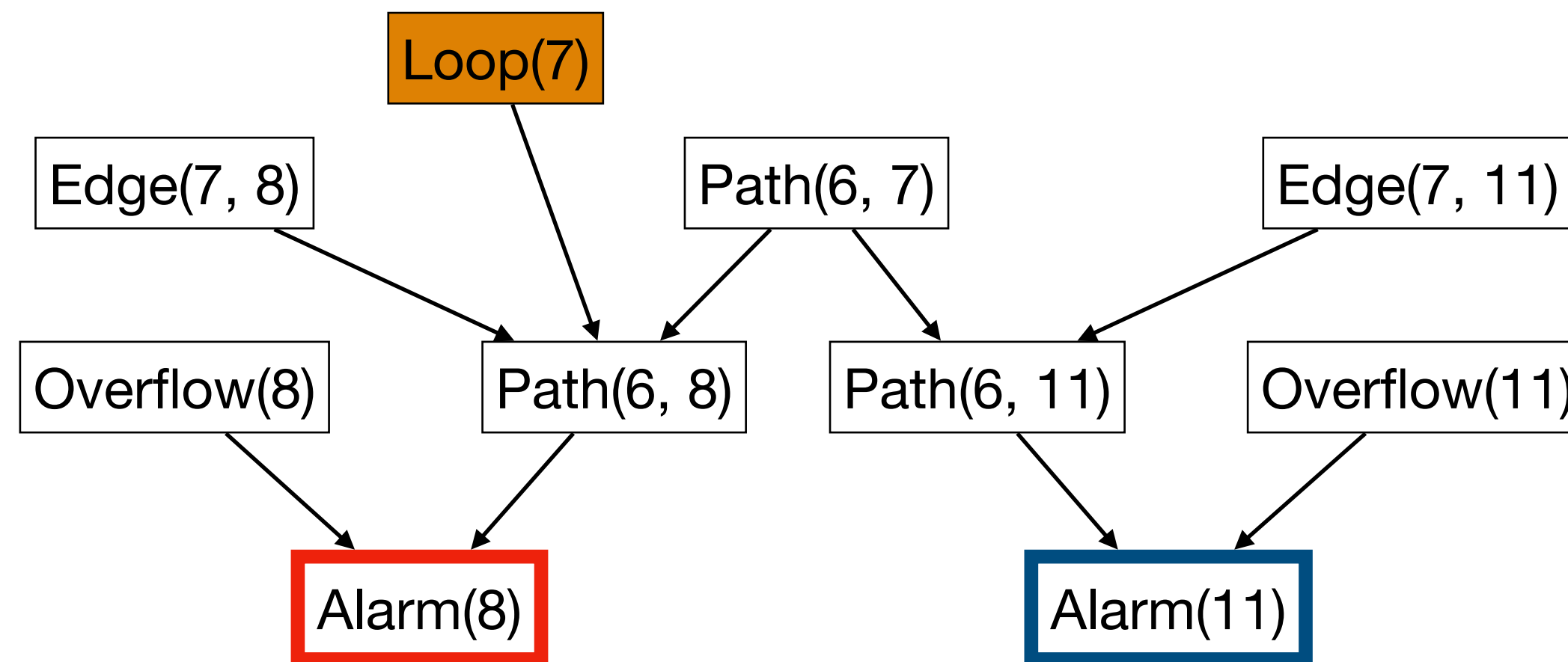


확률 모델 학습

- 잘못된 일반화가 일어나는 지점을 찾아 그 지점의 구문적 특징을 포착

Cmd ::= Lv := e | Assume(e) | Call(e, e) | Loop(e)
Lv ::= x | *E
E ::= n | Lv | E + E | ...

$\Pr(\text{Path}(x, y) \mid \text{Edge}(x, y)) = 0.99$
 $\Pr(\text{Path}(x, y) \mid \text{Path}(x, z), \text{Edge}(x, y), \text{Loop}(y)) = 0.99 \times p$
 $\Pr(\text{Path}(x, y) \mid \text{Path}(x, z), \text{Edge}(x, y), \text{!Loop}(y)) = 0.99$
 $\Pr(\text{Alarm}(y) \mid \text{Path}(x, y), \text{Overflow}(y)) = 0.99$



정리

- PL 와 ML 의 결합 사례 1: ML 을 이용한 정적 분석
- 흥미로운 요소: 논리만으로 해결이 어려운 문제를 확률로 해결
 - 예: 요약 해석 (abstract interpretation) 이 다루지 않는 안전성 조절, 자원량 조절, 상호작용

"프로그램 분석 개론 수업을 들었을 때, 프로그램 분석을 ML, AI로 확장시키는 아이디어가 재미있다고 느꼈습니다. 더 일반적으로는 논리를 확률과 학습으로 확장시키는 과정이 흥미롭다고 생각합니다. $\{0, 1\}$ 의 세계에서 $[0, 1]$ 의 세계로 나아간다면 무언가 멋진 결과가 나오지 않을까 생각하세요. 또, 프로그램 분석을 AI로 확장시킬 때 베이지안 추론을 사용한다는 점이 재밌었습니다. 블랙박스인 딥러닝 보단 더 매력적으로 느껴지기 때문입니다."

- 한 수강생으로부터